



INTERNATIONAL STANDARD ISO 9409-1:1996
TECHNICAL CORRIGENDUM 1

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INTERNATIONAL ORGANIZATION FOR STANDARDIZATION • МЕЖДУНАРОДНАЯ ОРГАНИЗАЦИЯ ПО СТАНДАРТИЗАЦИИ • ORGANISATION INTERNATIONALE DE NORMALISATION

Manipulating industrial robots — Mechanical interfaces —

Part 1: Plates (form A)

TECHNICAL CORRIGENDUM 1

Robots manipulateurs industriels — Interfaces mécaniques —

Partie 1: Interfaces à plateau (forme A)

RECTIFICATIF TECHNIQUE 1

Technical Corrigendum 1 to International Standard ISO 9409-1:1996 was prepared by Technical Committee ISO/TC 184, *Industrial automation systems and integration*, Subcommittee SC 2, *Robots for manufacturing environment*.

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Replace Figure 1 by the following.

ICS 25.040.30

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Descriptors: automation, automation engineering, manipulators, industrial robots, interfaces, plates, dimensions, designation, marking.

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