



INTERNATIONAL STANDARD ISO/IEC 13818-2:1996

TECHNICAL CORRIGENDUM 1

Published 1997-12-15

INTERNATIONAL ORGANIZATION FOR STANDARDIZATION • МЕЖДУНАРОДНАЯ ОРГАНИЗАЦИЯ ПО СТАНДАРТИЗАЦИИ • ORGANISATION INTERNATIONALE DE NORMALISATION
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Information technology — Generic coding of moving pictures and associated audio information: Video

TECHNICAL CORRIGENDUM 1

Technologies de l'information — Codage des images animées et du son associé: Vidéo

RECTIFICATIF TECHNIQUE 1

Technical Corrigendum 1 to International Standard ISO/IEC 13818-2:1995 was prepared by Joint Technical Committee ISO/IEC JTC 1, *Information technology*, Subcommittee SC 29, *Coding of audio, picture, multimedia and hypermedia information*.

ICS 35.040

Ref. No. ISO/IEC 13818-2:1996/Cor.1:1997(E)

Descriptors: data processing, moving pictures, image processing, video recording, video data, data converting, coding (data conversion).

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Printed in Switzerland

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INTERNATIONAL STANDARD

ITU-T RECOMMENDATION

**INFORMATION TECHNOLOGY – GENERIC CODING OF MOVING
PICTURES AND ASSOCIATED AUDIO INFORMATION: VIDEO**

TECHNICAL CORRIGENDUM 1

Introduction

Each corrigendum item is followed by an informative background.

1) Subclause 6.1.1.6

In “Sequence header” subclause, second last paragraph, replace the sentence:

In the coded bitstream, a repeat sequence header may precede either an I-picture or a P-picture, but not a B-picture.

by:

In the coded bitstream, the first picture following a sequence header or a repeated sequence header shall be either an I-picture or a P-picture, but not a B-picture.

Background

This was an editorial oversight.

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2) Subclause 6.2.4

Replace the syntax table for slice by:

slice() {	No. of bits	Mnemonic
slice_start_code	32	bslbf
if (vertical_size > 2800)		
slice_vertical_position_extension	3	uimsbf
if (<sequence_scalable_extension() is present in the bitstream>) {		
if (scalable_mode == 'data partitioning')		
priority_breakpoint	7	uimsbf
}		
quantiser_scale_code	5	uimsbf
if (nextbits() == '1') {		
slice_extension_flag	1	bslbf
intra_slice	1	uimsbf
slice_picture_id_enable	1	uimsbf
slice_picture_id	6	uimsbf
while (nextbits() == '1') {		
extra_bit_slice /* with the value '1' */	1	uimsbf
extra_information_slice	8	uimsbf
}		
}		
extra_bit_slice /* with the value '0' */	1	uimsbf
do {		
macroblock()		
} while (nextbits() != '000 0000 0000 0000 0000 0000')		
next_start_code()		
}		

Background

In some networks that do not have guaranteed bandwidth, e.g. Ethernet, FDDI, large bursts of errors may occur occasionally. If the errors are localized to one picture, then recovery can happen upon reception of the very next slice header. However, if the errors are spread over several pictures, then recovery may take a long time, since the decoder does not know what the decoding parameters are for the next available slice.

If the header information is available from a separately transmitted Data Partitioning layer, or available from the application, then error recovery can be speeded up considerably if the slice header contains information that an application can use to identify which picture the slice belongs to. The **slice_picture_id** provides this information.

3) Subclause 6.3.6

In colour primaries, after Table 6-6, replace:

In the case that sequence_display_extension() is not present in the bitstream or colour_description is zero the chromaticity is assumed to be that corresponding to colour primaries having the value 1.

by the following text:

In the case that `sequence_display_extension()` is not present in the bitstream or `colour_description` is zero, the chromaticity is assumed to be implicitly defined by the application.

In transfer_characteristics, after Table 6-8, replace:

In the case that `sequence_display_extension()` is not present in the bitstream or `colour_description` is zero the transfer characteristics are assumed to be those corresponding to transfer_characteristics having the value 1.

by the following text:

In the case that `sequence_display_extension()` is not present in the bitstream or `colour_description` is zero, the transfer characteristics are assumed to be implicitly defined by the application.

After Table 6-9 replace:

In the case that `sequence_display_extension()` is not present in the bitstream or `colour_description` is zero the matrix coefficients are assumed to be those corresponding to matrix_coefficients having the value 1.

by the following text and Note:

In the case that `sequence_display_extension()` is not present in the bitstream or `colour_description` is zero the matrix coefficients are assumed to be implicitly defined by the application.

NOTE – In applications which may have signals with more than one set of colour primaries, transfer characteristics, and/or matrix coefficients, it is recommended to transmit a sequence display extension with `colour_description` set to one, and to specify the appropriate values for the colorimetry parameters.

Background

In applications where only one set of colour primaries, transfer characteristics and matrix coefficients is used, there is not a need for the codec to pass colour description parameters. The current syntax includes default colour description parameters which could cause improper interpretation of many bitstreams.

A solution to this problem which embraces all existing implementations without introducing a new problem for other implementations is not to have a default definition, but instead to let the application define the default, as described in this corrigendum.

4) Subclause 6.3.10

a) Under the description of the syntax element `frame_pred_frame_dct`, replace the statement:

`frame_pred_frame_dct` shall be '1' if `progressive_frame` is '1'.

by:

`frame_pred_frame_dct` shall be '1' if `progressive_sequence` is '1'.

Under the description of the syntax element `progressive_frame`, replace the statement:

- `frame_pred_frame_dct` shall be 1.

by:

- if `progressive_sequence` is equal to one, then `frame_pred_frame_dct` shall be 1.

Background

The following text from MPEG95/044 explains the background for this corrigendum:

It appears that the restriction “`frame_pred_frame_dct` shall be 1 if `progressive_frame` is 1” causes problems when editing bitstreams, as demonstrated by the following example.

Let's say sequence 1 ends with a top field first interlaced frame, i.e.:

```
progressive_sequence=0
picture_structure=3
progressive_frame=0
top_field_first=1
repeat_first_field=0
```

while sequence 2 starts with a bottom field first interlaced frame, i.e.:

```
progressive_sequence=0
picture_structure=3
progressive_frame=0
top_field_first=0
repeat_first_field=0
```

Now, to put them together we need a "glue" frame with repeat_first_field as follows:

```
progressive_sequence=0
picture_structure=3
progressive_frame=1
top_field_first=1
repeat_first_field=1
```

The situation is depicted graphically as follows:

```
1T      g0 g2  2T
        |  |  |
1B      g1  2B
```

where (1T,1B) is the last frame of sequence 1 and (2B,2T) is the first frame of sequence 2. The "g"s signify the three fields of the "glue" frame. When editing bitstream, it is often necessary to insert "glue" frames, not only to match parity but also to introduce a delay in order to match VBV buffer fullness.

Ideally, we would like the "g"s to repeat the last field of sequence 1, i.e. g0 and g1 are both predicted by 1B while g2 is a repeat of g0.

It appears, however, that this is impossible since repeat_first_field can be 1 only if progressive_frame is 1 and field prediction is not allowed since progressive_frame=1 implies frame_pred_frame_dct=1.

That means we will get an inevitable jerk going from sequence 1 to sequence 2.

Our view is that progressive_frame applies to the current frame, while whether it can be coded well with frame_pred_frame_dct depends on both the current frame and the reference frame. The fact that the current frame is progressive does not necessarily mean that it can be coded well with frame_pred_frame_dct=1.

b) *In the definition for intra_vlc_format, the reference to "7.2.1" should be changed to "7.2.2.1".*

5) Subclause 6.3.15

In "Copyright extension" subclause, replace:

copyright_identifier -- This is an 8-bit integer which identifies a Registration Authority as designated by ISO/IEC JTC 1/SC 29.

by:

copyright_identifier -- This is an 8-bit integer given by a Registration Authority as designated by ISO/IEC JTC 1/SC 29.

Replace the sentence in the second last paragraph:

In this case, the value of `copyright_number` identifies uniquely the copyrighted work marked by the copyrighted extension and is provided by the Registration Authority identified by `copyright_identifier`.

by:

In this case, the value of `copyright_number` identifies uniquely the copyrighted work marked by the copyrighted extension.

Background

This corrigendum is to clear a confusion of who issues the `copyright_identifier` or the `copyright_number`.

6) Subclause 6.3.16

Replace:

`intra_slice_flag` – This flag shall be set to '1' to indicate the presence of `intra_slice` and `reserved_bits` in the bitstream.

by:

`slice_extension_flag` – This flag shall be set to '1' to indicate the presence of `intra_slice`, `slice_picture_id_enable`, `slice_picture_id` in the bitstream.

Replace:

`reserved_bits` – This is a 7-bit integer, it shall have the value zero, other values are reserved.

by:

`slice_picture_id_enable` – This flag controls the semantics of `slice_picture_id`. If `slice_picture_id_enable` is set to '0', `slice_picture_id` is not used by this specification and shall have the value zero. If `slice_picture_id_enable` is set to '1', `slice_picture_id` may have a value different from zero.

`slice_picture_id_enable` must have the same value in all the slices of a picture. `slice_picture_id_enable` may be omitted from the bitstream (by setting `slice_extension_flag` to '0') in which case it shall be assumed to have the value zero.

`slice_picture_id_enable` is not used by the decoding process.

`slice_picture_id` – This is a 6-bit integer. If `slice_picture_id_enable` is set to '0', `slice_picture_id` is not used by this specification and shall have the value zero. If `slice_picture_id_enable` is set to '1', `slice_picture_id` is application defined and may have any value, with the constraint that `slice_picture_id` shall have the same value in all the slices of a picture.

`slice_picture_id` is not used by the decoding process. `slice_picture_id` is intended to aid recovery on severe bursts of errors for certain types of applications. For example, the application may increment `slice_picture_id` with each transmitted picture, so that in case of severe burst error, when several slices are lost, the decoder can know if the slice following the burst error belongs to the current picture or to another picture, which may be the case if at least a picture header has been lost.

Background

See item 2) above.

7) Subclause 7.2.1

All 'dc_dct_size' should be changed to 'dct_dc_size', to be consistent with the syntax described in 6.2.6.

All 'dc_dct_differential' should be changed to 'dct_dc_differential', to be consistent with the syntax described in 6.2.6.

All 'dc_dct_pred' should be changed to 'dct_dc_pred', to be consistent with the previous changes.

8) Clause 8

Replace the paragraph preceding Table 8-1:

The profile_and_level_indication in the sequence_extension indicates the profile and level to which the bitstream complies. The meaning of the bits in this parameter is defined in Table 8-1.

by:

The profile_and_level_indication in the sequence_extension indicates the profile and level to which the bitstream complies. The most significant bit of profile_and_level_indication is called 'escape bit'. When the escape bit is set to zero, the profile and level are derived from profile_and_level_indication according to Tables 8-1, 8-2 and 8-3.

Background

In the course of study for the 4:2:2 profile amendment, it has been found that the descriptions of the profile_and_level_indication syntax referring to Table 8-1 and Table 8-4 are not aligned. We should state that:

- if the escape bit is '0', then profile and level are structured as in Tables 8-1, 8-2 and 8-3;
- if the escape bit is '1', then profile and level are structured as in Table 8-4.

9) Subclause 8.3

Replace the Note at the bottom of Table 8-8:

- b) This restriction applies to the final reconstructed motion vector. In the case of dual prime motion vectors it applies before scaling is performed, after scaling is performed and after the small differential motion vector has been added.

by the following text:

- b) This restriction applies to the final reconstructed motion vector. In the case of dual prime motion vectors, this restriction applies to all the following values:

$$\begin{aligned} & \text{vector}'[0][0][1] \\ & ((\text{vector}'[0][0][1] * m[\text{parity_ref}][\text{parity_pred}])//2) \\ & ((\text{vector}'[0][0][1] * m[\text{parity_ref}][\text{parity_pred}])//2) + e[\text{parity_ref}][\text{parity_pred}] \\ & ((\text{vector}'[0][0][1] * m[\text{parity_ref}][\text{parity_pred}])//2) + \text{dmvector}[1] \\ & ((\text{vector}'[0][0][1] * m[\text{parity_ref}][\text{parity_pred}])//2) + e[\text{parity_ref}][\text{parity_pred}] + \text{dmvector}[1] \end{aligned}$$
Background

An ambiguity has been pointed out regarding the restriction on the vertical range of the final reconstructed motion vectors when dual-prime prediction is used.

In 8.3, the Note at the bottom of Table 8-8 says:

- b) This restriction applies to the final reconstructed motion vector. In the case of dual prime motion vectors it applies before scaling is performed, after scaling is performed and after the small differential motion vector has been added.

The final dual prime motion vectors are computed according to the equations specified in 7.6.3.6. In those equations, the vertical motion vector coordinate is computed as follows:

$$\text{vector}'[r][0][1] = ((\text{vector}'[0][0][1] * m[\text{parity_ref}][\text{parity_pred}])//2) + e[\text{parity_ref}][\text{parity_pred}] + \text{dmvector}[1].$$

The “e[parity_ref][parity_pred]” is the adjustment necessary to reflect the vertical shift between the lines of the top field and the bottom field.

The problem is the ambiguity of the expression “before scaling is performed, after scaling is performed and after the small differential motion vector has been added”, since there are in fact three operations involved:

- a) scaling, i.e. the operation $((\text{vector}'[0][0][1] * m[\text{parity_ref}][\text{parity_pred}])//2)$;
- b) adding $e[\text{parity_ref}][\text{parity_pred}]$ (forgotten in the Note describing the restriction);
- c) adding $\text{dmvector}[1]$.

The order of the operations is not specified by the standard (only the result counts). In particular, b) and c) can be performed in any order and $e[\text{parity_ref}][\text{parity_pred}]$ and $\text{dmvector}[1]$ can be added first together and the result can then be added to the scaled vector.

10) Subclause B.5

Replace the right part of Table B.16 by:

Fixed length code	signed_level
1000 0000 0000	reserved
1000 0000 0001	-2047
1000 0000 0010	-2046
...	...
1111 1111 1111	-1
0000 0000 0000	Forbidden
0000 0000 0001	+1
...	...
0111 1111 1111	+2047

Background

It was pointed out that in the right part of Table B.16 the entry “1000 0000 0000” corresponding to $\text{signed_level} = -2048$ was omitted but never explicitly forbidden.

This corrigendum fixes the problem and guarantees that signed_level can always be coded with sign/value where the value fits on 11-bit, thus avoiding the risk of breaking any existing implementation. It was decided that this value should be “reserved” rather than “forbidden”. “forbidden” is usually used for values that would cause start-code emulation, which is not the case here.

11) Subclause C.3.1

After definition of $t(n)$, remove:

For the bits preceding the first picture start code and following the final picture start code $R(n) = R_{\text{max}}$.

and add the following text:

Ambiguity at the beginning of a sequence:

The interval of time $t_{n+1} - t_n$ between removal of two consecutive pictures can normally be derived from the bitstream as described in C.9, C.10, C.11 and C.12.

When random access is made in a sequence, $t_{n+1} - t_n$ cannot be determined from the video bitstream alone for the first picture(s) after the sequence header since the previous coded P- or I-frame does not exist in the decoded sequence. If the bitstream is multiplexed as part of a systems bitstream according to ITU-T Rec. H.222.0 | ISO/IEC 13818-1, then it is possible (but not certain) that information in the systems bitstream may be used to determine unambiguously this interval of time. This information is available if Decoding Time Stamps (DTS) are transmitted for pictures n and $n+1$.

If the rate $R(n)$ cannot be determined unambiguously, it is not possible for the VBV to precisely determine the fullness in trajectories in the VBV buffer during a limited period (always less than the maximum value for vbv_delay , which is approximately 0.73 seconds), therefore strict VBV verification of the entire bitstream is not always possible. Note that an encoder always knows the values of $t_{n+1} - t_n$ after each repeated sequence headers and therefore knows how to generate a bitstream that does not violate the VBV constraints at those points.

The ambiguity may become a problem when the video bitstream is remultiplexed and delivered at a rate different from the intended piecewise constant rate $R(n)$.

It should also be noted that the input rate for the bits preceding the first picture header cannot be determined from the bitstream.

Ambiguity at the end of a sequence:

The input of all the bits following the picture start code of the picture preceding an end of sequence code cannot be determined from the bitstream. There shall exist an input rate for these bits that does not lead to an overflow or, if low_delay is equal to 1, an underflow of the VBV buffer. This rate shall be less than the maximum rate specified in the sequence header.

Background

The sentence "For the bits preceding the first picture start code and following the final picture start code $R(n) = R_{\max}$ " was incorrect and the ambiguities in the VBV specification were not well documented and sometimes documented incorrectly. In particular, the existence of a system stream is not sufficient to lift the ambiguity in all cases.

12) Subclause C.9

Remove:

If $t_{n+1} - t_n$ cannot be determined with any of the previous paragraphs because the previous P- or I-Picture does not exist (which can occur at the beginning of a sequence), then the time interval is arbitrary with the following restrictions:

The time interval between removing one frame (or the first field of a frame) and removing the next frame can be arbitrarily defined equal to T , $2 \cdot T$ or $3 \cdot T$. In this case, the delivery rate of the data for the first frame is ambiguous. Therefore the VBV buffer status until after this data has been removed from the VBV buffer may have more than one value. At least one of the valid choices for the decoding time shall lead to a set of VBV buffer states that meet the requirements of this annex on overflow and underflow. If the bitstream is multiplexed as part of a systems bitstream according to ITU-T Rec. H.220.0 | ISO/IEC 13818-1, then information in the systems bitstream may be used to determine unambiguously the VBV buffer state after removing the first picture.

Background

See item 11) above.

13) Subclause C.11

Remove:

If $t_{n+1} - t_n$ cannot be determined with any of the previous paragraphs because the previous coded P- or I-frame does not exist (which can occur at the beginning of a sequence), then the time interval is arbitrary with the following restrictions:

The time interval between removing one frame (or the first field of a frame) and removing the next frame (or the first field of a frame) can be arbitrarily defined equal to $2 \cdot T$ or $3 \cdot T$. Therefore the VBV buffer status until after this data has been removed from the VBV buffer may have more than one value. At least one of the valid choices for the decoding time shall lead to a set of VBV buffer states that meet the requirements of this annex on overflow and underflow. If the bitstream is multiplexed as part of a systems bitstream according to ITU-T Rec. H.220.0 | ISO/IEC 13818-1, then information in the systems bitstream may be used to determine unambiguously the VBV buffer state.

Background

See item 11) above.

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