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Road vehicles — Open diagnostic data exchange (ODX) —

Part 3: Fault symptom exchange description (FXD)

Véhicules routiers — Diagnostic généralisé, échange de données (ODX) —

Partie 3: Format d'échange de système de défaut (FXD)

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ISO copyright office
CP 401 • Ch. de Blandonnet 8
CH-1214 Vernier, Geneva, Switzerland
Tel. +41 22 749 01 11
Fax +41 22 749 09 47
copyright@iso.org
www.iso.org

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Foreword

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The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

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This document was prepared by Technical Committee ISO/TC 22, *Road vehicles*, Subcommittee SC 31, *Data communication*.

Annex A, B and C of this document are normative and Annex D is for information only.

A list of all the parts in the ISO 22901 series can be found on the ISO website.

Introduction

0.1 Overview

This document has been established in order to define a new format called FXD (Fault symptom eXchange Description) which has been developed for provision of machine-readable descriptions of mainly fault symptom algorithms which are implemented as diagnostic software in an Electronic Control Unit (ECU).

The main business case is the data exchange from a function and software supplier to a vehicle manufacturer in a standardized format (FXD XML-Schema) in order to enable a tool based processing.

The software supplier will provide software related raw data, which have to be extended and refined by the vehicle manufacturer for different use cases. Based on the FXD content and associated calibration values, several end user documents can be generated such as the summary table for OBD documentation.

The expected main benefits of the FXD approach are an overall improved efficiency as well as an independency of system supplier and vehicle manufacturer-specific format handling.

FXD is an extension of ODX in order to support the documentation and fault symptom data exchange use cases for type approval and repair and maintenance information (RMI).

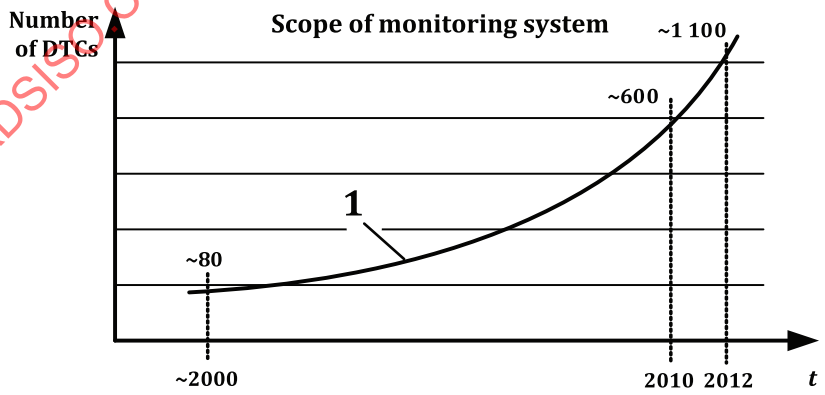
A normative annex will include the FXD XML-Schema which represents the data model for the digital exchange of the FXD data.

0.2 Motivation

The complexity of OBD monitoring systems is continuously evolving. Technological progress and regulatory updates drive the complexity of both engine systems themselves and the related OBD monitoring systems. For instance, the number of monitors and thereby also Diagnostic Trouble Codes (DTC) has considerably increased over time as shown here for a 6-cylinder gasoline application from calendar year 2000 up to 2012.

In addition to the pure number of monitors, also the OBD monitors themselves have become more and more sophisticated.

Figure 1 shows the evolving complexity of OBD systems.



Key

1 6-cyl gasoline engine

Figure 1 — Evolving complexity of OBD systems

0.3 Project complexity

Today's project complexity (e.g. variants) at the vehicle manufacturers is also an important aspect for diagnostic documentation. For all OBD-relevant monitoring strategies, the corresponding OBD documentation is generated. When these monitors are integrated by often different project teams, they may need to be specifically adapted and calibrated in order to operate properly in the different projects.

To ensure accurate OBD documentation across all projects, considerable efforts for synchronization and manual adjustment are necessary. Obviously, this specific approach will provide only a limited reuse potential.

Figure 2 shows the project complexity and accurate OBD documentation.

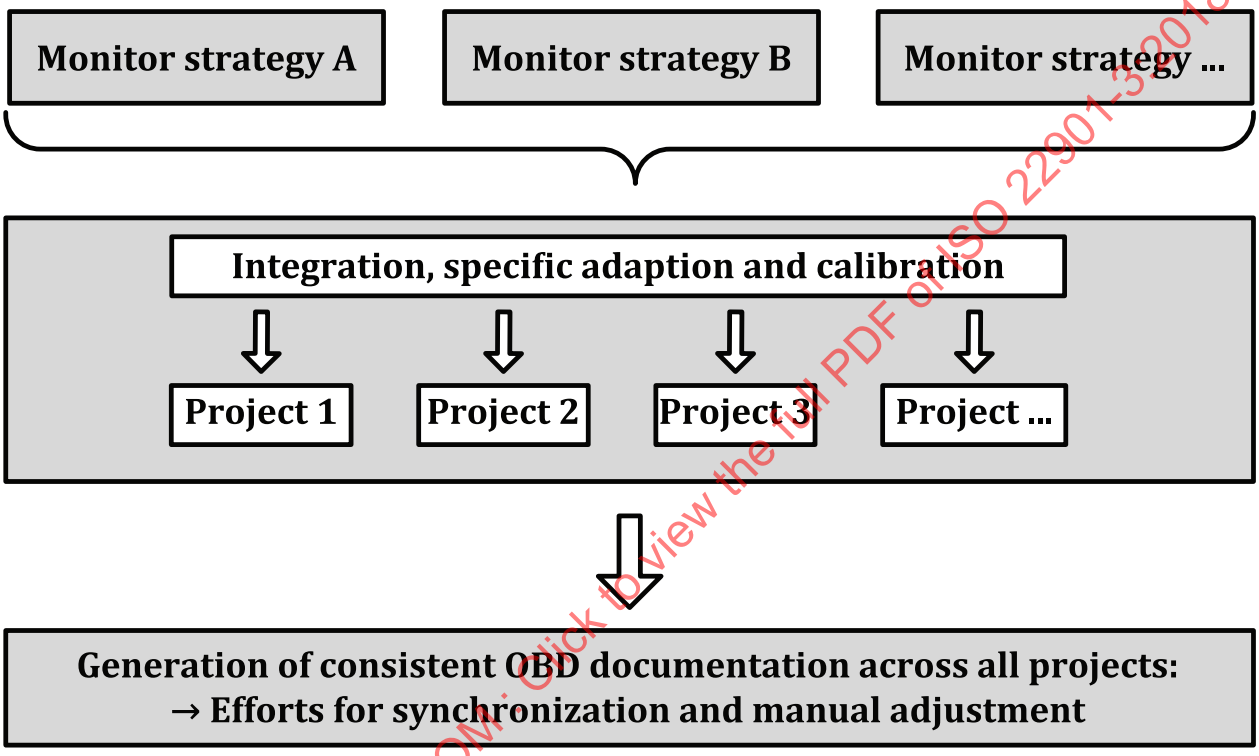


Figure 2 — Project complexity and accurate OBD documentation

In addition more complicated business models (multiple job shares across companies) challenge the OBD documentation process.

In the past, typically one ECU supplier also supplied most of the corresponding software. Nowadays and even more in future with the Autosar approach, the trend towards software packages from vehicle manufacturer and 3rd parties will increase.

As a consequence, multiple suppliers provide the information for the generation of OBD documentation with different format, structure and content. For understanding, it is often necessary to dig into the details of the complete software documentation itself. This is why the efforts for the integration and generation of OBD relevant information increases due to manual analysis and adjustment. Obviously this scenario will allow only a limited reuse.

Figure 3 shows the challenging job share and consistent OBD documentation.

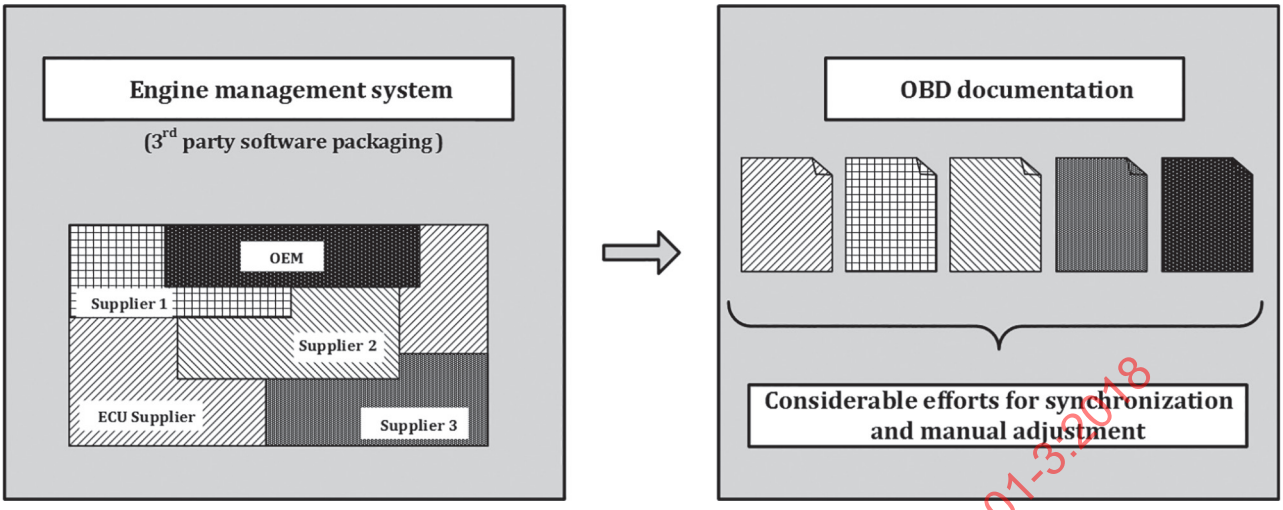


Figure 3 — Job sharing challenge and consistent OBD documentation

Scheduling constraints for generating OBD documentation during the development phase also represent a motivating factor for the introduction of the FXD approach. As the OBD development has become more and more extensive, the documentation is established as early as possible, but on the other hand late changes will cause iterations. Without efficient management of the corresponding OBD-relevant information, it is nearly impossible to answer to the challenging engineering targets and tight project schedules of today.

Road vehicles — Open diagnostic data exchange (ODX) —

Part 3:
Fault symptom exchange description (FXD)

1 Scope

This document specifies machine-readable descriptions of all fault symptom algorithms which are implemented as diagnostic software in an electronic control unit (ECU). The main use case is the standardized data exchange from a function & software supplier to a vehicle manufacturer (VM) in order to enable a tool-based information processing. Based on the FXD content and associated calibration values, several end user documents can be generated such as the "summary sheet" needed as part of the vehicle type approval documentation package or the "repair and maintenance information" (RMI). The expected main benefits of the FXD approach are an overall efficiency improvement as well as an independency of supplier- and VM-specific format handling.

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 22901-1, *Road vehicles — Open diagnostic data exchange (ODX) — Part 1: Data model specification*

SAE J1930-DA, *Digital Annex of E/E Systems Diagnostic Terms, Definitions, Abbreviations, and Acronyms*

SAE J1979-DA, *Digital Annex of E/E Diagnostic Test Modes*

SAE J2012-DA, *Digital Annex of E/E Diagnostic Trouble Code Definitions and Failure Type Byte Definitions*

3 Terms and definitions

No terms and definitions are listed in this document.

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

— IEC Electropedia: available at http://www.electropedia.org/

— ISO Online browsing platform: available at http://www.iso.org/obp

4 Abbreviated terms

For the purposes of this document, the abbreviated terms given in SAE J1930-DA, SAE J1979-DA and SAE J2012-DA and the following apply.

a2l	ASA P2 description file
AUTOSAR	AUTomotive Open System ARchitecture
DCY	driving cycle
DTC	diagnostic trouble code

ECU	electronic control unit
enum	enumeration
FCM	fault code memory
FID	function identifier
FXD	Fault symptom eXchange Description
HDO	ASAM harmonized data objects
MCL	monitoring checklist
MIL	malfunction indicator light
OBD	on-board diagnostics
OEM	original equipment manufacturer
OID	object identifier
OSC	oxygen storage capacity
RMI	repair and maintenance information
SENT	single edge nibble transmission
SI	système international d'unités
SW	software
URI	uniform resource identifier
VM	vehicle manufacturer
W3C	world wide web consortium
XML	extended mark-up language

5 Specification release version information

5.1 Specification for FXD XML-Schema release version

The schema specification release version of this document is: 2.0.0.

6 FXD concept

6.1 Overview

The automotive industry specified the requirements for provision of OBD-relevant information and developed a corresponding concept and format.

The main objectives were:

— Develop a machine-readable automotive format,

  — for single source of fault symptom description for different documentation use cases (e.g. type approval, repair and maintenance information) across project variants;

— for possible data processing utilizing state-of-the-art tooling;

— the use of XML as a base technology for the format definition (FXD XML-Schema);

— the reuse of structural patterns based on ISO 22901-1;

— the naming of structure elements which shall be close to the end user's needs.

6.2 Traditional workflow

Traditionally, the FXD-relevant information is exchanged between vehicle manufacturers and ECU software suppliers based on proprietary templates and formats.

Even the main FXD use cases "type approval" and "repair and maintenance information" are driven by different stakeholders and lead to incompatible exchange formats and processes for one and the same vehicle manufacturer.

The software suppliers have to process the full variety of templates and formats with limited reuse and a lot of manual interaction.

Finally, the integration and document generation at the vehicle manufacturer's site cannot be automated due to the non-availability of stable and standardized data formats.

6.3 Raw information

6.3.1 General definition and background

An abstract and structured description of all conditions/criteria/parameters that influence the monitoring process or strategy. It shall be possible to detect and heal a real fault via test conducted by using the "raw information" description.

The "raw information" description is a neutral description which is not biased towards any vehicle-manufacturer-specific end-user documentation.

"Raw information" descriptions will naturally need a subsequent, manual adaptation to reflect the respective requirements of the vehicle manufacturer, the project and end user documentation. This manual adaptation is within the responsibility of the vehicle manufacturer, see 6.4.

6.3.2 Requirements

6.3.2.1 General

“Raw information” descriptions shall be designed in a way to enable an automated value analysis when the relevant calibration labels are entered.

“Raw information” descriptions should refer to the corresponding software implementation. Therefore, a certain abstraction of software implementation is necessary. Furthermore, formal editing features have to be used to improve the readability (e.g. logical grouping of conditions / use of headlines where appropriate). For specific rules, see FXD rules.

The sequence of the fault detection algorithm shall be described by using a formal language. This formal language shall allow automatic processing of the information like the substitution of physical units, replacement of variable names (e.g. for different language areas), replacement of calibration labels and system constants by values, simplification and partial evaluation of expressions. The formal language shall allow the visualisation of the information for various audiences. It shall optionally be possible to describe algorithms textually if a formal description is not feasible or not desired.

6.3.2.2 Requirements for generating of raw information descriptions

Detailed requirements are defined in the rules for generation of FXD descriptions as detailed in Annex C.

6.3.2.3 Requirements for readers of "raw information" description

The information provided by the “raw information” description shall enable technically skilled staff with a general knowledge of vehicles, but no specific knowledge of diagnostics/OBD, to understand the physical process of the monitor.

Requirements:

— general engine and vehicle knowledge;

— general knowledge of diagnostics and OBD; and

— knowledge of this document (FXD).

The supplier will not assume any responsibility in case this “raw information” is forwarded to further audiences (e.g. certification authority, aftersales/service). An FXD file as provided by the supplier will not contain values of referenced calibration labels.

In case information may consist of prescribed values only, respective generic selection lists, will be provided and maintained by ISO.

6.4 FXD format and example

The main challenges for the FXD XML-Schema lie in meeting the documentation requirements of the "OBD summary sheet".

In order to enable an automatic publishing process from the FXD format to an "OBD summary sheet", all relevant information needs to be captured in the FXD format.

The fault symptom is the main structure criterion for the "OBD summary sheet". All fault-symptom-related information is organized underneath the corresponding node inside the FXD-Schema, which is called "FAULT-SYMPTOM".

Within the "OBD summary sheet" the most complex information deals with nested algorithmic expressions for "MALFUNCTION-CRITERIA" and "ENABLE-CONDITIONS". No control structures as known from programming languages are necessary.

Sample expression:

<parameter_1(operand)> < greater than…(operator)> < threshold_1(operand)>

<and/or (operator)>

<parameter_2(operand)> < less than…(operator)> < threshold_2(operand)>

The operands and operators have to be marked separately within the XML structure, as both have to be prepared for specific rendering, e.g. publishing to different table columns.

As the FXD data delivered by the software supplier will contain raw data based on the software implementation, a refinement concept is necessary to support different use cases. Therefore, the principle of inheritance is introduced to FXD, i.e. the symptom related raw data can be refined for a specific use case just by adding refined information characteristics to the FXD data. Later on, the tool chain will process the use-case-specific characteristics.

The raw data will contain software names for parameters and calibration data labels for e.g. thresholds. For generating OBD documentation, the software names have to be replaced by an end-user wording and the calibration data labels have to be replaced by the corresponding values. Both replacement mechanisms need to be supported by the FXD format.

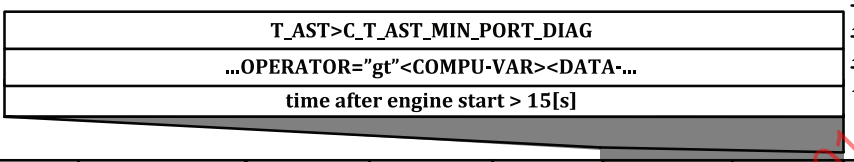
In addition to the requirements described above, the following content requests were taken into account to specify the FXD-Schema.

— interlocking matrix;

— management of FXD data at the vehicle manufacturer's site (e.g. ID management, link to function and software specifications, ...); and

— repair and maintenance information (e.g. language attribute).

Figure 4 shows the OBD summary sheet as one main motivation for the FXD format definition.



Component / System	Fault Code	Fault Code SAE Text	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Condition	Monitor Time	Frequency of Checks	MIL Illum.
Intake Manifold Runner Flap Position Sensor	P 2004	Intake Manifold Runner Control Stuck Open Bank 1	stuck closed check	signal voltage	<2,9[V]	timer after engine start	>15[s]	4[s]	continuous	2 DC

Figure 4 — OBD summary sheet as one main motivation for the FXD format definition

6.5 Basic concept of FXD

6.5.1 Basic requirements

The modelling of algorithmic expressions is a core part of the FXD-Schema and will be explained more in detail.

After analysing the content of the OBD summary sheets for algorithmic expressions, the following requests were captured:

— enable a formal description of nested algorithmic expressions, which are based on the software implementation;

— enable formal expressions (one operand may be a text string), which cannot be mapped 1:1 to the software implementation, but are necessary to reduce complexity;

— enable free text for e.g. repair and maintenance information; and

— enable direct re-use of raw information.

6.5.2 Formal description of diagnosis algorithms

For the description of fault-symptom-related conditions, the element COMPUTATION, is introduced. It can be:

— either a formal expression (ABSTRACT-SYNTAX); or

— an informal description (EXPLANATION).

The ABSTRACT-SYNTAX represents an expression tree, whose nodes may be:

— an operator (or function) OP with its arguments (operands) as child nodes (which might be again an expression tree);

— a variable COMPU-VAR, which consists of a reference DATA-DECLARATION-REF to an ECU variable, calibration parameter or system constant;

— a constant COMPU-CONST, which can be one of the following:

  — numerical value V;

  — string constant VT; or

  — boolean value VB.

The meaning of the operator OP is specified by its OPERATOR attribute. The set of valid operators is not specified in the FXD XML-Schema itself, but as digital Annex A of this document to provide the possibility to extend it without a schema change or change of the main document.

The EXPLANATION consists of an informal description DESC, providing multiple paragraphs and some standard XHTML features, and an optional set of references DATA-DECLARATION-REFS to ECU variable(s), calibration parameter(s) and system constant(s), which allows the declaration of dependencies on the ECU-data.

Figure 5 shows the COMPUTATION and ABSTRACT-SYNTAX as FXD core elements.

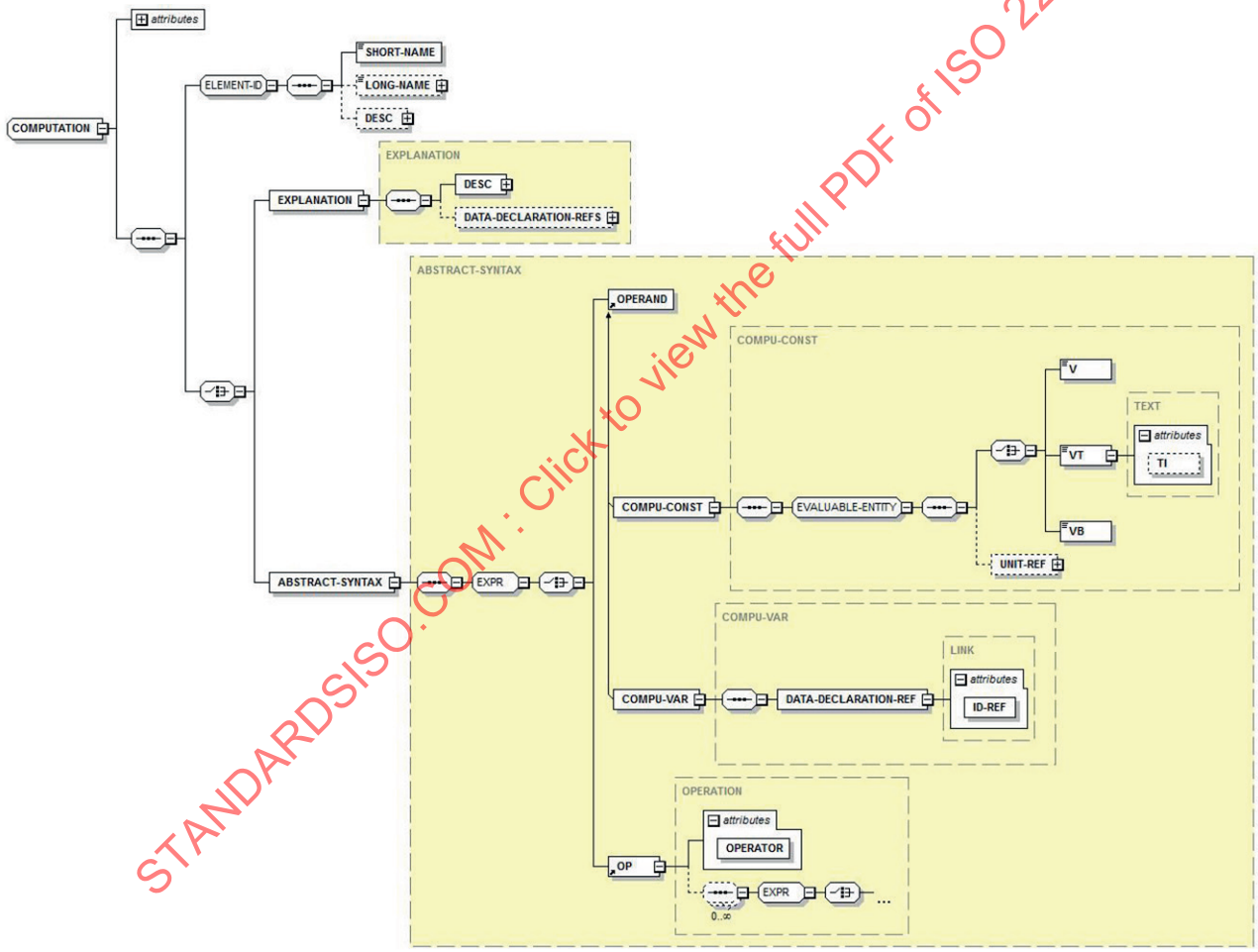


Figure 5 — COMPUTATION and ABSTRACT-SYNTAX as FXD core elements

6.5.3 Value inheritance mechanism to support use cases

Use cases in cluster 3 (see Figure 8) support the possibility to add use-case-specific representations of fault symptoms to an FXD file. A main use case in focus is the "adaptation" of malfunction criteria (FAULT-DETECTION-CRITERIA) and secondary parameters (ENABLE-CONDITIONS) by the vehicle manufacturer to comply with legislative requirements for creating type-approval-related documents. Other use cases may be representations of fault symptoms in different languages or for specific user groups.

A value inheritance mechanism is used as follows:

For each use case, an additional instance of a fault symptom can be created ("child fault symptom"), having the same name (SHORT-NAME) as the fault symptom which is derived from ("parent fault symptom").

Each child fault symptom refers to exactly one parent fault symptom. It is allowed to refer either to a fault symptom base specified by the supplier or to another existing child fault symptom.

In a child fault symptom, all sub-elements are optional to allow modification of arbitrary parts of the information of a fault symptom only.

All information, which is not specified in the child fault symptom, will be obtained from its parent hierarchy.

A child fault symptom shall not define a fault detection with a name (SHORT-NAME) that is not defined by its parent. A child fault symptom may only redefine inherited fault detections.

Implementation of value inheritance

The value inheritance mechanism applies to the elements FAULT-SYMPTOM and VARIABLE-DESCRIPTION. These elements have an SI attribute which specifies the use case. The initial FAULT-SYMPTOM or VARIABLE-DESCRIPTION from which other item descriptions are derived is called “base fault symptom” or “base variable description. The use case of these base items is “raw-information” (RAWINFO).

In order to establish value inheritance, a FAULT-SYMPTOM or VARIABLE-DESCRIPTION shall render a PARENT-REF element. The PARENT-REF refers to the parent item from which the FAULT-SYMPTOM or VARIABLE-DESCRIPTION wants to inherit. The parent item and the child item shall have the same SHORT-NAME.

The implementation of FXD value inheritance in XML-Schema makes use of the rather uncommon technique of derivation by restriction. XML-Schema allows the definition of a type by restricting the occurrences and contents of elements from the type from which it is derived.

A base symptom or variable description shall provide a minimum of information, specified by the non-optional elements. Fault symptoms or variable descriptions which make use of the FXD value inheritance only render elements which they redefine. In the simplest case, a derived fault symptom does not redefine anything but inherits all properties from its parent or ancestors. In this case the FAULT-SYMPTOM element would only have three child elements: SHORT-NAME, COMPANY-DATA-REF and PARENT-REF. Thus, the XML-Schema shall allow all other elements of a derived item to be optional.

The solution is to use XML-Schema mechanism “derivation by restriction” to define a base fault symptom type (FAULT-SYMPTOM-BASE) and a base variable description type (VARIABLE-DESCRIPTION-BASE). In the resulting FXD-XML-document, a base element is tagged with the attribute xsi:type="FAULT-SYMPTOM-BASE" or xsi:type=”VARIABLE-DESCRIPTION-BASE”.

6.6 FXD workflow

By introducing a machine-readable and standardised exchange format for the description of fault symptoms it is possible to improve the overall workflow.

The variety of formats and templates will be replaced by this document on the ECU software supplier's side. This will enable a homogeneous tool chain and a reuse of FXD data. The ECU software supplier will deliver "raw data", i.e. data, which are based on the software implementation and will be refined by the vehicle manufacturer depending on the use case.

For the vehicle manufacturer, the following tasks can be efficiently supported by tools in order to reduce the manual interaction:

— integration of FXD data from different ECU software suppliers;

— refinement of FXD data for different use cases (type approval, repair and maintenance information);

— enhancement of FXD data with calibration values; and

— creation of end user documents.

Figure 6 shows a possible FXD workflow.

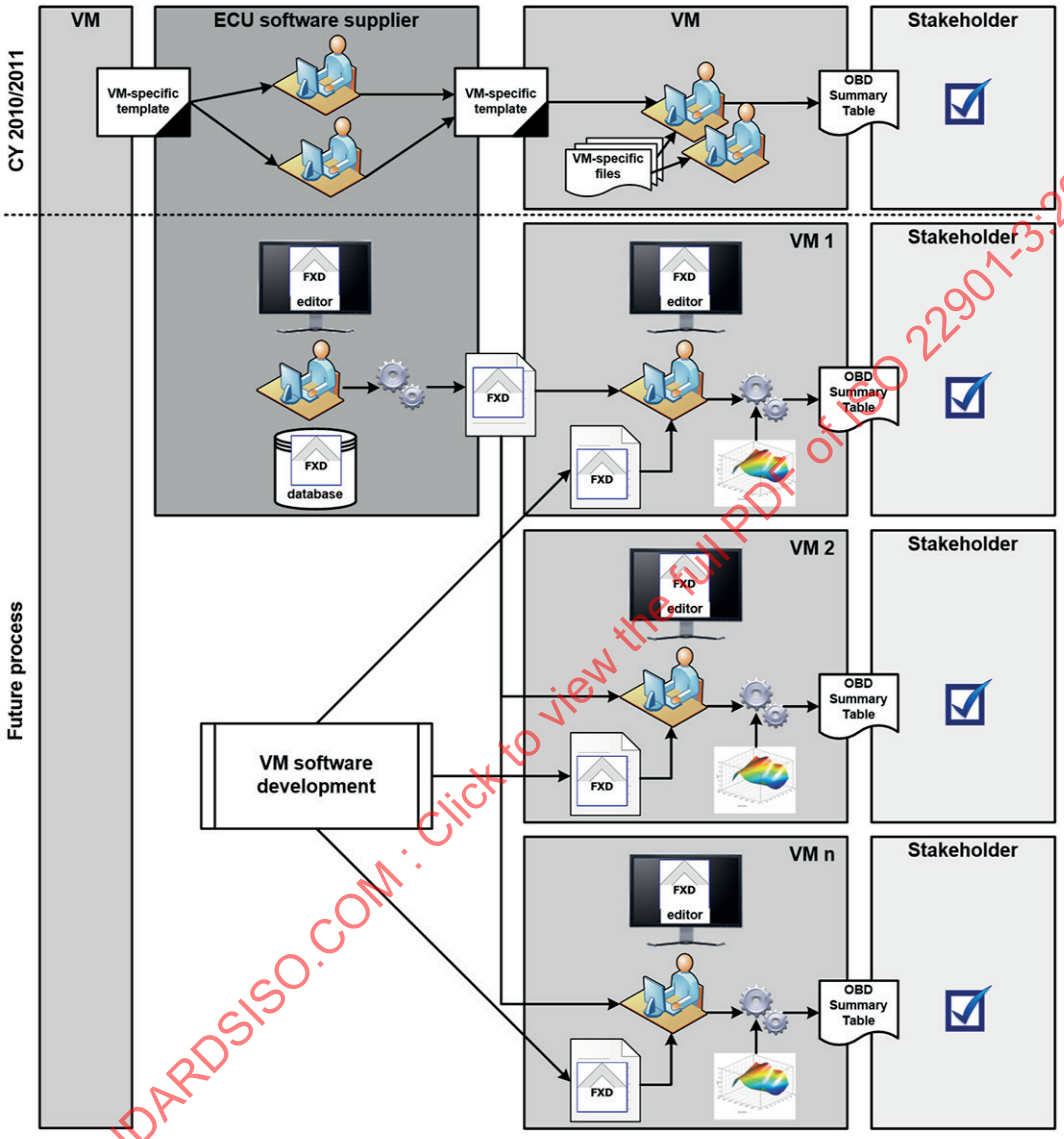


Figure 6 — Possible FXD workflow

6.7 FXD workflow example

A possible FXD workflow is shown below, choosing the "enable condition" of the fault symptom "Intake Manifold Runner Control - Stuck Open – Bank 1" as an example.

Step 1: Manage raw data on the ECU software supplier side

The raw data will either be entered into an FXD editor or be retrieved from existing systems. A dedicated FXD tool is required in order to manage the information. The raw data are based on software names, which are software-supplier-specific.

For the ABSTRACT-SYNTAX a set of rules are implemented, which allow to provide feedback regarding problems within algorithmic expressions. In addition, features like auto completion and checks for valid software names are recommended to be implemented.

Step 2: Create the FXD – XML file

Once the fault symptom information is completed on the ECU software supplier side, which is an iterative step along the software development process, there is the possibility to create an FXD file according to the FXD-Schema. This file will be delivered to the vehicle manufacturer.

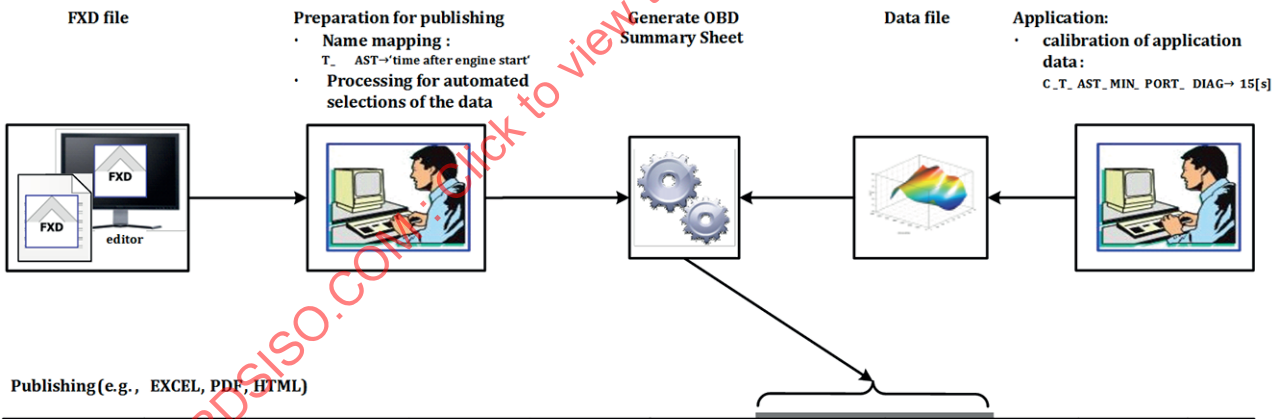
Step 3: Integrate and refine the FXD information on the vehicle manufacturer side

After receiving the FXD information from the supplier, the vehicle manufacturer will integrate the FXD parts into a FXD repository. Depending on the complexity of the fault symptom algorithm, it is necessary to refine the description for the different use cases. For the chosen example no refinement is necessary, as it is a simple enable condition. In addition, it is necessary to introduce a use-case-specific alias name for software parameters. In this example the alias name "time after engine start" is introduced for the original software-name T_AST.

Step 4: Generate the OBD summary sheet

After finalising the integration and refinement steps, the information is ready to be processed for end-user documentation. The value of C_T_AST_MIN_PORT_DIAG will be retrieved from the calibration value set. The unit (identical structural pattern as specified in ISO 22901-1) is part of the FXD label definition. Finally a rendering process will use the corresponding information in order to publish the information "Time after engine start > 15 s".

Figure 7 shows the processing steps in order to create the OBD summary sheet information.



Component / System	Fault Code	Fault Code SAE Text	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Condition	Monitor Time	Frequency of Checks	MIL Illum.
Intake Manifold Runner Flap Position Sensor	P2004	Intake Manifold Runner Control Stuck Open Bank 1	stuck closed check	signal voltage	<2, 9[V]	time after engine start	> 15[s]	4[s]	continuous	2 DC

Figure 7 — Processing steps in order to create the OBD summary table information

6.8 Constraints for schema updates

The update of the FXD XML-Schema to fulfil new requirements can cause having to update the tooling on both sides, supplier and OEM. Further, for new required fields the suppliers may need a phase-in time to generate the new descriptions.

In order to allow a continuous work with the latest schema version, the standard text “empty due to migration to new schema” is introduced.

The suppliers shall use the standard text “empty due to migration to new schema” to identify new mandatory text fields that could not be filled with a proper description. This new standard text shall be used only on mandatory text fields. New optional fields will not be created.

7 FXD use cases

7.1 General

This document has been specified in order to exchange information related to electronic control unit (ECU) fault symptoms between ECU software supplier and vehicle manufacturer.

This document specifies:

— the contents of the fault symptom exchange description (FXD) on a per-fault symptom basis;

— the XML-based structure of the fault symptom exchange description (FXD XML-Schema); and

— the supported use case for the exchange of the above mentioned description.

Figure 8 shows the principal information flow and use cases overview.

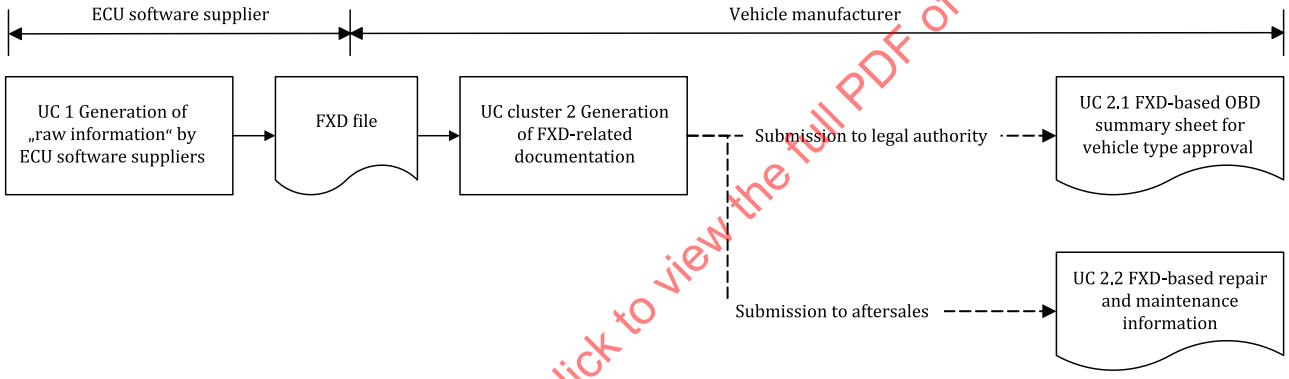


Figure 8 — Principal information flow and use cases overview

7.2 UC 1 Delivery of "raw information" by ECU software suppliers

Table 1 specifies the UC 1 Delivery of "raw information" by ECU software suppliers.

Table 1 — UC 1 Delivery of "raw information" by ECU software suppliers

Use case name	UC 1 Delivery of "raw information" by ECU software suppliers
Goal	Delivery of "raw information" from the ECU software program version by ECU software suppliers supports the generation of the FXD-based OBD summary sheet and fault symptom information for aftersales repair & maintenance information.
Actor	ECU software supplier
Use case input	ECU software program version
Use case output	FXD-XML raw information specific to the ECU-software-program version
Brief description	The 'raw' fault symptom information is provided as a so-called "fault symptom base". This representation of a fault symptom may not be suitable for different vehicle manufacturer-specific use cases, therefore additional representations of the same fault symptom can be added. For a more detailed description of the mechanism used, see 6.5.3.

In addition to a program version delivered to a vehicle manufacturer, the supplier may deliver a corresponding file, containing a negotiated description of fault symptoms supported by the respective program version. This file will be referred as FXD file.

Any information provided has to be considered as "raw information".

7.3 UC 2 – Generation of documentation based on FXD raw information

7.3.1 UC 2.1 Generation of OBD summary sheet for vehicle type approval

Table 2 specifies the UC 2.1 Generation of OBD summary sheet for vehicle type approval.

Table 2 — UC 2.1 Generation of OBD summary sheet for vehicle type approval

Use case name	UC 2.1 Generation of OBD summary sheet for vehicle type approval
Goal	Generate OBD summary sheet from FXD file as documentation for vehicle type approval
Actor	Vehicle manufacturer
Use case input	program version data version FXD-XML "raw information" specific to the ECU-software-program version information on disabling relations between the individual symptoms legal requirements other information as deemed necessary
Use case output	OBD summary sheet shall contain: component / system name; legislation-referenced DTC; customer code (DTC); customer code (customer fault text); monitor strategy description; malfunction criteria; threshold value; secondary parameters; enable conditions; fault debouncing; monitoring frequency; MIL illumination; ...
Brief description	The information supplied in the raw information is prepared according to the vehicle manufacturer's specifications, taking further input information (e.g. legal requirements) into account, and it is converted into wording that is understandable for the authority. The vehicle manufacturer then replaces the application labels used in the raw information with the application values according to the specific program and data version of the project to be described. See Figure 11.

7.3.2 UC 2.2 FXD-based repair and maintenance information

Table 3 specifies the UC 2.2 FXD-based repair and maintenance information.

Table 3 — UC 2.2 FXD-based repair and maintenance information

Use case name	UC 2.2 FXD-based repair and maintenance information
Goal	Generate FXD-based repair and maintenance information as part of the vehicle manufacturer's service information publication package to repair garages
Actor	Vehicle manufacturer
Use case input	program version; data version; FXD-XML "raw information" specific to the ECU-software-program version; information on disabling relations between the individual symptoms; and other information as deemed necessary.
Use case output	Instructions for guided troubleshooting. Service information sheet shall contain: component / system name; legislation-referenced DTC; customer code (DTC); customer code (customer fault text); monitor strategy description; OK-DETECTION-CRITERIA; threshold value; secondary parameters; enable conditions; OK-DEBOUNCE; malfunction criteria; MIL illumination; substitution function; protection function; ...
Brief description	After finalising the integration and refinement steps (see 6.6), the information is ready to be processed for end-user documentation. In addition to the information about the fault detection, information for service concerning fault healing is processed as well.. Finally, a rendering process will use the corresponding information in order to publish the information, e.g. "Time after engine start > 15 s".

8 General properties of FXD elements

8.1 Attributes

Generally, there are two kinds of attributes:

Content: Attributes that support an assessment of the content of the related FXD element. This information is used to control further processing of the FXD information itself.

Infrastructure: Attributes that are used to identify the internal XML-structure of an FXD description

In the following, the existing attributes are introduced.

8.1.1 DESC-EXTENT (Content)

DESC-EXTENT identifies the completeness of the related description of the fault symptom.

It is defined for the elements:

— FAULT-SYMPTOM

— VARIABLE-DESCRIPTION

Table 4 definies the supported values of the attribute DESC-EXTENT.

Table 4 — Supported values of DESC-EXTENT

Value	Explanation
COMPLETE	To identify a complete description
PARTIAL	To identify an incomplete description. PARTIAL shall only be used in case the supplier is not responsible for the missing parts of the description, e.g. in case of diagnostics performed by a smart device.

The attribute DESC-EXTENT needs to be distinguished from DESC-STATE. The attribute DESC-STATE shall be used to identify descriptions that are – from the author's perspective and responsibility – not yet finalised and therefore not yet mature.

8.1.2 HREF (Content)

HREF identifies an external document by an URI. If the URI is not absolute (i.e. it does not start with a scheme) then it is resolved first against the base URI specified by xml:base, second against the URI of current document location.

e.g. HREF="http://www.iso.org/iso/iso_catalogue/catalogue_tc/catalogue_detail.htm?csnumber=60264"

It is defined for the elements:

EXTERNAL-DOC

8.1.3 ID (Infrastructure)

ID provides an XML-internal identifier for the related element, which can be used to refer to this element, see ID-REF.

e.g.: ID="ID47110815"

It is defined for the elements:

— AUXILIARY-OBJECT;

— COMPANY-DATA;

— COMPUTATION;

— DATA-DECLARATION;

— FAULT-DETECTION;

— FAULT-SYMPTOM;

— FAULT-SYMPTOM-3RD-PARTY;

— FID;

— MASK;

— PHYSICAL-DIMENSION;

— SERVICE-06-ID;

— UNIT; and

— VARIABLE-DESCRIPTION.

The value of ID shall conform to standard XML type xs:ID.

8.1.4 ID-REF (Infrastructure)

ID-REF is used to refer to another XML element by specifiying the value its ID attribute, see ID.

e.g.: ID-REF=”ID47110815”

It is defined for the elements:

— AUXILIARY-OBJECT-REF;

— COMPANY-DATA-REF;

— COMPUTATION-REF;

— DATA-DECLARATION-REF;

— FAULT-SYMPTOM-REF;

— FID-REF;

— MASK-REF;

— PARENT-REF;

— PHYSICAL-DIMENSION-REF;

— SERVICE-06-ID-REF; and

— UNIT-REF.

8.1.5 OID (Content)

OID is used for invariant identification of an FXD element but not for linking. Any FXD compliant tool shall not change the content of the OID (if present) over the whole life cycle of the concerned element. Any system that provides import/export facilities of FXD into another format shall ensure to maintain an OID during an import / modify / export cycle. The provider is responsible to ensure the uniqueness of the OID. Therefore, the use of Universally Unique Identifiers (UUIDs) as described in ISO/IEC 11578:1996 is recommended.

e.g. OID=”499848a3-d5a2-48d9-bd45-525c99e903b3”.

It is defined for the elements:

— FAULT-SYMPTOM; and

— VARIABLE-DESCRIPTION.

8.1.6 OPERATOR (Content)

Operator specifies the specific FXD operator to be applied to the child elements of the current element.

e.g. OPERATOR=”duration_of”

It is defined for the elements:

OP

The set of supported values consists of all specified FXD operators, in accordance with Annex A.

8.1.7 SI (Content)

SI (Semantic Information) specifies the semantic characteristic of the related element.

Table 5 defines the supported values of SI.

Table 5 — Supported values of SI

Value	Explanation
RAWINFO	For “neutral” descriptions delivered by the system supplier according to UC 2.
SUMMARY	For “final” descriptions created according to UC 2.1.
SERVICE	For “final” descriptions created according to UC 2.2.
OTHER	For other use cases

e.g. SI=”RAWINFO”

It is defined for the elements:

— FAULT-SYMPTOM;

— TEXT-MAPPING; and

— VARIABLE-DESCRIPTION.

8.1.8 DESC-STATE (Content)

State specifies the maturity of the related element.

e.g. DESC-STATE=”RELEASED”

It is defined for the elements:

— FAULT-SYMPTOM; and

— VARIABLE-DESCRIPTION.

Table 6 defines the supported values of the attribute DESC-STATE.

Table 6 — Supported values of DESC-STATE

Value	Explanation
INITIAL	For initial descriptions
DRAFT	For intermediate maturity
RELEASED	For finalised descriptions

8.1.9 TI (Infrastructure)

TI (Text Identifier) provides an XML-internal identifier for the related textual element, which is intended to be used to specify alternative texts/formulations (e.g. in a different language).

e.g.: TI=”TI47110816”

It is defined for the elements:

— DESC;

— DISPLAY-NAME; and

— VT.

TI consists of a string of arbitrary characters.

8.1.10 VERSION (Content)

Version provides the current version number of the FXD-Schema as the only supported value. It thus specifies the structure and content of the related FXD file.

It consists of three numbers 'x.y.z': 'x' will be increased in case of incompatible changes, 'y' will be increased in case of compatible changes (e.g. only optional elements are removed or added), 'z' is increased for bug fixes.

Note, that in any case former documents become invalid with respect to the new schema version because at least the FXD version number has changed. Applications shall consider this issue and decide whether or not to accept a FXD document

e.g.: VERSION=”1.5.0”

It is defined for the elements:

FAULT-SYMPTOM-EXCH-DESC

The specified schema version shall be used for validation purposes of an FXD file.

8.1.11 xml:base (Infrastructure)

xml:base is a World Wide Web Consortium recommended facility for defining base URIs for parts of XML documents.

It is defined for the elements:

FAULT-SYMPTOM-EXCH-DESC

8.1.12 xml:lang (Infrastructure)

xml:lang is used to specify the natural language in which the content of the related element is given.

It is defined for the elements:

— COMPUTATION;

— FAULT-SYMPTOM;

— FAULT-SYMPTOM-EXCH-DESC;

— TEXT-MAPPING; and

— VARIABLE-DESCRIPTION.

For supported values, refer to http://www.iso.org/iso/home/standards/language_codes.htm.

8.1.13 xsi:nil (Content)

xsi:nil is used to allow empty content at dedicated mandatory elements.

It is allowed for the following elements and has the following semantic:

— CUSTOM-CODES / no custom code existing;

— ENABLE-CONDITIONS / no enable condition existing;

— FAULT-DEBOUNCE / no fault debounce existing;

— LEGAL-CODE / no legal code existing;

— LEGISLATIONS / no legislations existing;

— OK-DEBOUNCE / has same content as FAULT-DEBOUNCE;

— OK-DETECTION-CRITERIA / is logical inversion of content of FAULT-DETECTION-CRITERIA; and

— OK-ENABLE-CONDITIONS / has same content as ENABLE-CONDITIONS.

In order to enable this attribute, the respective element shall have the nillable attribute set to true in the corresponding schema definition.

8.1.14 xsi:type (Infrastructure)

xsi:type shall be used to specify the proper XML type in the schema in case of ambiguities. Here, it is needed to select the base type for inheritance for fault symptoms and variable descriptions with attribute SI attribute set to RAWINFO.

It is defined for the following elements with the following values:

— FAULT-DETECTION / @xsi:type="FAULT-DETECTION-BASE";

— FAULT-DETECTIONS / @xsi:type="FAULT-DETECTIONS-BASE";

— FAULT-SYMPTOM / @xsi:type="FAULT-SYMPTOM-BASE"; and

— VARIABLE-DESCRIPTION / @xsi:type="VARIABLE-DESCRIPTION-BASE".

8.2 Variant coding

The following different types of variant coding have been identified:

— Depending on the value of a calibration label different algorithms are activated in the software: These conditions will be provided as part of the COMPUTATIONS (e.g. referenced by ENABLE-CONDITIONS) in the FXD file.

— Depending on the value of a function-internal calibration label, algorithms may be activated or deactivated. These labels are described in a dedicated element, for details see DISABLE-REPORT-ONLY (see 9.6.11.13) and DISABLE-FULLY (see 9.6.11.14).

— Multiple calibration data sets exist for one program version, which means that one calibration label may represent different values for different data sets: The FXD file as provided by the supplier will contain generic calibration label names only, so this use case is not considered.

8.3 Generic selection lists

For several information elements, the values shall be derived from general selection lists (in accordance with Annex B):

— MON_COMPONENT;

— MON_FREQUENCY;

— READINESS_GROUP;

— RATIO_GROUP;

— MCL_STRATEGY (legislation-reference);

— SIMULATION_METHOD; and

— GENERIC_TYPE.

These generic selection lists shall be versioned, released and provided by ISO.

Constraints for selection list content:

— existing values from all older versions shall remain valid; and

— new versions will not be applied to existing data.

According to the various examples provided so far, spaces and special characters have to be supported. So, arbitrary strings will be supported without additional mark-up for all selection lists in the schema.

8.4 External document references

If required, an arbitrary number of external documents (e.g. images, complex descriptions) may be referenced from the DESC and the RESOURCES element, using the optional structure EXTERNAL-DOCS.

8.5 Referencing ECU variables and calibration labels

To refer to ECU variables or calibration labels, the element DATA-DECLARATION is introduced. A DATA-DECLARATION contains the name of the variable or calibration label, including "[...]" for array element access and "." for substructure access, if required, e.g. "DSM.DFC_test".

NOTE In case of variant coded calibration labels, only the generic name will be provided, see 8.2.

Additional information about labels shall be obtained from the 'a2l' file, if necessary, e.g. physical units, axes labels of curves and maps.

Each DATA-DECLARATION may be referenced where appropriate using a DATA-DECLARATION-REF. This allows multiple references to the same DATA-DECLARATION for reuse.

8.6 General FXD elements, used for identification and description

The following group of FXD elements is used to uniquely identify the fundamental elements of a diagnostic SW algorithm. These are mainly variables, calibration parameters and configuration parameters (system constants), fault symptoms, variable descriptions and FIDs.

It consists of:

— SHORT-NAME: mandatory identifier according to the specification of an ASAM HDO SHORT-NAME;

— LONG-NAME: optional element to provide a human readable name according to the specification of an ASAM HDO LONG-NAME; and

— DESC: optional element for further details.

This group of elements is referred to as “Element-Id”.

9 Description of FXD elements

9.1 General

Subclauses 8.2 to 9.4 describe the FXD-Schema elements specifying general information needed e.g. for the exchange of the FXD file.

9.2 ADMIN-DATA

9.2.1 General

The ADMIN-DATA element is modelled similar to the ODX element with the same name, but some extensions are needed to specify the project-specific information (see 9.2.2 to 9.2.6).

9.2.2 COMPANY-DATA-REF

Within the COMPANY-DATA-REF, the company providing the FXD file (see 8.3) is referred by the attribute ID-REF.

9.2.3 ECU-FAMILY

The control unit family is to be entered to identify the type of control unit the descriptions are created for.

9.2.4 PROJECT

This element is used to identify the project. The project will be specified by its name (NAME) and its version (SW-BASELINE).

9.2.5 RESOURCES

The element RESOURCES shall be used to identify project-specific files, which are used as data base for the FXD file:

— DATA-DESCRIPTION shall contain a reference to the data description resource, e.g. 'a2l' file (mandatory);

— CALIBRATION shall contain a reference to the calibration data set (optional);

— EXTERNAL-DOCS may contain references to additional files used. Each EXTERNAL-DOC provides a textual explanation of the document and the reference to it by the attribute HREF.

9.2.6 DOC-REVISIONS

DOC-REVISIONS are a subset of the same element of ISO 22901-1.

This information is used to distinguish between different releases of a FXD file for one program version.

Each DOC-REVISION consists of

— REVISION-LABEL: optional text field to specifiy the version,

— STATE: mandatory element to specify the maturity by the predefined schema values:

  — DEVELOPMENT (for development deliveries to the vehicle manufacturer);

  - SERIES (for series delivery to the vehicle manufacturer);
  - RELEASED (for released by the vehicle manufacturer).
- DATE: mandatory element to specify the delivery date.

9.3 COMPANY-DATAS

9.3.1 General

Information about all companies responsible for the FXD file contents (e.g. name, involved personnel) will be specified here. It is a subset of the same ISO 22901-1 ODX element. For each company one element COMPANY-DATA shall be provided.

9.3.2 COMPANY-DATA

COMPANY-DATA consists of the following elements, identifying a company and its members:

- Element-Id (see 8.6),
- TEAM-MEMBERS: optional element to provide information on company members. For details refer to ISO 22901-1.

NOTE ECU software suppliers will provide information about companies only.

9.4 DATA-DICTIONARY

9.4.1 DATA-DECLARATIONS

DATA-DECLARATIONS are used to describe control unit internal variables, calibration data types and system constants.

Each DATA-DECLARATION consists of:

- Element-Id (see 8.6);
- DATA/DATA-NAME: mandatory element that contains the ‘a2l’ name of the DATA-DECLARATION;
- DATA/DATA-TYPE: mandatory element to specify the type by one of the following predefined schema values:
  - CALIBRATED (for calibration data to be replaced when generating the summary sheets);
  - CALIBRATION-INFO (calibration data which is used for information and should not be replaced by its value);
  - NON-CALIBRATABLE (non calibratable constants, e.g. system constants);
  - ONLINE (variables);
  - STATE-VALUE (values of state machine variables);
- DATA/DISPLAY-NAME: optional element to provide the DISPLAY_IDENTIFIER from the 'a2l' file; and
- DATA/DATA-VALUE: optional structure to provide a Boolean (VB), a numerical (V) or a textual (VT) value together with an optional (reference to a) physical unit (via UNIT-REF).

A DATA-DECLARATION is referred by one or more computations. This list is introduced to enable reuse of DATA-DECLARATIONS. A precondition for the DATA-DECLARATIONS is that internal variables and calibration data are unique within their context ('a2l' file).

9.4.2 COMPUTATIONS

A COMPUTATION is used to describe a computation algorithm in a formal or in a textual/verbal manner. A COMPUTATION consists of:

— Element-Id (see 8.6) and

— Either: ABSTRACT-SYNTAX: Formal syntax tree consisting of operators and operands. The operands can either be constants (COMPU-CONST) or variables (COMPU-VAR, referencing DATA-DECLARATIONs).

— Or: EXPLANATION: A textual, human-readable description.This variant can be used when an ABSTRACT-SYNTAX would be too complex, or a more human-friendly informal description is desired. It may also be useful if the details shall not be described but only the general purpose of the algorithm.

In either case the variables and calibration parameters etc. which the algorithm uses should be listed under DATA-DECLARATION-REFs. This helps to understand functional relationship between various variables.

Figure 9 visualises an ABSTRACT-SYNTAX expression (N > C_N_Thr + 1 000 rpm).

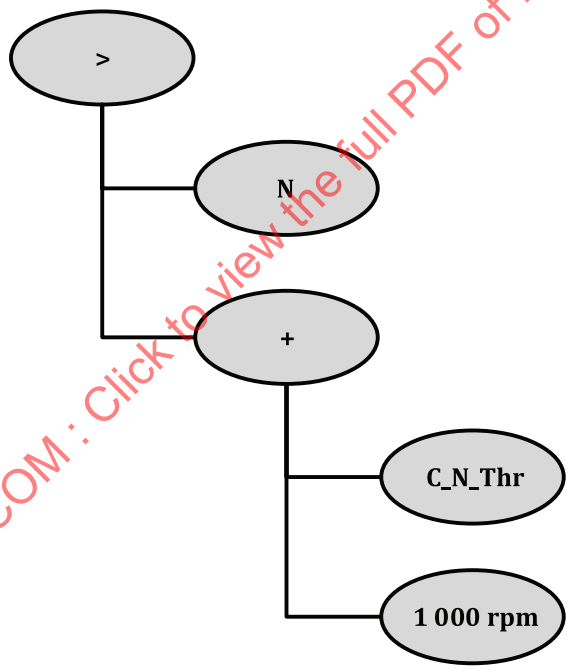


Figure 9 — Visualisation of an ABSTRACT-SYNTAX expression

A corresponding FXD representation is:

<ABSTRACT-SYNTAX>

<OP OPERATOR=”gt”>

<COMPU-VAR>

<DATA-DECLARATION-REF ID-REF="N"/>

</COMPU-VAR>

<OP OPERATOR=”add”>

<COMPU-VAR>

<DATA-DECLARATION-REF ID-REF="C_N_Thr"/>

</COMPU-VAR>

<COMPU-CONST>

<V>1000</V>

<UNIT-REF ID-REF=”rpm”/>

</COMPU-CONST>

</OP>

</OP>

</ABSTRACT-SYNTAX>

— It is important to note, that FXD computations are not required to be evaluable. It is completely legal to define a computation that would have the form (in pseudo-code): sqrt(“some mysterious function”). This is because the main purpose of FXD is the description of functions, functional relationships, conditions and algorithms for documentation issues. However, FXD computations should be as formal as possible to allow automatic processing. This approach has some great advantages:

— FXD computations can be partly evaluated. For example calibration labels can be replaced by values and parts of the computation (sub-trees of the abstract syntax) can be reduced.

— The whole computation can be transformed so that variables or physical units are replaced. For example the condition V32 > 100 km/h can be automatically transformed into “current velocity” > 62 mph.

— Inconsistencies and circular dependencies can be detected.

— FXD computations can be further processed, especially for visualisation.

9.4.3 UNIT-SPEC

This list is introduced to enable reuse of physical units. They are referenced by a computation formula if needed for constant values.

The UNIT-SPEC including UNIT-GROUPS, UNITS, and PHYSICAL-DIMENSIONS is defined as a subset of the corresponding element in ISO 22901-1.

NOTE Physical units of variables and calibration labels are implicit and have to be derived from the 'a2l' file.

9.5 VARIABLE-DESCRIPTIONS

9.5.1 General

A VARIABLE-DESCRIPTION is used to describe the computation of an ECU variable (in FXD represented by a DATA-DECLARATION with DATA-TYPE set to “ONLINE”) in detail. Within the schema, the element VARIABLE-DESCRIPTIONS is designed on the same level as the element FAULT-SYMPTOMS. It also includes the same meta information (COMPANY-DATA-REF, ECU-FUNCS, CONFIGURATION, attributes: DESC-EXTENT, DESC-STATE, ID, OID, SI, xml:lang)

A VARIABLE-DESCRIPTION supports three different **variable types**:

SIMPLE-VARIABLE: single COMPUTATION;

BIT-FIELD-VARIABLE: COMPUTATION for each contained BIT-FIELD; and

STATE-GRAPH: definition of the STATES and COMPUTATION for each supported STATE-TRANSITION.

VARIABLE-DESCRIPTIONs are subject to the same value inheritance mechanism as FAULT-SYMPTOMs. For this purpose, there is a PARENT-REF element. See section on value inheritance.

If a VARIABLE-DESCRIPTION is inherited from another VARIABLE-DESCRIPTION the variable type shall not be changed. In addition, the complete information of the variable type can only be overwritten as a whole.

9.5.2 Element-Id

Key of variable description: supplier specific unique name, described in accordance with 8.6.

9.5.3 COMPANY-DATA-REF

This element contains the reference to the company providing the VARIABLE-DESCRIPTION.

9.5.4 ECU-FUNCS

The section specifies the names and the versions of the ECU-FUNCs contributing to the calculation of the variable described.

Each ECU-FUNC consists of the two elements described below.

9.5.4.1 LONG-NAME

This is the supplier-specific name of the ECU-FUNC according to the specification of a HDO LONG-NAME as provided in the 'a2l' file.

9.5.4.2 VERSION

This element contains the version of the ECU-FUNC as given in the ‘a2l’ element FUNCTION_VERSION for the function calculating the described variable.

9.5.5 CONFIGURATION

This element contains the references to DATA-DECLARATIONS representing non-calibratable constants ("system constants") which have an influence on the calculation of the described variable.

9.5.6 DATA-DECLARATION described by a VARIABLE-DESCRIPTION

This element contains a reference to the DATA-DECLARATION element, which is described by this VARIABLE-DESCRIPTION.

9.5.7 SIMPLE-VARIABLE

A SIMPLE-VARIABLE is used if the variable (e.g. a byte or even a single bit) represents a single physical value, which is not a state (of a state machine). For this use case, the calculation is described by a single COMPUTATION.

9.5.8 BIT-FIELD-VARIABLE

If the value of a variable does not represent a single value but distinct bits or bit fields represent independent values (i.e. flags) the BIT-FIELD-VARIABLE element is used. A BIT-FIELD-VARIABLE consists of BIT-FIELDs, each of them representing a single physical value. A BIT-FIELD is defined by:

A LONG-NAME;

A BIT-MASK (unsigned integer); and

A BIT-FIELD-COMPUTATION, referencing a COMPUTATION.

NOTE The BIT-FIELD-COMPUTATION returns a value for the bit field to be described, but it will not be aligned with the bit field position.

EXAMPLE If a single bit is described, the BIT-FIELD-COMPUTATION will return 0/1 regardless at which bit position the corresponding bit is defined.

9.5.9 STATE-GRAPH

If the variable represents the states of a state machine the STATE-GRAPH element is used.

A STATE-GRAPH consists of:

— STATES: lists the supported state values of the variable using DATA-DECLARATION-REFs to DATA-DECLARATIONs of DATA-TYPE 'STATE-VALUE'.

— INITIAL-STATE: lists the initial state, using a DATA-DECLARATION-REF to a DATA-DECLARATION of DATA-TYPE 'STATE-VALUE'.

— STATE-TRANSITIONS: Consists of an arbitrary number of STATE-TRANSITIONs, specifying the:

— FROM-STATE (Reference to a DATA-DECLARATION);

— TO-STATE (Reference to a DATA-DECLARATION); and the

— REQUIRED-CONDITION (Reference to a COMPUTATION specifying conditions that shall be fulfilled for the state transition to take place).

— STATE-COMPUTATION: Possibility to specify the computation of the documented state values from the internal values of the state graph variable, if there is no 1:1 mapping between the two (e.g. masking and shifting of dedicated bits, in this case the state graph variable is implemented as a bit field).

NOTE The DATA-DECLARATION-REFs in INITIAL-STATE, FROM-STATE, TO-STATE is listed in the element STATES.

9.6 FAULT-SYMPTOMS

9.6.1 General

This subclause describes FXD-Schema elements specifying fault-symptom-specific information.

NOTE Fault symptoms in a program version supplied by 3rd parties will be described separately (see 9.7).

9.6.2 Element-Id

Key of (fault-symptom-based) description: supplier-specific unique name of the fault symptom described in accordance to section 8.6.

NOTE The SHORT-NAME of the FAULT-SYMPTOM shall correspond to the FAULT-SYMPTOM-NAME of the 'a2l' file

EXAMPLES for SHORT-NAMEs:

— DFC_Agre; and

— PVS_DRIFT.

9.6.3 COMPANY-DATA-REF

This element contains the reference to the company providing the FAULT-SYMPTOM.

9.6.4 ECU-FUNCS

The section specifies the names and the versions of the ECU-FUNCs, contributing to the calculation of the fault symptom. Annex C contains the correct listing of functions/versions.

9.6.4.1 LONG-NAME

This element contains the supplier-specific name of the ECU-FUNC according to the specification of an HDO LONG-NAME as provided in the 'a2l' file.

EXAMPLE DSALSU

9.6.4.2 VERSION

This element contains the version of the ECU-FUNC as given in the 'a2l' element FUNCTION_VERSION for the diagnostic function.

9.6.5 CONFIGURATION

This element contains the references to DATA-DECLARATIONS representing non-calibratable constants ("system constants") which have an influence on the calculation of the described fault symptom.

Additionally, the value of each system constant, shall be given in the corresponding DATA-VALUE element. Further details are contained in Annex C.

9.6.6 FAULT-IDENTIFICATION

9.6.6.1 Legal code

The fault code requested by legislation is provided as a reference to a computation which is either a value, or a label, or a label with indexation that can be given. Table 7 defines the external test equipment FAULT-CODE.

Table 7 — External test equipment FAULT-CODE

Reference to OBD summary table	OBD Fault Code
Format	Implemented as a reference to a computation (COMPUTATION-REF). Thus, the element can contain either a calibration label name or an actual value entered as a decimal value.

9.6.6.2 CUSTOM-CODES

Here, the customer-specific code is provided as a reference to a computation where either a value, or a label, or a label with indexation can be given. In addition to that, the type of the CUSTOM-CODE can be specified in order to enable a distinction between different CUSTOM-CODES. Table 8 defines the service fault code.

Table 8 — Service fault code

Reference to OBD summary table	None
Format	Implemented as a reference to a computation (COMPUTATION-REF). Thus, the element can contain either a calibration label name or an actual value entered as a decimal value.

9.6.6.3 FAULT-TYPE

Each fault symptom can be allocated to a DTC and, additionally, further distinctive features can be provided for the corresponding fault symptom for the service. The classification of the fault types is regulated in SAE J2012 [3]. Table 9 defines the element FAULT-TYPE.

Table 9 — FAULT-TYPE

Reference to OBD summary table	None
Format	Implemented as a reference to a computation (COMPUTATION-REF). Thus, the element can contain either a calibration label name or an actual value entered as a hexadecimal value.

9.6.7 MON-COMPONENT or system

This element provides a short description of the MON-COMPONENT or system.

EXAMPLE Accelerator Pedal Position Sensor 1.

Table 10 defines the element MON-COMPONENT / system.

Table 10 — MON-COMPONENT/system

Reference to OBD summary table	Component/System
Format	Text field with ASCII characters
SELECTION-LIST-NAME	MON_COMPONENT

9.6.8 FAULT-CLASSIFICATION

This element consists of either an ERR-CLASS or a MIL-RELEVANCE and an additional, optional element MIL-DEBOUNCE-GROUP.

9.6.8.1 ERR-CLASS

This element contains information about the connection between the driver warning (MIL, EPCL/SYS etc.) and the priority.

Table 11 defines the element ERR-CLASS.

Table 11 — ERR-CLASS

Reference to OBD summary table	MIL Illumination
Format	Implemented as a reference to a computation (COMPUTATION-REF). Thus, the element can contain either a calibration label name or an actual value entered as a decimal value.
Additional information	Examples for possible fault classes are: Service fault (NOT OBD-relevant) OBD-relevant faults (with priority "Fault" for the service tester) OBD-relevant faults "Fuel system monitoring" and "Misfire" OBD-relevant faults "Misfire monitoring" [MIL + flashing MIL] Service fault (NOT OBD-relevant) with clearance of service fault as per OBD [service only] OBD-relevant faults with clearance of service fault as per OBD [MIL]

9.6.8.2 MIL-RELEVANCE

This field contains the information of whether the described FAULT-SYMPTOM should switch the OBD lamp on.

Table 12 defines the element MIL-RELEVANCE fault.

Table 12 — MIL-RELEVANCE fault

Reference to OBD summary table	MIL Illumination
Format	Implemented as a reference to a computation (COMPUTATION-REF). Thus, the element can contain either a calibration label name or an actual value entered as "true" or "false".

9.6.8.3 MIL-DEBOUNCE-GROUP

If shared MIL debouncing becomes necessary for several FAULT-SYMPTOMS with fault memories based purely on FAULT-SYMPTOMS, and if this has been agreed with homologation, these FAULT-SYMPTOMS may be assigned to one MIL group.

Table 13 defines the element MIL DEBOUNCE-GROUP.

Table 13 — MIL-DEBOUNCE-GROUP

Reference to OBD summary table	None
Format	Implemented as a reference to a computation (COMPUTATION-REF). Thus, the element can contain either a calibration label name or an actual value entered as a decimal value.
Additional information	Only if the MIL group is directly hardcoded in the software (program), this dependency has to be described as text. One example of a description: Fuel System Monitoring in the additive and mulitplicative range: FRAmax represents the fault symptoms FRAmax, FRAmin, ORAmax, ORAmin.

9.6.9 RATIO-GROUPS for in-use monitor performance ratio (IUMPR)

For FAULT-SYMPTOMS from component groups that are required to be output as IUMPR via service 0916 in accordance with OBD legislation and which shall be assigned to a specified RATIO-GROUP. The RATIO-GROUP is to be entered from a selection list (see B.3.4). Multiple assignments are supported.

Table 14 defines the element RATIO-GROUP.

Table 14 — RATIO-GROUP

Reference to OBD summary table	Yes
Format	Implemented as a reference to a computation (COMPUTATION-REF). Thus, the element can contain either a calibration label name or an actual value entered as a decimal value.
SELECTION-LIST-NAME	RATIO_GROUP
Additional information	For all fault symptoms from a ratio group, the lowest IUMPR individual ratio is to be calculated in the control unit and the associated numerator and denominator for this lowest ratio output via service 09. IUMPR individual ratios for fault symptoms that do not have to be output for compliance with OBD legislation, but which are still linked to IUMPR (e.g. purely service-relevant sub-diagnostics on the oxygen sensor) can also be assigned to predefined extended ratio groups (without SAE short identifiers). However, the lowest individual ratio is not calculated. These extended ratio groups serve exclusively for theme-related IUMPR data evaluation.

9.6.10 READINESS-GROUP

Documentation of allocation for FAULT-SYMPTOMS with respect to readiness status (Service 0116, PID 0116) and monitor status (Service 0116, PID 4116). Table 15 defines the element READINESS-GROUP.

Table 15 — READINESS-GROUP

Reference to OBD summary table	None
Format	Implemented as a reference to a computation (COMPUTATION-REF). Thus, the element can contain either a calibration label name or an actual value.
---	For every fault symptom concerned, the associated readiness group is to be entered.
SELECTION-LIST-NAME	READINESS_GROUP

9.6.11 FAULT-DETECTIONS

9.6.11.1 FAULT-DETECTION general information

Since for a given fault symptom multiple strategies to detect a fault may exist, for each of them a separate FAULT-DETECTION shall be provided. In the following, the subelements of a single FAULT-DETECTION are described.

9.6.11.2 Element-Id

Key of fault detection description: supplier specific unique name of the fault detection, described in accordance to section 8.6.

9.6.11.3 MON-STRATEGY

This element provides a rough classification of the underlying fault detection algorithm.

Table 16 defines the element MON-STRATEGY.

Table 16 — MON-STRATEGY

Reference to OBD summary table	Monitor strategy description
Format	Text field with ASCII characters
Additional information	Terms based on the MCL are principally to be used.

For rationality and functional checks, it should be clear and comprehensible on the basis of the description used how the employed strategy works for the concerned component. It is not enough to simply enter terms such as "rationality check".

Terms are to be used, such as:

— Functional check stuck closed;

— Rationality check unable to open;

— Measurement of OSC compared to OSC of borderline catalyst; and

— CAN communication with gateway, etc.

9.6.11.4 FAULT-DETECTION-CRITERIA

This element contains the description of the fault detection criteria, which is defined as follows:

— The FAULT-DETECTION-CRITERIA is the criterion which "decides" whether a fault is present or not.

— This decision may be preliminary in the sense that a subsequent confirming phase can still be necessary to distinguish between an actual fault and a misdetection. This confirming phase is typically referred to as "debouncing".

— Every condition that has to be fulfilled as a precondition so that the decision can be computed does not belong to the FAULT-DETECTION-CRITERIA. These are enable (or test) conditions.

Annex C contains further details.

Table 17 defines the element FAULT-DETECTION-CRITERIA.

Table 17 — FAULT-DETECTION-CRITERIA

Reference to OBD summary table	Malfunction Criteria / Threshold Value
Format	Implemented as a reference to a computation (COMPUTATION-REF), see 9.4.2.
Additional information	Here, the description of the basic fault symptom detection criterion is provided. The description is to be provided preferably in a formal way by using the sub-element ABSTRACT-SYNTAX. If the complexity of the fault detection criterion exceeds a certain limit, the description may also be provided in the form of a verbal description using the subelement EXPLANATION. The decision between formal and verbal description should be taken on a case by case basis.

9.6.11.5 ENABLE-CONDITIONS

Here, the description of physical enable conditions (or test conditions) for each FAULT-DETECTION-CRITERIA shall be given.

When structuring the description, the definitions (see 3.1) and the ABSTRACT-SYNTAX (see 9.4.2) is to be taken into account. The internal control unit label names are used for the descriptions. If this is not the case, the terms specified in SAE J1930-DA are principally to be used. Table 18 defines the element ENABLE-CONDITIONS.

Definition of ENABLE-CONDITIONS:

— Every condition, that has to be fulfilled as a precondition, (once or during the complete calculation of the fault detection criterion) that the fault detection criterion can be computed is an enable (or test) condition;

— An atomic enable condition can typically be presented in the form: "Label simple comparison operator threshold"; and

— Single atomic enable conditions can be combined by further operators, such as "AND","OR" etc.

Table 18 — ENABLE-CONDITIONS

<table>
<tr><th>Reference to OBD summary table</th><th colspan="3">secondary parameters / enable conditions</th></tr>
<tr><td>Format</td><td colspan="3">Implemented as a reference to a computation (COMPUTATION-REF), see 9.4.2.</td></tr>
<tr><td>Additional Information</td><td colspan="3">Here, the conditions are described that have to be fulfilled in order to enable the computation of the fault detection criterion.
The following conditions have similar effects as enable conditions; however, they are to be listed in separate elements since they are used for controlling and filtering in the subsequent document processing.</td></tr>
<tr><td></td><td>Element</td><td>Calibration</td><td>Effects</td></tr>
<tr><td></td><td>CENTRAL-CALIBRATION-INFORMATION (9.6.1.2)</td><td>Central</td><td>Monitoring function is active. Fault code management is inhibited.</td></tr>
<tr><td></td><td>DISABLE-FULLY (9.6.11.14)</td><td>Decentral</td><td>Monitoring function is not active.</td></tr>
<tr><td></td><td>DISABLE-REPORT-ONLY (9.6.11.13)</td><td>Decentral</td><td>Monitoring function is active. Fault code management is inhibited.</td></tr>
<tr><td></td><td colspan="3">Enable conditions that are managed using sequential control (between engine and monitoring functions shall be documented exclusively in the element EXCLUSION (9.6.13.2).</td></tr>
</table>

9.6.11.6 Debounce information for fault detection

Brief description of the debounce process, taking the applied “program parameters” into account. The applied “program parameters” are displayed by means of a referencing process, for which a value, a label, or a label with textual description is used (see Figure 10).

9.6.11.7 FAULT-DEBOUNCE

The Debounce Time refers to the time period between the time when the fault is detected and the time when the fault is stored in the fault memory. This applies to a defective component.

Marginal conditions:

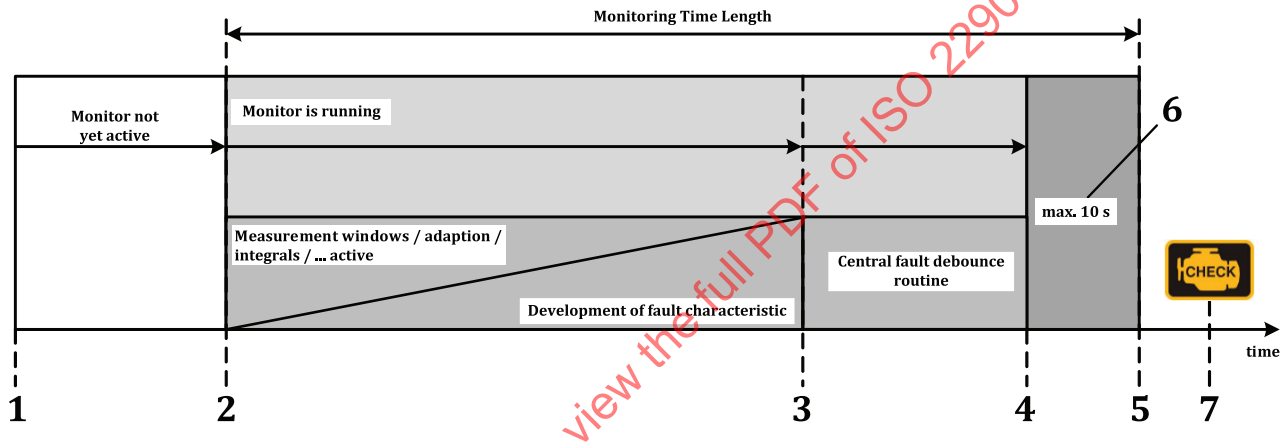
This applies to a neutral system, i.e. no adaptations had taken place within the preceding driving cycles (neither positive nor negative) before the defective component to be monitored was installed. Furthermore, the defective component to be monitored produces a fault value that has exactly the value necessary, and is thus just large enough for the monitor to detect a fault (neither lower nor higher).

Table 19 defines the element FAULT-DEBOUNCE.

Table 19 — FAULT-DEBOUNCE

Reference to OBD summary table	Fault Debouncing Length
Format	Implemented as a reference to a computation (COMPUTATION-REF).
Additional information	Here, the control unit supplier is expected to submit a proposal in an XML structure describing the complete debouncing method and which can also be integrated into an ODX container. This refers to the debouncing process starting with the fulfillment of the FAULT-DETECTION-CRITERIA. EXAMPLE: time-based debouncing, incident-based debouncing, etc. The vehicle manufacturer will be responsible for simplifying the homologation documents. In English, only the terms agreed with the homologation officials are to be used for this description of fault debouncing (specification in Master Summary Table from homologation).

Figure 10 shows the calculation of the monitoring time length.



Key

1 defective component installed
2 monitor start
3 fault detected
4 fault detected and debounced
5 updates: OBD modes, IUMPR, fault memory, ...
6 Maximum time period to store the fault in the fault memory (FCM) in accordance with applicable OBD legislation
7 Pending / MIL

Figure 10 — Determination of the monitoring time length

9.6.11.8 MON-FREQUENCY

The supplier delivers the raw information as a proposal and the vehicle manufacturer applies the information e.g. for the summary sheets according to the calibration data.

A list of possible values will be provided as defined in Annex B.

Table 20 defines the element MON-FREQUENCY.

Table 20 — MON-FREQUENCY

Reference to OBD summary table	Frequency of Checks
Format	Text field with ASCII characters
SELECTION-LIST-NAME	MON_FREQUENCY
—	A defined term entered by the supplier for the OBD summary table in accordance with the specification in the Master OBD summary table from homologation (see Additional information).
—	For vehicle manufacturers, an additional description element is required in order to enter valuable information for service.

Definition of the monitoring frequency

On a functional level, the monitoring frequency describes the most frequent execution of a diagnostic functionality, e.g. a diagnostic monitor that the ECU software is capable of.

On the level of a concrete application, the monitoring frequency describes the actual behaviour of the functionality on this application. In the following the term monitor refers to one specific FAULT-DETECTION.

For the assessment of the monitoring frequency, all prerequisites are taken into account, especially values calculated in other functions, which are used as part of the diagnostic monitor.

Example

A diagnostic monitor has a set of parameters influencing the monitoring frequency:

"number of times for which the monitor is executed in one dcy"

"delay time of the monitor after monitoring result"

With these two parameters, the diagnostic monitor could be tuned to anything between continuous and once.

Continuous

"number of times for which the monitor is executed in one dcy" = FF (infinitive),

"delay time of the monitor after monitoring result" = 0.

Once

"number of times for which the monitor is executed in one dcy" = 1,

"delay time of the monitor after monitoring result" = FF (infinitive).

Definition

Once per ECU lifetime

The monitor is usually executed only once per ECU lifetime. This may be a check during production of the ECU or during production of the vehicle.

Once per driving cycle

Regardless how many times the enable conditions of a monitor are met during a driving cycle, the monitor only runs once and reports the pass/fail decision to the fault code memory only once.

Figure 11 illustrates how the monitoring cycle is processed if run once.

NOTE 1 This is just an example.

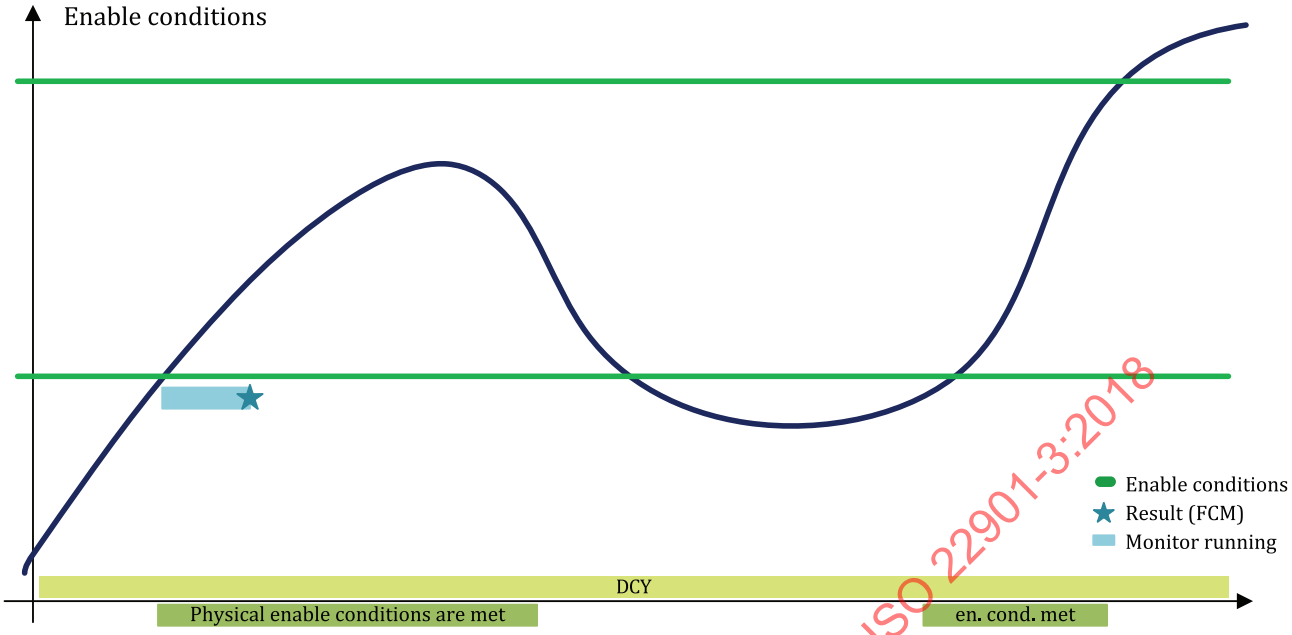


Figure 11 — Definition Once per driving cycle

Continuous

Every time the enable conditions of a monitor are met, the diagnostic monitor is executed immediately. After the time necessary to execute the diagnostic monitor and report to fault code memory, the monitor is executed again.

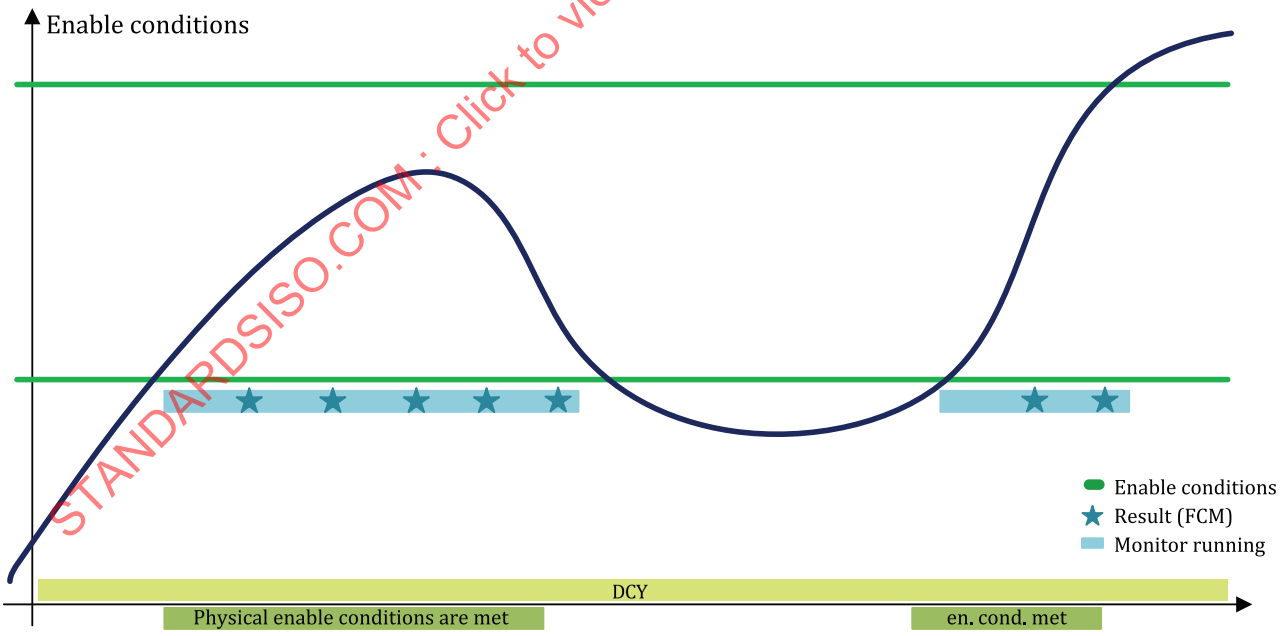


Figure 12 — Definition Continuous

Figure 12 illustrates how the monitoring cycle is processed if continusously monitored.

NOTE 2 This is just an example.

Multiple

The diagnostic monitor is executed more than once in a driving cycle.

Each time the enable conditions are met, the monitor produces at least one pass fail decision but does not run continuously.

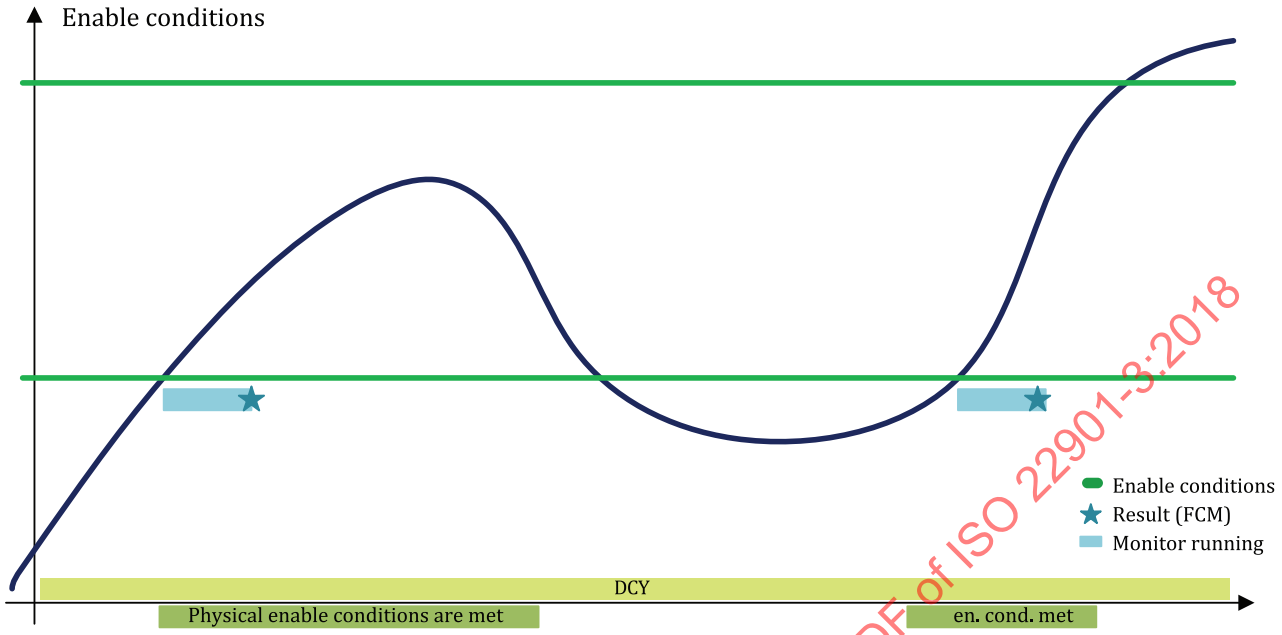


Figure 13 — Definition Multiple

Figure 13 illustrates how the monitoring cycle is processed if multiple definitions of monitoring apply.

NOTE 3 This is just an example.

9.6.11.9 OK-DETECTION-CRITERIA

This element provides the description of the OK detection algorithm by referencing a COMPUTATION. For details on COMPUTATIONS, see 9.4.2.

Definition of OK-DETECTION-CRITERIA:

— The OK-DETECTION-CRITERIA is the criterion which "decides", whether healing is present or not.

— This decision may be preliminary in the sense that a subsequent confirming phase can still be necessary to distinguish between actual healing and misdetection. This confirming phase is typically referred to as "debouncing".

— Every condition that has to be fulfilled as a precondition so that the decision can be computed does not belong to the OK-DETECTION-CRITERIA. These are enable (or test) conditions for fault healing.

Table 21 defines the element OK-DETECTION-CRITERIA.

Table 21 — OK-DETECTION-CRITERIA

Reference to OBD summary table	none
Format	Implemented as a reference to a computation (COMPUTATION-REF), see 9.4.2.
Additional information	Here, the description of the basic fault symptom healing detection criterion is indicated. The description is to be provided preferably in a formal way by using the sub-element ABSTRACT-SYNTAX. If the complexity of the fault detection criterion exceeds a certain limit, the description may also be provided in the form of a verbal description using the subelement EXPLANATION. The decision between formal and verbal description should be taken on a case by case basis.

9.6.11.10 OK-ENABLE-CONDITIONS

Description of physical enable conditions/test conditions for healing.

This is an element which shall be used only in case a diagnostic monitor is asymmetric with respect to enable conditions (i.e. if the enable conditions for healing detection are differing from the enable conditions for fault detection).

When structuring the description, the definitions (see 3.1) and the ABSTRACT-SYNTAX (see 9.4.2) is to be taken into account. The internal control unit label names are used for the descriptions. If this is not the case, the terms specified in SAE J1930-DA are principally to be used defines the enable conditions.

Definition of enable conditions for healing:

Every condition that has to be fulfilled as a precondition (once or during the complete calculation of the healing detection criterion) that the healing detection criterion can be computed is an enable (or test) condition.

— An atomic enable condition can typically be presented in the form: "Label simple comparison operator threshold".

— Single atomic enable conditions can be combined by further operators, such as "AND","OR" etc.

— Table 22 defines the element OK-ENABLE-DETECTION.

Table 22 — OK-ENABLE-DETECTION

Reference to OBD summary table	none
Format	Implemented as a reference to a computation (COMPUTATION-REF), see 9.4.2.
Additional Information	Here, the conditions that have to be fulfilled in order to enable the computation of the healing detection criterion are described.

9.6.11.11 OK-DEBOUNCE

Brief description of the debounce for the OK detection, taking the applied "program parameters" (see) into account. The applied “program parameters” are displayed by means of a referencing process, for which a value, a label, or a label with textual description is used (see Figure 10).

Table 23 — OK-DEBOUNCE

Reference to OBD summary table	None
Format	Implemented as a reference to a computation (COMPUTATION-REF).

9.6.11.12 Reference to OBD legislation

9.6.11.12.1 General

This element is needed for OBD relevant fault symptoms and will be omitted for others. This element contains a reference to the part of legislation that initiated the introduction or change of the fault symptom and will be provided by the supplier.

9.6.11.12.2 LEGISLATIONS

The LEGISLATION reference shall be provided as a text field with ASCII characters. The content of the text field shall be the section numbering of the regulation and its detail.

EXAMPLE

LAW CCR 1968.2

SECTION (e)(11.2.1)(A)

Here, no update will be expected for the life time of the software, only in the event that new features were introduced which will - as a rule - lead to another symptom name, should the new section of LEGISLATION be stated. Table 24 defines the reference to OBD LEGISLATION.

Table 24 — LEGISLATION

Reference to OBD summary table	MCL
Format	Text field with ASCII characters
—	The additional, optional XML element receives the name MCL-STRATEGY
Additional information	This information is the first step towards generating a list of MONITORING REQUIREMENTS, which illustrates the connection between component, section of legislation and SAE J2012-DA code. The assignment "Name of fault symptom" to fault code is performed by the vehicle manufacturer using data.

9.6.11.12.3 MCL-STRATEGY

This information is necessary for all OBD-relevant comprehensive components and contains a generic description of the FAULT-DETECTION-STRATEGY of the FAULT-SYMPTOM. The terminology to be used is listed in a Selection List (in accordance with Annex B). Table 25 defines the element MCL-STRATEGY.

Table 25 — MCL-STRATEGY

Reference to OBD summary table	MCL
Format	Text field with ASCII characters
SELECTION-LIST-NAME	MCL_STRATEGY

9.6.11.13 DISABLE-REPORT-ONLY

Inactive conditions shall be distinguished from physical enable conditions, since inactive conditions:

— cannot change during ECU-runtime (rather they are typically fixed by the engineering calibration process); and

— will be used for control of further documentation processing.

This element provides the description of function-internally defined conditions that have to be fulfilled so that the fault detection is deactivated.

In DISABLE-REPORT-ONLY, inactive conditions shall be described that deactivate error reports to fault storage memory only, whereas the calculation of the diagnostic algorithm is not deactivated.

The description is implemented by a reference to a COMPUTATION. For details on COMPUTATIONS, see 9.4.2. Table 26 defines the element DISABLE-REPORT-ONLY.

Table 26 — DISABLE-REPORT-ONLY

Reference to OBD summary table	Inactive conditions shall not appear in the OBD summary table
Format	Implemented as a reference to a computation (COMPUTATION-REF). Thus, the element can contain either a calibration label name (Abstract-Syntax) or an actual value entered as a decimal value.
Additional information	Enter here which conditions have to be fulfilled to deactivate fault reporting. This point is not to be confused with 9.6.12 CENTRAL-CALIBRATION-INFO. In both cases, fault output is suppressed, however, in this case, the function itself, not a central label, suppresses the fault report.

9.6.11.14 DISABLE-FULLY

Inactive conditions shall be distinguished from physical enable conditions, since inactive conditions:

— cannot change during ECU-runtime (rather they are typically fixed by the engineering calibration process); and

— will be used for control of further documentation processing.

This element provides the description of function internally defined conditions that have to be fulfilled so that the fault detection is deactivated.

In DISABLE-FULLY, inactive conditions shall be described that deactivate the calculation of the diagnostic algorithm, so that no error will be reported to fault storage memory.

The description is implemented by a reference to a COMPUTATION. For details on COMPUTATIONS, see 9.4.2. Table 27 defines the element DISABLE-FULLY.

Table 27 — DISABLE-FULLY

Reference to OBD summary table	Inactive conditions shall not appear in the OBD summary table
Format	Implemented as a reference to a computation (COMPUTATION-REF). Thus, the element can contain either a calibration label name (Abstract Syntax) or an actual value entered as a decimal value.
Additional information	Enter here which conditions have to be fulfilled to deactivate the calculation of the diagnostic algorithm, so that no error will be reported to fault storage memory.

9.6.11.15 OBD service 0616 information

To enable reuse for this information, one or more specific elements in the OBD service 0616-list — Request on-board monitoring test results for specific monitored systems, as defined in ISO 15031-5, are referenced. For a detailed description of OBD service 0616 information, see 8.8. This information will be indicated for OBD service 0616 relevant fault symptoms only.

9.6.11.16 GENERIC-TYPE

This element contains the information, which type of diagnostic the fault symptom belongs to.

The following values are supported:

— COMMUNICATION;

— ELECTRICAL; and

— OTHER DIAGNOSIS.

Table 28 defines the element GENERIC-TYPE.

Table 28 — GENERIC-TYPE

Reference to OBD summary table	None
Format	Text field with ASCII characters
Attribute	Use case
SELECTION-LIST-NAME	GENERIC_TYPE

Description of the supported standard values:

COMMUNICATION: the fault symptom detects communication error between 2 ECUs or between 1 ECU and an intelligent component.

ELECTRICAL: the fault symptom detects electrical errors that are continuously monitored or not continuously monitored; further detailed classification regarding the monitoring frequency can be generated using the already existing element – MON-FREQUENCY-

OTHER DIAGNOSIS: the fault symptom detects errors that are not electrical or of communication kind.

9.6.12 CENTRAL-CALIBRATION-INFOS

This element provides central calibration labels that affect the behaviour of fault-symptom-related software (and thus the behaviour of the fault symptom itself).

Here, central means provided by a central service functionality (e.g. fault symptom manager) for all fault symptoms in a program version, in contrast to calibration labels locally defined in specific software functions.

These central calibration labels, although they state an enable condition from the logical point of view, shall not be listed as part of the general enable conditions (see 9.6.11.5 ENABLE-CONDITIONS) since they do not represent a physical enable condition (i.e. their value will not change during ECU runtime) and will be used for control of further documentation processing.

The element COMPUTATION-REF contains the label information, i.e. the name of the calibration label, whereas the element INFO-TYPE contains information about the type of the information.

Since the calibration labels described here will mostly be supplier-specific, the INFO-TYPE values will also be supplier-specific. The following symptom characteristics are typically determined by the central calibration:

— Activation/Deactivation of the fault symptoms;

— Configuration/Setting of the initialisation behaviour;

— Suppression of the monitor during defined operating conditions;

— Control of the fault memory output (master/slave control unit);

— Settings regarding central fault-debounce mechanisms; etc.

If more than one calibration labels are used by the supplier, they are all to be listed.

Table 29 defines the element CENTRAL-CALIBRATION-INFO.

Table 29 — CENTRAL-CALIBRATION-INFO

Reference to OBD summary table	None
Format	Implemented as a reference to a computation (COMPUTATION-REF) along with a text field "INFO-TYPE" for additional information on the calibration label referenced to in the COMPUTATION-REF.

9.6.13 INHIBITIONS information

9.6.13.1 INHIBITIONS by symptom

INHIBITIONS by symptoms either provides the list of symptoms (FAULT-SYMPTOM-REFS) which inhibit the calculation of the (currently described) fault symptom hard-coded or it provides a list of FIDs (FID-REFS), each FID providing a list of inhibiting fault symptoms (FAULT-SYMPTOM-REFS) or inhibiting auxiliary objects (AUXILIARY-OBJECT-REFS).

Annex D contains further details and defines the list of validation FIDs.

Table 30 — List of validation FIDs

Reference to OBD summary table	Secondary Parameter
Format	Contains a set of references to a function identifier (FID) with child element FID-TYPE set to validation
Additional information	All calibration assignments (see Annex D, Figure D.2) are to be listed for all validation FIDs and inhibiting FIDs referenced by INHIBITIONs. This concerns, for example, symptoms, signal qualities, auxiliary events and similar. In order to make a complete assessment of the application allocations possible, the debounce status valid for the individual allocations stated above are to be listed to take the FID into consideration. EXAMPLE: Limits (e.g. Def50_Deb100, Tested, ...) Signal qualities (1...15) Masks (ERR, PND, REC, ...)

The element inhibition by symptom provides a list of FIDs (FID-REFS), with each FID providing a list of inhibiting fault symptoms or – via COMPUTATION-REF – calibration labels, which also contain a list of inhibiting fault symptoms. Table 31 defines the list of INHIBITIONS by symptom via FIDs.

Table 31 — List of INHIBITIONS BY-SYMPTOM via FIDs

Reference to OBD summary table	Disablement Chart
Format	Implemented as set of references to a function identifier (INHIBITIONS/BY-SYMPTOM/FID-REFS/FID-REF) each referencing a set of inhibiting fault symptoms (FIDS/FID/FAULT-SYMPTOM-REFS/FAULT-SYMPTOM_REF)) or inhibiting auxiliary objects (FIDS/FID/AUXILIARY-OBJECT-REFS/AUXILIARY-OBJECT-REF).
Additional information	All calibration allocations (see Annex D, Figure D.2) are to be listed for all validation FIDs and inhibiting FIDs referenced by INHIBITIONS. This concerns, for example, symptoms, signal qualities, auxiliary events and similar. In order to make a complete assessment of the calibration allocations possible, the debounce statuses valid for the individual assignments stated above are to be listed to take the FID into consideration. EXAMPLE: Limits (e.g. Def50_Deb100, Tested, ...) Signal qualities (1...15) Masks (ERR, PND, REC, ...) This additional information does not have to be supplied to all vehicle manufacturers.

Description of the fault symptoms which will directly inhibit the described fault symptom directly in the SW.

Table 32 defines the description of inhibiting fault symptoms (hard coded).

Table 32 — Description of inhibiting fault symptoms (hard coded)

Reference to OBD summary table	Disablement Chart
Format	List of fault symptom names as used in the container containing the element.

9.6.13.2 INHIBITIONS by function

INHIBITIONS by functionality contains information concerning temporary disablement of the calculation of the considered fault symptom by EXCLUSION, which means due to other functionality currently performed. The EXCLUSION can be described by the supplier as:

— Free text to denote the disabling functionality,

— Reference to one or more calibration label(s) containing one or more disabling FIDs.

The vehicle manufacturer can prepare the EXCLUSION for the usage in the summary sheet in a formalized way.

To implement those requirements, this element provides the EXCLUSION by referencing a COMPUTATION. For details on COMPUTATIONS, see 9.4.2.

Some diagnostic functions cannot be executed at the same time as other functions, for example mixture adaptation and fuel tank ventilation. This suppression should be treated in the same way as an inhibit condition and be scheduled accordingly. All symptom names and/or functions should be entered that are in direct congruence to the symptom under consideration. If exclusions can be defined via the application, the relevant application labels are to be stated.

Table 33 defines the element EXCLUSIONS.

Table 33 — EXCLUSIONS

Reference to OBD summary table	Enable condition
Format	Text field with ASCII characters
Element 1	One or more application labels
Element 2	Description field

9.6.14 SUBSTITUTION-FUNCTION

A description of additional, function-internal measures being activated once the fault symptom is stored in the fault memory shall be provided in an XHTML text format. The activation of the substitution function is carried out via a hard-coded link between the symptom and the substitution function.

NOTE Here, only measures that are activated by the function/module that causes the entry of the fault symptom in the fault memory (i.e. function-internal) will be described.

Table 34 defines the description of SUBSTITUTION-FUNCTION (hard-coded).

Table 34 — Description of SUBSTITUTION-FUNCTION (hard-coded)

Reference to OBD summary table	None
Format	Human readable description in XHTML format.

9.6.15 PROTECTIVE-FUNCTION

A description of additional, function-internal measures being activated before the fault symptom is stored in the fault memory shall be provided in an XHTML text format.

NOTE The functionality to activate the PROTECTIVE-FUNCTION is not calibratable but hard-coded in the software. Such behaviour is usually undesirable but for the protection of people and the technical equipment it cannot always be avoided for technical reasons.

Table 35 defines the element PROTECTIVE-FUNCTION.

Table 35 — PROTECTIVE-FUNCTION

Reference to OBD summary table	None
Format	Human readable description in XHTML format.

9.6.16 SIMULATION-METHOD

This element provides a rough classification of the simulation method to trigger the OBD-relevant fault symptom.

Table 36 defines the element SIMULATION-METHOD.

Table 36 — SIMULATION-METHOD

Reference to OBD summary table	The simulation method shall not appear in the OBD summary table as described in the selection list. Maybe more detailed information is requested by the authorities.
Format	Text field with ASCII characters
Attribute	Use case
SELECTION-LIST-NAME	SIMULATION_METHOD

Supported standard values and their semantics (and examples) are:

— **REMOVE COMPONENT**: to trigger a fault symptom by removal of components.

Sensors unplugged

Missing particulate filter

— **MODIFIED COMPONENT**: a customised electrical or mechanical manipulation has been designed on the component that should have the same effects as the real failure.

Particulate filter efficiency: mechanical deterioration

Gasoline catalyst efficiency: aging using an oven

— **BREAK OUT BOX**: simulation of electrical failure.

Short circuit

Open circuit

— **EXTERNAL SIGNAL SIMULATION BOX**: to trigger a fault symptom, a simulation of the inputs of the system (sensors signal) is needed.

O2 sensor too slow

NOx sensor not available

— **EXTERNAL ACTUATOR DRIVER BOX**: to trigger a fault symptom, a simulation of the outputs (actuator position) is needed via a driver box.

Stuck closed EGR

Misfire generation via ignition coil driving

— **SOFTWARE CONTROL STRATEGY**: to trigger a fault symptom, a dedicated software control strategy has been coded to simulate the environment. The strategy shall be activated via an external tool request, no external box is needed.

Misfire generation through a tool request

O2 sensor too slow

— **NOT FEASIBLE** in homologation: there is no way to demonstrate the failure associated with the fault symptom (for example if there is a risk of severe damage to the vehicle).

Memory corruption

Atmospheric pressure electrical failure (when the pressure sensor is inside the ECU and not reachable)

— **OTHER**: for further information

9.6.17 ##other-Information (for symptoms)

Objective of this mechanism is to add any XML content with a different namespace than no-name-namespace. E.g. vehicle manufacturers can list additional proprietary symptom-specific information (use case 3, see 7.3).

Table 37 defines the docking point for VM-specific extension.

Table 37 — Docking point for VM-specific extension

Reference to OBD summary table	None
Format	XML

9.7 FAULT-SYMPTOM-3RD-PARTYS

For a 3rd party fault symptom, the following elements are available:

— SHORT-NAME: Name of the fault symptom as used by the company providing the FXD document,

— THIRD-PARTY/COMPANY-DATA-REF: Reference to the company which originally provides the 3rd -party fault symptom functionality,

— THIRD-PARTY/FAULT-SYMPTOM-3RD-PARTY-SHORT-NAME: Name of the fault symptom as defined by the company which originally provides the 3rd party fault symptom functionality.

Table 38 defines the element FAULT-SYMPTOM-3RD-PARTY.

Table 38 — FAULT-SYMPTOM-3RD-PARTY

Reference to OBD summary table	None
Format	Text field with ASCII characters
—	Text description in XHTML for this function.

9.8 SERVICE-06-IDS

OBD service 06 "Request on-board monitoring test results for specific monitored systems" is specified in ISO 15031-5 or SAE J1979.

A list of all OBD service 06 identifiers, which are referenced by fault symptoms, is provided. The service 06 relevant information is described by the following sub-elements of a SERVICE-06-ID. Each test result is output by the OBD service 06 with an OBDMID (Monitor-ID), a TID (Test-ID) and a USID (Unit and Scaling ID).

— The OBDMID is used comprehensively for all vehicle manufacturers and indicates the component in question.

— Several TIDs can be assigned to each OBDMID. These TIDs correspond to the individual fault symptoms and each contains a test value (measurement label) and a lower and an upper test limit value (application label or application label with indexation).

— The USID is used to indicate the unit and the scaling of the value to be monitored.

— In case a special algorithm to access the data is needed (e.g. to provide an index in addition to the label) the method on how to retrieve the correct information has to be clarified between vehicle manufacturer and supplier.

Table 39 defines the output of test results via external test equipment service 06 (e.g.: 21 for Catalyst Monitoring).

Table 39 — SERVICE-06-IDS

Reference to OBD summary table	Yes
Format	Either the label name or the actual value.
Additional information	For the diagnostic cases relevant to OBD service 0616 stated below, the OBDMID shall be stated here. The OBDMID is to be entered in hexadecimal form (e.g. 1C16) standard values for spark-ignition engines: Misfire monitoring, Catalyst monitoring, Evaporative system monitoring, Secondary air system monitoring, Oxygen sensor monitoring, Oxygen sensor heater monitoring, EGR and/or VVT monitoring; standard values for diesel engines: Misfire monitoring, Fuel system monitoring, NMHC catalyst monitoring (oxidation catalyst), NOx after-treatment monitoring (NOx catalyst, NOx absorber), Boost pressure system monitoring, Exhaust gas sensor monitoring, PM filter monitoring, EGR and/or VVT system monitoring.

Table 40 defines the output of test results via OBD service 0616 (TID).

Table 40 — OBD service 0616 TIDs

Reference to OBD summary table	Yes
Format	Either the label name or the actual value.
—	The TID is to be entered in decimal form (e.g. 132)
—	Each OBDMID can have several TIDs.
Additional information	The element service 06 TID should be described specific to its monitor strategy, because it's possible that a symptom owns multiple monitor strategies.

Table 41 defines the output of test results via external test equipment service 0616 (Unit and Scaling ID)

Table 41 — OBD service 0616 USIDs

Reference to OBD summary table	None
Format	The USID is to be entered in hexadecimal form (e.g. 1C16)
—	For each TID, a USID has to be provided. There can be more TIDs per OBDMID.

9.9 FIDS

9.9.1 General

This subclause describes FXD-Schema elements specifying function-identifier-specific information.

9.9.2 Element-Id

Key of (fault-symptom-based) description: supplier-specific unique name of the function identifier described in accordance to 8.6.

NOTE The SHORT-NAME of the function identifier corresponds to the function identifier of the 'a2l' file.

9.9.3 FID-TYPE

It is distinguished between the three different types of a function identifier with the possible values:

— 'CALCULATION' or

— 'VALIDATION' or

— 'OTHER' for non fault symptom related purposes, e.g. limp home.

In case of a mixture 'CALCULATION' will be used.

9.9.4 ECU-FUNC

9.9.4.1 LONG-NAME

This is the supplier-specific name of the ECU function configuring the function identifier according to the specification of an HDO LONG-NAME.

EXAMPLE DSALSU

9.9.4.2 VERSION

This is the version of the ECU-FUNC as given in the 'a2l' element FUNCTION_VERSION for the function in which FID is configured.

9.9.5 FAULT-SYMPTOM-REFS

The fault symptoms which have an impact on the FIDs (i.e. act as an inhibit source) are referenced, if needed together with a specific MASK-REF. Table 42 defines the referencing element FAULT-SYMPTOM-REFS.

Table 42 — FAULT-SYMPTOM-REFS

Reference to OBD summary table	Disabling matrix
Format	List of fault symptoms as in the ‘a2l’ file.

9.9.6 AUXILIARY-OBJECT-REFS

Other elements (e.g. signal qualities) which have an impact on the FIDs (e.g. act as an inhibit source) are referenced, if needed together with a specific MASK. Table 43 defines the referencing element AUXILIARY-OBJECT-REFS.

Table 43 — AUXILIARY-OBJECT-REFS

Reference to OBD summary table	Disabling matrix
Format	List of signal qualities as in the ‘a2l’ file

9.9.7 EXPLANATION

Each FID is described in more detail (DESC), including substitute reactions. Additionally, a list of ECU elements (e.g. calibration parameters) relevant for this FID may be included (DATA-DECLARATION-REFS).

Table 44 defines the FID EXPLANATION.

Table 44 — EXPLANATION

Reference to OBD summary table	None
Format	Human readable description in XHTML format.
---	Validation and inhibition shall be explicitly distinguished.
---	Emergency running and substitute reaction shall be described, but not distinguished.

9.10 AUXILIARY-OBJECTS

Auxiliary objects are objects that can be used to disable the calculation of a function identifier (FID) in the same way as fault symptoms are used. Therefore, also their use within the configuration/definition of a function identifier is identical to the use of a fault symptom.

9.11 MASKS

Here, all those masks shall be listed that are referenced by the single sub-elements FAULT-SYMPTOM-REFS of each FID.

Masks are used to detail the (system) conditions under which a given fault symptom or auxiliary objects actually acts as inhibit source. A mask can thus contain e.g. detailed information on the defect level or debounce state.

9.12 TEXT-MAPPINGS

A text mapping provides the possibility to define a mapping of a text, e.g. an online variable to an alias name. This can be used by the vehicle manufacturers in order to replace texts which are defined in the FXD file by a vehicle-manufacturer-internal naming or naming required by the legislator. The 1-to-1 mapping is specified by an element TEXT-MAP and its child elements TI and its alias TEXT.

9.13 Any Other-Information (for container)

At the end of a fault symptom it is possible to add any XML content with a different namespace than the no-name-namespace. This may be useful if other information than offered by the FXD model shall be transported along with the FXD information.

Annex A
(normative)

Digital Annex of FXD XML-Schema

A.1 FXD XML-Schema document

A.1.1 General

The FXD XML-Schema are available as an electronic attachment with this document.

To be self-sufficient, the following paragraphs integrate those documents.

A.1.2 FXD-Schema V2.0.0 xml.xsd

```
      <?xml version='1.0'?>
      <xs:schema targetNamespace="http://www.w3.org/XML/1998/namespace" xmlns:xs="http://
www.w3.org/2001/XMLSchema" xml:lang="en">

       <xs:annotation>
        <xs:documentation>
         See http://www.w3.org/XML/1998/namespace.html and
         http://www.w3.org/TR/REC-xml for information about this namespace.

          This schema document describes the XML namespace, in a form
          suitable for import by other schema documents.

          Note that local names in this namespace are intended to be defined
          only by the World Wide Web Consortium or its subgroups.  The
          following names are currently defined in this namespace and should
          not be used with conflicting semantics by any Working Group,
          specification, or document instance:

          base (as an attribute name): denotes an attribute whose value
               provides a URI to be used as the base for interpreting any
               relative URIs in the scope of the element on which it
               appears; its value is inherited.  This name is reserved
               by virtue of its definition in the XML Base specification.

          lang (as an attribute name): denotes an attribute whose value
               is a language code for the natural language of the content of
               any element; its value is inherited.  This name is reserved
               by virtue of its definition in the XML specification.

          space (as an attribute name): denotes an attribute whose
               value is a keyword indicating what whitespace processing
               discipline is intended for the content of the element; its
               value is inherited.  This name is reserved by virtue of its
               definition in the XML specification.

          Father (in any context at all): denotes Jon Bosak, the chair of
               the original XML Working Group.  This name is reserved by
               the following decision of the W3C XML Plenary and
               XML Coordination groups:

                   In appreciation for his vision, leadership and dedication
                   the W3C XML Plenary on this 10th day of February, 2000
                   reserves for Jon Bosak in perpetuity the XML name
                   xml:Father
        </xs:documentation>
       </xs:annotation>
```

```
        <xs:annotation>
         <xs:documentation>This schema defines attributes and an attribute group
               suitable for use by
               schemas wishing to allow xml:base, xml:lang or xml:space attributes
               on elements they define.

               To enable this, such a schema must import this schema
               for the XML namespace, e.g. as follows:
               &lt;schema . . .>
                . . .
                &lt;import namespace="http://www.w3.org/XML/1998/namespace"
                           schemaLocation="http://www.w3.org/2001/03/xml.xsd"/>

               Subsequently, qualified reference to any of the attributes
               or the group defined below will have the desired effect, e.g.

               &lt;type . . .>
                . . .
                &lt;attributeGroup ref="xml:specialAttrs"/>

                will define a type which will schema-validate an instance
                element with any of those attributes</xs:documentation>
        </xs:annotation>

        <xs:annotation>
         <xs:documentation>In keeping with the XML Schema WG's standard versioning
          policy, this schema document will persist at
          http://www.w3.org/2001/03/xml.xsd.
          At the date of issue it can also be found at
          http://www.w3.org/2001/xml.xsd.
          The schema document at that URI may however change in the future,
          in order to remain compatible with the latest version of XML Schema
          itself.  In other words, if the XML Schema namespace changes, the version
          of this document at
          http://www.w3.org/2001/xml.xsd will change
          accordingly; the version at
          http://www.w3.org/2001/03/xml.xsd will not change.
         </xs:documentation>
        </xs:annotation>

        <xs:attribute name="lang" type="xs:language">
         <xs:annotation>
          <xs:documentation>In due course, we should install the relevant ISO 2- and
3-letter
               codes as the enumerated possible values . . .</xs:documentation>
         </xs:annotation>
        </xs:attribute>

        <xs:attribute name="space" default="preserve">
         <xs:simpleType>
          <xs:restriction base="xs:NCName">
           <xs:enumeration value="default"/>
           <xs:enumeration value="preserve"/>
          </xs:restriction>
         </xs:simpleType>
        </xs:attribute>
        <xs:attribute name="base" type="xs:anyURI">
         <xs:annotation>
          <xs:documentation>See http://www.w3.org/TR/xmlbase/ for
                            information about this attribute.</xs:documentation>
         </xs:annotation>
        </xs:attribute>
        <xs:attributeGroup name="specialAttrs">
         <xs:attribute ref="xml:base"/>
         <xs:attribute ref="xml:lang"/>
         <xs:attribute ref="xml:space"/>
        </xs:attributeGroup>
</xs:schema>
```

A.1.3 FXD-Schema V.2.0.0 fxd.xsd

```
	<?xml version="1.0" encoding="utf-8"?>
	<xs:schema xmlns:xs="http://www.w3.org/2001/XMLSchema"
elementFormDefault="qualified" attributeFormDefault="unqualified">
		<xs:import namespace="http://www.w3.org/XML/1998/namespace"
schemaLocation="xml.xsd"/>
		<xs:include schemaLocation="fxd-xhtml.xsd"/>
		<xs:complexType name="ABSTRACT-SYNTAX">
			<xs:sequence>
				<xs:group ref="EXPR"/>
			</xs:sequence>
		</xs:complexType>
		<xs:complexType name="ADDRESS">
			<xs:simpleContent>
				<xs:extension base="xs:string"/>
			</xs:simpleContent>
		</xs:complexType>
		<xs:complexType name="ADMIN-DATA">
			<xs:sequence>
				<xs:element name="COMPANY-DATA-REF" type="LINK"/>
				<xs:element name="ECU-FAMILY" type="ECU-FAMILY"/>
				<xs:element name="PROJECT" type="PROJECT"/>
				<xs:element name="RESOURCES" type="RESOURCES"/>
				<xs:element name="DOC-REVISIONS" type="DOC-REVISIONS"/>
			</xs:sequence>
		</xs:complexType>
		<xs:complexType name="ASSIGNABLE" abstract="true">
			<xs:sequence>
				<xs:element name="COMPUTATION-REF" type="LINK"/>
			</xs:sequence>
		</xs:complexType>
		<xs:complexType name="AUXILIARY-OBJECT">
			<xs:sequence>
				<xs:group ref="ELEMENT-ID"/>
			</xs:sequence>
			<xs:attributeGroup ref="ID-ATTRIBUTE"/>
		</xs:complexType>
		<xs:complexType name="AUXILIARY-OBJECT-REFS">
			<xs:sequence>
				<xs:element name="AUXILIARY-OBJECT-REF" type="MASKED-LINK"
maxOccurs="unbounded"/>
			</xs:sequence>
		</xs:complexType>
		<xs:complexType name="AUXILIARY-OBJECTS">
			<xs:sequence>
				<xs:element name="AUXILIARY-OBJECT" type="AUXILIARY-OBJECT"
minOccurs="0" maxOccurs="unbounded"/>
			</xs:sequence>
		</xs:complexType>
		<xs:complexType name="BIT-FIELD">
			<xs:sequence>
				<xs:element name="LONG-NAME" type="LONG-NAME"/>
				<xs:element name="BIT-MASK" type="xs:positiveInteger"/>
				<xs:element name="BIT-FIELD-COMPUTATION" type="BIT-FIELD-
COMPUTATION"/>
			</xs:sequence>
		</xs:complexType>
		<xs:complexType name="BIT-FIELD-COMPUTATION">
			<xs:complexContent>
				<xs:extension base="ASSIGNABLE"/>
			</xs:complexContent>
		</xs:complexType>
		<xs:complexType name="BIT-FIELD-VARIABLE">
			<xs:sequence>
				<xs:element name="BIT-FIELD" type="BIT-FIELD" minOccurs="1"
maxOccurs="unbounded"/>
			</xs:sequence>
		</xs:complexType>
		<xs:complexType name="BY-FUNCTION">
			<xs:sequence>
```

```
                        <xs:element name="EXCLUSIONS" type="EXCLUSIONS" minOccurs="0"/>
                  </xs:sequence>
            </xs:complexType>
            <xs:complexType name="BY-SYMPTOM">
                  <xs:sequence>
                        <xs:element name="FAULT-SYMPTOM-REFS" type="FAULT-SYMPTOM-REFS"
minOccurs="0"/>
                        <xs:element name="AUXILIARY-OBJECT-REFS" type="AUXILIARY-
OBJECT-REFS" minOccurs="0"/>
                        <xs:element name="FID-REFS" type="FID-REFS" minOccurs="0"/>
                  </xs:sequence>
            </xs:complexType>
            <xs:complexType name="CENTRAL-CALIBRATION-INFO">
                  <xs:complexContent>
                        <xs:extension base="ASSIGNABLE">
                              <xs:sequence>
                                    <xs:element name="INFO-TYPE" type="INFO-TYPE"/>
                              </xs:sequence>
                        </xs:extension>
                  </xs:complexContent>
            </xs:complexType>
            <xs:complexType name="CENTRAL-CALIBRATION-INFOS">
                  <xs:sequence>
                        <xs:element name="CENTRAL-CALIBRATION-INFO" type="CENTRAL-
CALIBRATION-INFO" maxOccurs="unbounded"/>
                  </xs:sequence>
            </xs:complexType>
            <xs:complexType name="CITY">
                  <xs:simpleContent>
                        <xs:extension base="xs:string"/>
                  </xs:simpleContent>
            </xs:complexType>
            <xs:complexType name="COMPANY-DATA">
                  <xs:sequence>
                        <xs:group ref="ELEMENT-ID"/>
                        <xs:element name="TEAM-MEMBERS" type="TEAM-MEMBERS"
minOccurs="0"/>
                  </xs:sequence>
                  <xs:attributeGroup ref="ID-ATTRIBUTE"/>
            </xs:complexType>
            <xs:complexType name="COMPANY-DATAS">
                  <xs:sequence>
                        <xs:element name="COMPANY-DATA" type="COMPANY-DATA"
maxOccurs="unbounded"/>
                  </xs:sequence>
            </xs:complexType>
            <xs:complexType name="COMPU-CONST">
                  <xs:complexContent>
                        <xs:extension base="OPERAND">
                              <xs:sequence>
                                    <xs:group ref="EVALUABLE-ENTITY"/>
                              </xs:sequence>
                        </xs:extension>
                  </xs:complexContent>
            </xs:complexType>
            <xs:element name="COMPU-CONST" type="COMPU-CONST"
substitutionGroup="OPERAND"/>
            <xs:complexType name="COMPU-VAR">
                  <xs:complexContent>
                        <xs:extension base="OPERAND">
                              <xs:sequence>
                                    <xs:element name="DATA-DECLARATION-REF"
type="LINK"/>
                              </xs:sequence>
                        </xs:extension>
                  </xs:complexContent>
            </xs:complexType>
            <xs:element name="COMPU-VAR" type="COMPU-VAR" substitutionGroup="OPERAND"/>
            <xs:complexType name="COMPUTATION">
                  <xs:sequence>
                        <xs:group ref="ELEMENT-ID"/>
```

```
                        <xs:choice>
                              <xs:element name="EXPLANATION" type="EXPLANATION"/>
                              <xs:element name="ABSTRACT-SYNTAX" type="ABSTRACT-
SYNTAX"/>
                        </xs:choice>
                  </xs:sequence>
                  <xs:attributeGroup ref="ID-ATTRIBUTE"/>
                  <xs:attribute ref="xml:lang"/>
            </xs:complexType>
            <xs:complexType name="COMPUTATIONS">
                  <xs:sequence>
                        <xs:element name="COMPUTATION" type="COMPUTATION" minOccurs="0"
maxOccurs="unbounded"/>
                  </xs:sequence>
            </xs:complexType>
            <xs:complexType name="CONFIGURATION">
                  <xs:sequence>
                        <xs:element name="DATA-DECLARATION-REFS" type="DATA-
DECLARATION-REFS"/>
                  </xs:sequence>
            </xs:complexType>
            <xs:complexType name="CUSTOM-CODE">
                  <xs:complexContent>
                        <xs:extension base="FAULT-CODE">
                              <xs:sequence>
                                    <xs:element name="CUSTOM-CODE-TYPE" type="CUSTOM-
CODE-TYPE"/>
                              </xs:sequence>
                        </xs:extension>
                  </xs:complexContent>
            </xs:complexType>
            <xs:simpleType name="CUSTOM-CODE-TYPE">
                  <xs:restriction base="xs:NMTOKEN"/>
            </xs:simpleType>
            <xs:complexType name="CUSTOM-CODES">
                  <xs:sequence>
                        <xs:element name="CUSTOM-CODE" type="CUSTOM-CODE"
maxOccurs="unbounded"/>
                  </xs:sequence>
            </xs:complexType>
            <xs:complexType name="DATA">
                  <xs:sequence>
                        <xs:element name="DATA-NAME" type="xs:string"/>
                        <xs:element name="DATA-TYPE" type="DATA-TYPE"/>
                        <xs:element name="DISPLAY-NAME" type="TEXT" minOccurs="0"/>
                        <xs:element name="DATA-VALUE" type="VALUE" minOccurs="0"/>
                  </xs:sequence>
            </xs:complexType>
            <xs:complexType name="DATA-DECLARATION">
                  <xs:sequence>
                        <xs:group ref="ELEMENT-ID"/>
                        <xs:element name="DATA" type="DATA"/>
                  </xs:sequence>
                  <xs:attributeGroup ref="ID-ATTRIBUTE"/>
            </xs:complexType>
            <xs:complexType name="DATA-DECLARATION-REFS">
                  <xs:sequence>
                        <xs:element name="DATA-DECLARATION-REF" type="LINK"
maxOccurs="unbounded"/>
                  </xs:sequence>
            </xs:complexType>
            <xs:complexType name="DATA-DECLARATIONS">
                  <xs:sequence>
                        <xs:element name="DATA-DECLARATION" type="DATA-DECLARATION"
minOccurs="0" maxOccurs="unbounded"/>
                  </xs:sequence>
            </xs:complexType>
            <xs:complexType name="DATA-DICTIONARY">
                  <xs:sequence>
                        <xs:element name="DATA-DECLARATIONS" type="DATA-DECLARATIONS"/>
                        <xs:element name="COMPUTATIONS" type="COMPUTATIONS"/>
```

```
                        <xs:element name="UNIT-SPEC" type="UNIT-SPEC"/>
                </xs:sequence>
        </xs:complexType>
        <xs:simpleType name="DATA-TYPE">
                <xs:restriction base="xs:NMTOKEN">
                        <xs:enumeration value="CALIBRATED"/>
                        <xs:enumeration value="CALIBRATION-INFO"/>
                        <xs:enumeration value="NON-CALIBRATABLE"/>
                        <xs:enumeration value="ONLINE"/>
                        <xs:enumeration value="STATE-VALUE"/>
                </xs:restriction>
        </xs:simpleType>
        <xs:complexType name="DEPARTMENT">
                <xs:simpleContent>
                        <xs:extension base="xs:string"/>
                </xs:simpleContent>
        </xs:complexType>
        <xs:simpleType name="DESC-EXTENT">
                <xs:restriction base="xs:NMTOKEN">
                        <xs:enumeration value="COMPLETE"/>
                        <xs:enumeration value="PARTIAL"/>
                </xs:restriction>
        </xs:simpleType>
        <xs:simpleType name="DESC-STATE">
                <xs:restriction base="xs:string">
                        <xs:enumeration value="INITIAL"/>
                        <xs:enumeration value="DRAFT"/>
                        <xs:enumeration value="RELEASED"/>
                </xs:restriction>
        </xs:simpleType>
        <xs:complexType name="DESCRIPTION">
                <xs:sequence>
                        <xs:group ref="block" minOccurs="0" maxOccurs="unbounded"/>
                        <xs:element name="EXTERNAL-DOCS" type="EXTERNAL-DOCS"
minOccurs="0"/>
                </xs:sequence>
                <xs:attributeGroup ref="TI-ATTRIBUTE"/>
        </xs:complexType>
        <xs:complexType name="DISABLE-FULLY">
                <xs:complexContent>
                        <xs:extension base="ASSIGNABLE"/>
                </xs:complexContent>
        </xs:complexType>
        <xs:complexType name="DISABLE-REPORT-ONLY">
                <xs:complexContent>
                        <xs:extension base="ASSIGNABLE"/>
                </xs:complexContent>
        </xs:complexType>
        <xs:complexType name="DOC-REVISION">
                <xs:sequence>
                        <xs:element name="REVISION-LABEL" type="xs:string"
minOccurs="0"/>
                        <xs:element name="STATE" type="DOCUMENT-STATE"/>
                        <xs:element name="DATE" type="xs:dateTime"/>
                </xs:sequence>
        </xs:complexType>
        <xs:complexType name="DOC-REVISIONS">
                <xs:sequence>
                        <xs:element name="DOC-REVISION" type="DOC-REVISION"
maxOccurs="unbounded"/>
                </xs:sequence>
        </xs:complexType>
        <xs:simpleType name="DOCUMENT-STATE">
                <xs:restriction base="xs:string">
                        <xs:enumeration value="DEVELOPMENT"/>
                        <xs:enumeration value="SERIES"/>
                        <xs:enumeration value="RELEASED"/>
                </xs:restriction>
        </xs:simpleType>
        <xs:complexType name="ECU-FAMILY">
                <xs:complexContent>
```

```
                        <xs:extension base="SELECTABLE"/>
                    </xs:complexContent>
                </xs:complexType>
                <xs:complexType name="ECU-FUNC">
                    <xs:sequence>
                        <xs:element name="LONG-NAME" type="LONG-NAME"/>
                        <xs:element name="VERSION" type="xs:string"/>
                    </xs:sequence>
                </xs:complexType>
                <xs:complexType name="ECU-FUNCS">
                    <xs:sequence>
                        <xs:element name="ECU-FUNC" type="ECU-FUNC"
maxOccurs="unbounded"/>
                    </xs:sequence>
                </xs:complexType>
                <xs:group name="ELEMENT-ID">
                    <xs:sequence>
                        <xs:element name="SHORT-NAME" type="SHORT-NAME"/>
                        <xs:element name="LONG-NAME" type="LONG-NAME" minOccurs="0"/>
                        <xs:element name="DESC" type="DESCRIPTION" minOccurs="0"/>
                    </xs:sequence>
                </xs:group>
                <xs:complexType name="EMAIL">
                    <xs:simpleContent>
                        <xs:extension base="xs:string"/>
                    </xs:simpleContent>
                </xs:complexType>
                <xs:complexType name="ENABLE-CONDITIONS">
                    <xs:complexContent>
                        <xs:extension base="ASSIGNABLE"/>
                    </xs:complexContent>
                </xs:complexType>
                <xs:complexType name="ERR-CLASS">
                    <xs:complexContent>
                        <xs:extension base="ASSIGNABLE"/>
                    </xs:complexContent>
                </xs:complexType>
                <xs:group name="EVALUABLE-ENTITY">
                    <xs:sequence>
                        <xs:choice>
                            <xs:element name="V" type="xs:double"/>
                            <xs:element name="VT" type="TEXT"/>
                            <xs:element name="VB" type="xs:boolean"/>
                        </xs:choice>
                        <xs:element name="UNIT-REF" type="LINK" minOccurs="0"/>
                    </xs:sequence>
                </xs:group>
                <xs:complexType name="EXCLUSION">
                    <xs:complexContent>
                        <xs:extension base="ASSIGNABLE"/>
                    </xs:complexContent>
                </xs:complexType>
                <xs:complexType name="EXCLUSIONS">
                    <xs:sequence>
                        <xs:element name="EXCLUSION" type="EXCLUSION"
maxOccurs="unbounded"/>
                    </xs:sequence>
                </xs:complexType>
                <xs:complexType name="EXPLANATION">
                    <xs:sequence>
                        <xs:element name="DESC" type="DESCRIPTION"/>
                        <xs:element name="DATA-DECLARATION-REFS" type="DATA-
DECLARATION-REFS" minOccurs="0"/>
                    </xs:sequence>
                </xs:complexType>
                <xs:group name="EXPR">
                    <xs:choice>
                        <xs:element ref="OPERAND"/>
                        <xs:element ref="OP"/>
                    </xs:choice>
                </xs:group>
```

```
            <xs:complexType name="EXTERNAL-DOC">
                  <xs:simpleContent>
                        <xs:extension base="xs:string">
                              <xs:attribute name="HREF" type="xs:anyURI"
use="required"/>
                        </xs:extension>
                  </xs:simpleContent>
            </xs:complexType>
            <xs:complexType name="EXTERNAL-DOCS">
                  <xs:sequence>
                        <xs:element name="EXTERNAL-DOC" type="EXTERNAL-DOC"
maxOccurs="unbounded"/>
                  </xs:sequence>
            </xs:complexType>
            <xs:complexType name="FAULT-CLASSIFICATION">
                  <xs:sequence>
                        <xs:choice>
                              <xs:element name="ERR-CLASS" type="ERR-CLASS"/>
                              <xs:element name="MIL-RELEVANCE" type="MIL-RELEVANCE"/>
                        </xs:choice>
                        <xs:element name="MIL-DEBOUNCE-GROUP" type="MIL-DEBOUNCE-GROUP"
minOccurs="0"/>
                  </xs:sequence>
            </xs:complexType>
            <xs:complexType name="FAULT-CODE">
                  <xs:complexContent>
                        <xs:extension base="ASSIGNABLE"/>
                  </xs:complexContent>
            </xs:complexType>
            <xs:complexType name="FAULT-DEBOUNCE">
                  <xs:complexContent>
                        <xs:extension base="ASSIGNABLE"/>
                  </xs:complexContent>
            </xs:complexType>
            <xs:complexType name="FAULT-DETECTION">
                  <xs:sequence>
                        <xs:group ref="ELEMENT-ID"/>
                        <xs:element name="GENERIC-TYPE" type="GENERIC-TYPE"
minOccurs="0"/>
                        <xs:element name="MON-STRATEGY" type="MON-STRATEGY"
minOccurs="0"/>
                        <xs:element name="FAULT-DETECTION-CRITERIA" type="FAULT-
DETECTION-CRITERIA" minOccurs="0"/>
                        <xs:element name="ENABLE-CONDITIONS" type="ENABLE-CONDITIONS"
nillable="true" minOccurs="0"/>
                        <xs:element name="FAULT-DEBOUNCE" type="FAULT-DEBOUNCE"
nillable="true" minOccurs="0"/>
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minOccurs="0"/>
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Automotive GmbH.
       All rights reserved, also regarding any disposal, exploitation, reproduction,
editing, distribution, as well as in the event of applications for industrial property
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                    <xs:sequence>
                        <xs:group ref="ELEMENT-ID"/>
                        <xs:element name="ROLES" type="ROLES" minOccurs="0"/>
```

```
                        <xs:element name="DEPARTMENT" type="DEPARTMENT" minOccurs="0"/>
                        <xs:element name="ADDRESS" type="ADDRESS" minOccurs="0"/>
                        <xs:element name="ZIP" type="ZIP" minOccurs="0"/>
                        <xs:element name="CITY" type="CITY" minOccurs="0"/>
                        <xs:element name="PHONE" type="PHONE" minOccurs="0"/>
                        <xs:element name="FAX" type="FAX" minOccurs="0"/>
                        <xs:element name="EMAIL" type="EMAIL" minOccurs="0"/>
                        <xs:element name="HOMEPAGE" type="HOMEPAGE" minOccurs="0"/>
                  </xs:sequence>
            </xs:complexType>
            <xs:complexType name="TEAM-MEMBERS">
                  <xs:sequence>
                        <xs:element name="TEAM-MEMBER" type="TEAM-MEMBER"
maxOccurs="unbounded"/>
                  </xs:sequence>
            </xs:complexType>
            <xs:complexType name="TEXT">
                  <xs:simpleContent>
                        <xs:extension base="xs:string">
                              <xs:attributeGroup ref="TI-ATTRIBUTE"/>
                        </xs:extension>
                  </xs:simpleContent>
            </xs:complexType>
            <xs:complexType name="TEXT-MAP">
                  <xs:sequence>
                        <xs:element name="TI" type="xs:string"/>
                        <xs:element name="TEXT" type="xs:string"/>
                  </xs:sequence>
            </xs:complexType>
            <xs:complexType name="TEXT-MAPPING">
                  <xs:sequence>
                        <xs:element name="COMPANY-DATA-REF" type="LINK"/>
                        <xs:element name="TEXT-MAPS" type="TEXT-MAPS"/>
                  </xs:sequence>
                  <xs:attributeGroup ref="SI-ATTRIBUTE"/>
                  <xs:attribute ref="xml:lang"/>
            </xs:complexType>
            <xs:complexType name="TEXT-MAPPINGS">
                  <xs:sequence>
                        <xs:element name="TEXT-MAPPING" type="TEXT-MAPPING"
minOccurs="0" maxOccurs="unbounded"/>
                  </xs:sequence>
            </xs:complexType>
            <xs:complexType name="TEXT-MAPS">
                  <xs:sequence>
                        <xs:element name="TEXT-MAP" type="TEXT-MAP" minOccurs="0"
maxOccurs="unbounded"/>
                  </xs:sequence>
            </xs:complexType>
            <xs:complexType name="THIRD-PARTY">
                  <xs:sequence>
                        <xs:element name="COMPANY-DATA-REF" type="LINK"/>
                        <xs:element name="FAULT-SYMPTOM-3RD-PARTY-SHORT-NAME"
type="SHORT-NAME"/>
                  </xs:sequence>
            </xs:complexType>
            <xs:attributeGroup name="TI-ATTRIBUTE">
                  <xs:attribute name="TI" type="xs:string" use="optional"/>
            </xs:attributeGroup>
            <xs:complexType name="TO-STATE">
                  <xs:sequence>
                        <xs:element name="DATA-DECLARATION-REF" type="LINK"/>
                  </xs:sequence>
            </xs:complexType>
            <xs:complexType name="UNIT">
                  <xs:sequence>
                        <xs:group ref="ELEMENT-ID"/>
                        <xs:element name="DISPLAY-NAME" type="TEXT"/>
                        <xs:element name="FACTOR-SI-TO-UNIT" type="xs:double"
minOccurs="0"/>
                        <xs:element name="OFFSET-SI-TO-UNIT" type="xs:double"
```

```
minOccurs="0"/>
                        <xs:element name="PHYSICAL-DIMENSION-REF" type="LINK"
minOccurs="0"/>
                </xs:sequence>
                <xs:attributeGroup ref="ID-ATTRIBUTE"/>
            </xs:complexType>
            <xs:complexType name="UNIT-GROUP">
                <xs:sequence>
                        <xs:group ref="ELEMENT-ID"/>
                        <xs:element name="CATEGORY" type="UNIT-GROUP-CATEGORY"/>
                        <xs:element name="UNIT-REFS" type="UNIT-REFS" minOccurs="0"/>
                </xs:sequence>
            </xs:complexType>
            <xs:simpleType name="UNIT-GROUP-CATEGORY">
                <xs:restriction base="xs:string">
                        <xs:enumeration value="COUNTRY"/>
                        <xs:enumeration value="EQUIV-UNITS"/>
                </xs:restriction>
            </xs:simpleType>
            <xs:complexType name="UNIT-GROUPS">
                <xs:sequence>
                        <xs:element name="UNIT-GROUP" type="UNIT-GROUP"
maxOccurs="unbounded"/>
                </xs:sequence>
            </xs:complexType>
            <xs:complexType name="UNIT-REFS">
                <xs:sequence>
                        <xs:element name="UNIT-REF" type="LINK" maxOccurs="unbounded"/>
                </xs:sequence>
            </xs:complexType>
            <xs:complexType name="UNIT-SPEC">
                <xs:sequence>
                        <xs:element name="UNIT-GROUPS" type="UNIT-GROUPS"
minOccurs="0"/>
                        <xs:element name="UNITS" type="UNITS" minOccurs="0"/>
                        <xs:element name="PHYSICAL-DIMENSIONS" type="PHYSICAL-
DIMENSIONS" minOccurs="0"/>
                </xs:sequence>
            </xs:complexType>
            <xs:complexType name="UNITS">
                <xs:sequence>
                        <xs:element name="UNIT" type="UNIT" maxOccurs="unbounded"/>
                </xs:sequence>
            </xs:complexType>
            <xs:complexType name="VALUE">
                <xs:sequence>
                        <xs:group ref="EVALUABLE-ENTITY"/>
                </xs:sequence>
            </xs:complexType>
            <xs:complexType name="VARIABLE-DESCRIPTION">
                <xs:sequence>
                        <xs:group ref="ELEMENT-ID"/>
                        <xs:element name="COMPANY-DATA-REF" type="LINK"/>
                        <xs:element name="ECU-FUNCS" type="ECU-FUNCS" minOccurs="0"/>
                        <xs:element name="CONFIGURATION" type="CONFIGURATION"
minOccurs="0"/>
                        <xs:element name="DATA-DECLARATION-REF" type="LINK"
minOccurs="0"/>
                        <xs:choice>
                                <xs:element name="SIMPLE-VARIABLE" type="SIMPLE-VARIABLE"
minOccurs="0"/>
                                <xs:element name="BIT-FIELD-VARIABLE" type="BIT-FIELD-
VARIABLE" minOccurs="0"/>
                                <xs:element name="STATE-GRAPH" type="STATE-GRAPH"
minOccurs="0"/>
                        </xs:choice>
                        <xs:element name="PARENT-REF" type="LINK" minOccurs="0"/>
                        <xs:any namespace="##other" processContents="lax"
minOccurs="0"/>
                </xs:sequence>
                <xs:attribute name="DESC-STATE" type="DESC-STATE" use="required"/>
```

```
                        <xs:attribute name="DESC-EXTENT" type="DESC-EXTENT" use="required"/>
                        <xs:attributeGroup ref="ID-ATTRIBUTE"/>
                        <xs:attributeGroup ref="SI-ATTRIBUTE"/>
                        <xs:attributeGroup ref="OID-ATTRIBUTE"/>
                        <xs:attribute ref="xml:lang"/>
                </xs:complexType>
                <xs:complexType name="VARIABLE-DESCRIPTION-BASE">
                        <xs:complexContent>
                                <xs:restriction base="VARIABLE-DESCRIPTION">
                                        <xs:sequence>
                                                <xs:group ref="ELEMENT-ID"/>
                                                <xs:element name="COMPANY-DATA-REF" type="LINK"/>
                                                <xs:element name="ECU-FUNCS" type="ECU-FUNCS"/>
                                                <xs:element name="CONFIGURATION"
type="CONFIGURATION" minOccurs="0"/>
                                                <xs:element name="DATA-DECLARATION-REF"
type="LINK"/>
                                                <xs:choice>
                                                        <xs:element name="SIMPLE-VARIABLE"
type="SIMPLE-VARIABLE"/>
                                                        <xs:element name="BIT-FIELD-VARIABLE"
type="BIT-FIELD-VARIABLE"/>
                                                        <xs:element name="STATE-GRAPH" type="STATE-
GRAPH"/>
                                                </xs:choice>
                                                <xs:any namespace="##other" processContents="lax"
minOccurs="0"/>
                                        </xs:sequence>
                                </xs:restriction>
                        </xs:complexContent>
                </xs:complexType>
                <xs:complexType name="VARIABLE-DESCRIPTIONS">
                        <xs:sequence>
                                <xs:element name="VARIABLE-DESCRIPTION" type="VARIABLE-
DESCRIPTION" minOccurs="0" maxOccurs="unbounded"/>
                        </xs:sequence>
                </xs:complexType>
                <xs:simpleType name="VERSION">
                        <xs:restriction base="xs:string">
                                <xs:enumeration value="2.0.0"/>
                        </xs:restriction>
                </xs:simpleType>
                <xs:complexType name="ZIP">
                        <xs:simpleContent>
                                <xs:extension base="xs:string"/>
                        </xs:simpleContent>
                </xs:complexType>
</xs:schema>
```

A.2 FXD XML-Schema elements mapping list

Table A.1 lists the FXD XML-Schema elements mapping to this document.

NOTE Referencing elements are not listed below (e.g. FAULT-SYMPTOM-REFS).

Table A.1 — FXD XML-Schema elements mapping list to this document

FXD XML-Schema element	Attributes	Clause	Reference to subclause in this document
			Title
ABSTRACT-SYNTAX		6.3.2.1 6.5.2 9.4.2	General Formal description of diagnosis algorithms COMPUTATIONS
ADMIN-DATA		9.2.1	General
AUXILIARY-OBJECT	ID	9.10	AUXILIARY-OBJECTS

Table A.1 *(continued)*

FXD XML-Schema element	Attributes	Clause	Reference to subclause in this document Title
AUXILIARY-OBJECTS		9.10	AUXILIARY-OBJECTS
BIT-FIELD		9.5.1	General
BIT-FIELD-COMPUTATION		9.5.8	BIT-FIELD-VARIABLE
BIT-FIELD-VARIABLE		9.5.1	General
		9.5.8	BIT-FIELD-VARIABLE
BIT-MASK		9.5.8	BIT-FIELD-VARIABLE
BY-FUNCTION		9.6.13.2	INHIBITIONS by function
BY-SYMPTOM		9.6.13.1	INHIBITIONS by symptom
CALIBRATION		9.2.5	RESOURCES
CENTRAL-CALIBRATION-INFO		9.6.12	CENTRAL-CALIBRATION-INFOS
CENTRAL-CALIBRATION-INFOS		9.6.12	CENTRAL-CALIBRATION-INFOS
COMPANY-DATA	ID	6.5.3	Implementation of value inheritance
		9.3.1	General COMPANY-DATA information
		9.3.2	COMPANY-DATA
COMPANY-DATAS		9.3	COMPANY-DATAS
COMPU-CONST		6.5.2	Formal description of diagnosis algorithms
COMPU-VAR		6.5.2	Formal description of diagnosis algorithms
COMPUTATION	xml:lang	6.5.2	Formal description of diagnosis algorithms
	ID	9.4.2	COMPUTATONS
		9.5.1	General
COMPUTATIONS		9.4.2	COMPUTATIONS
CONFIGURATION		9.6.5	CONFIGURATION
CUSTOM-CODE		9.6.6.2	CUSTOM-CODES
CUSTOM-CODES	xsi:nil	9.6.6.2	CUSTOM-CODES
DATA		9.4.1	DATA-DECLARATIONS
DATA-DECLARATION	ID	6.3.2.1	General
		8.5	Referencing ECU variables and calibration labels
		9.4.1	DATA-DECLARATIONS
		9.5.1	General
DATA-DECLARATIONS		9.4.1	DATA-DECLARATIONS
DATA-DESCRIPTION		9.2.5	RESOURCES
DATA-DICTIONARY		9.4	DATA-DICTIONARY
DATA-NAME		9.4.1	DATA-DECLARATIONS
		9.4.4	Values for declared data
DATA-TYPE		9.5.1	General
DATA-VALUE		9.6.5	Configuration of the FAULT-SYMPTOM
DATE		9.2.6	Document life cycle information

Table A.1 *(continued)*

FXD XML-Schema element	Attributes	Clause	Reference to subclause in this document Title
DESC	TI	6.5.2	Formal description of diagnosis algorithms
		8.4	External document references
		8.6	General FXD elements, used for identification and description
		9.9.7	Explanation of the FID
DISABLE-FULLY		9.6.11.14	DISABLE-FULLY
DISABLE-REPORT-ONLY		9.6.11.13	DISABLE-REPORT-ONLY
DISPLAY-NAME	TI	9.4.1 9.4.3	DATA-DECLARATIONS UNIT-SPEC
DOC-REVISION		9.2.6	DOC-REVISIONS
DOC-REVISIONS		9.2.6	DOC-REVISIONS
ECU-FAMILY		9.2.3	ECU-FAMILY
ECU-FUNC		9.5.4.1	Name of the ECU-FUNC
		9.5.4.2	Version of the ECU-FUNC
		9.5.4	Reference to the ECU-FUNC
ECU-FUNCS		9.5.4	Reference to the ECU-FUNC
ENABLE-CONDITIONS	xsi:nil	6.5.3 9.6.11.5	Value inheritance mechanism to support use cases ENABLE-CONDITIONS
ERR-CLASS		9.6.8.1	ERR-CLASS
EXCLUSION		9.6.13.2	INHIBITIONS by function
EXCLUSIONS		9.6.13.2	INHIBITIONS by function
EXPLANATION		6.3.2.1	General
		6.5.2	Formal description of diagnosis algorithms
		9.4.2	COMPUTATIONS
EXTERNAL-DOC	HREF	8.4	External document references
		9.2.5	RESOURCES
EXTERNAL-DOCS		8.4	External document references
		9.2.5	RESOURCES
FAULT-CLASSIFICATION		9.6.8	FAULT-CLASSIFICATION
FAULT-DEBOUNCE	xsi:nil	9.6.11.7	FAULT-DEBOUNCE
FAULT-DETECTION	xsi:type	9.6.11	FAULT-DETECTIONS
	ID	9.6.11.1	FAULT-DETECTION general information
FAULT-DETECTION-CRITERIA		6.5.3 9.6.11.4	Value inheritance machanism to support use cases FAULT-DETECTION-CRITERIA
FAULT-DETECTIONS	xsi:type	9.6.11	FAULT-DETECTIONS
FAULT-IDENTIFICATION		9.6.6	FAULT-IDENTIFICATION

Table A.1 *(continued)*

FXD XML-Schema element	Attributes	Clause	Reference to subclause in this document Title
FAULT-SYMPTOM	xsi:type	6.4	FXD format and example
	DESC-STATE	6.5.3	Implementation of value inheritance
	DESC-EXTENT	9.6	FAULT-SYMPTOMS
	xml:lang		
FAULT-SYMPTOM-3RD-PARTY	ID	9.7	FAULT-SYMPTOM-3RD-PARTY
FAULT-SYMPTOM-3RD-PARTY-SHORT-NAME		9.7	FAULT-SYMPTOM-3RD-PARTY
FAULT-SYMPTOM-3RD-PARTYS		9.7	FAULT-SYMPTOM-3RD-PARTY
FAULT-SYMPTOM-EXCH-DESC	VERSION		Root-Element
	xml:lang		
	xml:base		
FAULT-SYMPTOMS		9.5.1	General
		9.6	FAULT-SYMPTOMS
FAULT-TYPE		9.6.6.3	FAULT-TYPE
FID	ID	9.9	FIDS
FID-TYPE		9.9.3	Type of the FID
FIDS		9.9	FIDS
FROM-STATE		9.5.9	STATE-GRAPH
GENERIC-TYPE		8.3	Generic selection lists
		9.6.11.16	GENERIC-TYPE
INHIBITIONS		9.6.13	INHIBITIONS information
INITIAL-STATE		9.5.9	STATE-GRAPH
LEGAL-CODE	xsi:nil	9.6.6.1	Legal Code
LEGISLATION		9.6.11.12	Reference to OBD legislation
		9.6.11.12.2	LEGISLATION
LEGISLATIONS	xsi:nil	9.6.11.12.2	LEGISLATIONS
LONG-NAME		8.6	General FXD elements, used for identification and description
		9.5.4.1	LONG-NAME
		9.5.8	BIT-FIELD-VARIABLE
		9.6.4.1	LONG-NAME
		9.9.4.1	LONG-NAME
MASK	ID	9.11	MASKS
MASKS		9.11	MASKS
MCL-STRATEGY		8.3	Generic selection lists
		9.6.11.12	Reference to OBD legislation
		9.6.11.12.3	MCL-STRATEGY
MIL-DEBOUNCE-GROUP		9.6.8.3	MIL-DEBOUNCE-GROUP
MIL-RELEVANCE		9.6.8.2	MIL-RELEVANCE
MON-COMPONENT		8.3	Generic selection lists
		9.6.7	MON-COMPONENT or system

Table A.1 *(continued)*

FXD XML-Schema element	Attributes	Clause	Reference to subclause in this document Title
MON-FREQUENCY		8.3 9.6.11.8	Generic selection lists MON-FREQUENCY
MON-STRATEGY		9.6.11.3	MON-STRATEGY
NAME		9.2.4 9.2.5	PROJECT RESOURCES
OBDMID		9.8	SERVICE-06-IDS
OBDTID		9.8	SERVICE-06-IDS
OBDTIDS		9.8	SERVICE-06-IDS
OBDUSID		9.8	SERVICE-06-IDS
OK-DEBOUNCE	xsi:nil	9.6.11.11	OK-DEBOUNCE
OK-DETECTION-CRITERIA	xsi:nil	9.6.11.9	OK-DETECTION-CRITERIA
OK-ENABLE-CONDITIONS	xsi:nil	9.6.11.10	OK-ENABLE-CONDITIONS
OP	OPERATOR	6.5.2	Formal description of diagnosis algorithms
OPERAND		9.4.2	COMPUTATIONS
PHYSICAL-DIMENSION	ID	9.4.3	UNIT-SPEC
PHYSICAL-DIMENSIONS		9.4.1	Physical units
PROJECT		9.2.4	Project information
PROTECTIVE-FUNCTION		9.6.15	PROTECTIVE-FUNCTION
RATIO-GROUP		8.3 9.6.9	Generic selection lists RATIO-GROUPS
RATIO-GROUPS		9.6.9	RATIO-GROUPS
READINESS-GROUP		8.3 9.6.10	Generic selection lists READINESS-GROUP
REQUIRED-CONDITION		9.5.9	STATE-GRAPH
RECOURCES		8.4 9.2.5	External document references RESOURCES
REVISION-LABEL		9.2.6	Document life cycle information
SERVICE-06		9.8	SERVICE-06-IDS
SERVICE-06-ID	ID	9.8	SERVICE-06-IDS
SERVICE-06-IDS		9.8	SERVICE-06-IDS
SHORT-NAME		6.5.3 6.5.4 8.6	Value inheritance mechanism to support use cases Implementation of value inheritance General FXD elements, used for identification and description
SIMPLE-VARIABLE		9.5.1 9.5.7	General SIMPLE-VARIABLE
SIMULATION-METHOD		8.3 9.6.16	Generic selection lists SIMULATION-METHOD
STATE		9.2.6	Document life cycle information
STATE-COMPUTATION		9.5.13	STATE-GRAPH

Table A.1 *(continued)*

FXD XML-Schema element	Attributes	Clause	Reference to subclause in this document
			Title
STATE-GRAPH		9.5.1	General
		9.5.13	STATE-GRAPH
STATE-TRANSITION		9.5.1	General
STATE-TRANSITIONS		9.5.9	STATE-GRAPH
STATES		9.5.1	General
		9.5.9	STATE-GRAPH
SUBSTITUTION-FUNCTION		9.6.14	SUBSTITUTION-FUNCTION
SW-BASELINE		9.2.4	PROJECT
		9.2.5	RESOURCES
TEXT-MAP		9.12	TEXT-MAPPINGS
TEXT-MAPPING	xml:lang	9.12	TEXT-MAPPINGS
	SI		
TEXT-MAPPINGS		9.12	TEXT-MAPPINGS
TEXT-MAPS		9.12	TEXT-MAPPINGS
THIRD-PARTY		9.7	FAULT-SYMPTOM-3RD-PARTYS
TO-STATE		9.5.9	STATE-GRAPH
UNIT	ID	9.4.3	UNIT-SPEC
UNIT-GROUP		9.4.3	UNIT-SPEC
UNIT-GROUPS		9.4.3	UNIT-SPEC
UNIT-SPEC		9.4.3	UNIT-SPEC
UNITS		9.4.3	UNIT-SPEC
VARIABLE-DESCRIPTION	xsi:type	6.5.3	Implementation of value inheritance
	DESC-STATE	9.5	VARIABLE-DESCRIPTION
	DESC-EXTENT	9.5.3	COMPANY-DATA-REF
	xml:lang	9.5.5	CONFIGURATION
	ID		
	SI		
	OID		
VARIABLE-DESCRIPTIONS		9.5.1	General
VT	TI	6.5.2	Formal description of diagnosis algorithms

A.3 Operators for the ABSTRACT-SYNTAX

Operators for the ABSTRACT-SYNTAX are FXD computations that are primarily used for documentation purposes and not for evaluation; strict typing is not desired. Nevertheless, the computations or parts of them can be regarded as evaluable computations. In this case, a detailed definiton of the operators' arguments and return values is required. FXD defines three value types:

a) boolean:

— The value can only be either true or false.

— It is either a COMPU-CONST/VB or the result of a boolean operation.

b) numerical:

— The value shall be a number (integer or float, representing a physical value in most cases).

— It is either a COMPU-CONST/V or the result of a numerical operation.

c) string:

— The value can be arbitrary text content.

— COMPU-CONST/VT (strings) shall be assumed to represent a description of a value of the proper type.

Table A.2 defines the evaluable FXD operator types, i.e. the table defines how the operators behave or would behave if the arguments are of the specified type and if evaluation is desired. The note 'variable' means that the argument should actually be a variable and not a constant value.

Table A. 2 defines the FXD operator types.

Table A.2 — FXD operator types

Function/ Operator	Min/Max Arity	Explanation	result type	1st parameter type	2nd parameter type	3rd/ further parameter type
abs	1	Absolute value	**numerical**	numerical	---	---
add	2 / unbounded	Addition	**numerical**	numerical	numerical	numerical
and	2 / unbounded	Logical and	**boolean**	boolean	boolean	boolean
bin_and	2 / unbounded	Binary and (bit by bit)	**numerical**	numerical	numerical	numerical
bin_or	2 / unbounded	Binary or (bit by bit)	**numerical**	numerical	numerical	numerical
bin_xor	2	Binary xor (exclusive or bit by bit)	**numerical**	numerical	numerical	---
ceil	1	Round to next integer greater or equal to the value	**numerical**	numerical	---	---
delay[a]	2	A value is delayed by a certain time. The first argument is the condition and the second argument is the delay time. delay(n>n_min and n<n_max, 10*ms) expresses the situation that the condition has been fulfilled for at least 10ms.	**boolean**	**boolean**	numerical	---
delta	1	Difference between the current and the previously calculated value of a variable, e.g.: delta(temp) This is equivalent to temp – previous(temp)	**numerical**	numerical	---	---

a The type of the 1st parameter determines the result type

b This implies that a boolean value and a numerical value are always not equal.

c The operator for_time is deprecated: duration_of shall be used instead.

d For readability a comparison with a boolean value shall be forced.

e The (identical) types of the 2nd and 3rd parameter determine the result type.

f A comparison of boolean with numerical is not permitted only.

g The result shall be accepted.

h The type of the 2nd parameter determines the result type.

i The type of the 1st parameter determines the result type.

Table A.2 *(continued)*

Function/ Operator	Min/Max Arity	Explanation	result type	1st parameter type	2nd parameter type	3rd/ further parameter type
div	2	Division	**numerical**	numerical	numerical	---
duration_of	1	Determines the time the condition described by the 1st parameter is continuously true.	**numerical**	boolean	---	---
edge_alternating	1	edge_alternating(X): = edge_rising(X) or edge_falling(X). If a rising or falling edge of X occurs, the output will be true for one sampling period.	**boolean**	boolean	---	---
edge _falling	1	edge_falling(X): = if(previous(X)!=0 and X==0, true, false). If a falling edge of X occurs, the output will be true for one sampling period.	boolean	boolean	---	---
edge_rising	1	edge_rising(X): = if(previous(X)=0 and X!=0, true, false). If a rising edge of X occurs, the output will be true for one sampling period.	**boolean**	boolean	---	---
eq[b]	2	Equal. Two values can only be equal if they are of the same type.	**boolean**	**any**	**any**	**---**
floor	1	Round down next integer less or equal to the value	**numerical**	numerical	---	---
ge	2	Greater than or equal	**boolean**	numerical	numerical	---
getbit	2	Determines the value of the n-th bit in the expression described by the 1st parameter. The bit position is defined by the 2nd parameter (starting at 0)	**boolean**	numerical	numerical	---
gradient	2	Quotient of the difference between the current and the previously calculated value of a variable and the respective time or angle difference the calculations took place, e.g.: gradient(temp,1s) This is equivalent to delta(temp)/1s And to (temp – previous(temp))/1s	**numerical**	numerical	numerical	---

a The type of the 1st parameter determines the result type

b This implies that a boolean value and a numerical value are always not equal.

c The operator for_time is deprecated: duration_of shall be used instead.

d For readability a comparison with a boolean value shall be forced.

e The (identical) types of the 2nd and 3rd parameter determine the result type.

f A comparison of boolean with numerical is not permitted only.

g The result shall be accepted.

h The type of the 2nd parameter determines the result type.

i The type of the 1st parameter determines the result type.

Table A.2 *(continued)*

Function/ Operator	Min/Max Arity	Explanation	result type	1st parameter type	2nd parameter type	3rd/ further parameter type
gt	2	Greater than	**boolean**	numerical	numerical	

ife	3	Conditional expression, considered as a function with three (C, T, E) arguments, where
		C is the condition
		T is the result if C is true
		E is the result if C is false
		Simple example distinguishing between two values depending on a bit:
		if(B_manualtransmission, 6,4)
		Example for nested ifs:
		if(B_manualtransmission, if(B_4wheel,8,6),4)
			any	boolean	**any**	**any**

le	2	Lower than or equal	**boolean**	numerical	numerical	
lt	2	Lower than	**boolean**	numerical	numerical	
max	2 / unbounded	Maximum of different values	**numerical**	numerical	numerical	numerical
min	2 / unbounded	Minimum of different values	**numerical**	numerical	numerical	numerical
max_value	1 or 1+2*n (n denotes the dimension of the label)	Evaluates the maximum value of the field. The first operand is the name of the label. If no further operands are specified, the overall maximum is evaluated. If there are n pairs of additional operands, each pair specifies a range for the one axis by specifying the first and last index to be taken into account for the maximum computation.	**numerical**	**variable**	numerical	numerical

a The type of the 1st parameter determines the result type

b This implies that a boolean value and a numerical value are always not equal.

c The operator for_time is deprecated: duration_of shall be used instead.

d For readability a comparison with a boolean value shall be forced.

e The (identical) types of the 2nd and 3rd parameter determine the result type.

f A comparison of boolean with numerical is not permitted only.

g The result shall be accepted.

h The type of the 2nd parameter determines the result type.

i The type of the 1st parameter determines the result type.

Table A.2 *(continued)*

Function/ Operator	Min/Max Arity	Explanation	result type	1st parameter type	2nd parameter type	3rd/ further parameter type
min_value	1 or 1+2*n (n denotes the dimension of the label)	Evaluates the minimum value of the field. The first operand is the name of the label. If no further operands are specified, the overall minimum is evaluated. If there are n pairs of additional operands each pair specifies a range for the one axis by specifying the first and last index to be taken into account for the minimum computation.	**numerical**	**variable**	numerical	numerical
mul	2 / unbounded	Multiplication	**numerical**	numerical	numerical	numerical
neq[f]	2	Not equal. If two values are of different type they are always not equal.	**boolean**	**any**	**any**	
nop	0 / unbounded	No operation	**any**	any		
not	1	Logical not	**boolean**	boolean	---	---
note[h]	2	The purpose of the Note Operator is to provide a simple possibility to explain subsequent conditions by a short verbal expression. Accordingly, the first argument is a text string, the second argument is a computation, formulated in abstract syntax (see 8.4.2)	**any**	**string**	**any**	---
or	2 / unbounded	Logical or	**boolean**	boolean	boolean	boolean
pow	2	Power of a number, exponential function, pow(a,b) = a^b	**numerical**	numerical	numerical	---
previous[i]	1	Access to the previously calculated value of a variable, e.g.: - previous(B_state) - previous(temp)	**numerical**	**variable**	---	---
shift_left	2	Shift left (fill with 0)	**numerical**	numerical	numerical	---
shift_right	2	Shift right (fill with 0)	**numerical**	numerical	numerical	---
sqrt	1	Sqare root of a number, √x	**numerical**	numerical	---	---
sub	2	Subtraction	**numerical**	numerical	numerical	---

[a] The type of the 1st parameter determines the result type

[b] This implies that a boolean value and a numerical value are always not equal.

[c] The operator for_time is deprecated: duration_of shall be used instead.

[d] For readability a comparison with a boolean value shall be forced.

[e] The (identical) types of the 2nd and 3rd parameter determine the result type.

[f] A comparison of boolean with numerical is not permitted only.

[g] The result shall be accepted.

[h] The type of the 2nd parameter determines the result type.

[i] The type of the 1st parameter determines the result type.

Table A.2 *(continued)*

Function/ Operator	Min/Max Arity	Explanation	result type	1st parameter type	2nd parameter type	3rd/ further parameter type
value	1+n (n denotes the dimension of the label)	The value operator evaluates the value of a field by specifying the field name as first parameter and an "axis value" for each dimension of the field as following parameters.The field can be of any form/dimension, e.g. a curve, a map, an index table. The field is defined by an arbitrary number of supporting points for each dimension. The result depends on the evaluation strategy for the field. The most common evaluation strategies are : Access to a field element via index, the supporting points represent the index values, e.g. value (KnockLevel, CylNo) Access to a field element by selecting the nearest lower supporting point without interpolation Access to a field element by calculating the result via (linear) interpolation	**numerical**	**variable**	numerical	numerical
within	2 / 3	Within(A,B): defines a range Within(X,A,B) True if a value X is in the range A...B, otherwise false	**boolean**	numerical	numerical	numerical
xor	2	Exclusive disjunction, also called exclusive or	**boolean**	boolean	boolean	Boolean

a The type of the 1st parameter determines the result type

b This implies that a boolean value and a numerical value are always not equal.

c The operator for_time is deprecated: duration_of shall be used instead.

d For readability a comparison with a boolean value shall be forced.

e The (identical) types of the 2nd and 3rd parameter determine the result type.

f A comparison of boolean with numerical is not permitted only.

g The result shall be accepted.

h The type of the 2nd parameter determines the result type.

i The type of the 1st parameter determines the result type.

Annex B
(normative)

Digital Annex of FXD Selection Dictionary

B.1 FXD Selection Dictionary documents

B.1.1 General

The FXD XML-Schema are available as an electronic attachment with this document.

To be self-sufficient, the following paragraphs integrate those documents.

B.1.2 FXD-Selection-Dictionary V1.1.0.xsd

```
<?xml version="1.0" encoding="UTF-8"?>
<xs:schema xmlns:xs="http://www.w3.org/2001/XMLSchema" xmlns:xml="http://
www.w3.org/XML/1998/namespace" elementFormDefault="qualified"
attributeFormDefault="unqualified">
	<xs:import namespace="http://www.w3.org/XML/1998/namespace" schemaLocation="xml.
xsd"/>
	<xs:complexType name="ADMIN-DATA">
		<xs:sequence>
			<xs:element name="DOC-REVISIONS" type="DOC-REVISIONS"/>
		</xs:sequence>
	</xs:complexType>
	<xs:complexType name="DOC-REVISION">
		<xs:sequence>
			<xs:element name="REVISION-LABEL" type="xs:string" minOccurs="0"/>
			<xs:element name="STATE" type="STATE"/>
			<xs:element name="DATE" type="xs:dateTime"/>
			<xs:element name="MODIFICATIONS" type="MODIFICATIONS" minOccurs="0"/>
		</xs:sequence>
	</xs:complexType>
	<xs:complexType name="DOC-REVISIONS">
		<xs:sequence>
			<xs:element name="DOC-REVISION" type="DOC-REVISION"
maxOccurs="unbounded"/>
		</xs:sequence>
	</xs:complexType>
	<xs:complexType name="EXTERNAL-DOC">
		<xs:simpleContent>
			<xs:extension base="xs:string">
				<xs:attribute name="HREF" type="xs:anyURI" use="required"/>
			</xs:extension>
		</xs:simpleContent>
	</xs:complexType>
	<xs:complexType name="EXTERNAL-DOCS">
		<xs:sequence>
			<xs:element name="EXTERNAL-DOC" type="EXTERNAL-DOC"
maxOccurs="unbounded"/>
		</xs:sequence>
	</xs:complexType>
	<xs:attributeGroup name="ID-ATTRIBUTE">
		<xs:attribute name="ID" type="xs:ID" use="required"/>
	</xs:attributeGroup>
	<xs:simpleType name="STATE">
		<xs:restriction base="xs:string">
			<xs:enumeration value="DRAFT"/>
			<xs:enumeration value="RELEASED"/>
			<xs:enumeration value="DEPRECATED"/>
		</xs:restriction>
```

```
	</xs:simpleType>
	<xs:complexType name="LINK">
		<xs:annotation>
			<xs:documentation>Generic reference to another element in the schema
instance document.</xs:documentation>
		</xs:annotation>
		<xs:attributeGroup ref="LINK-ATTR"/>
	</xs:complexType>
	<xs:attributeGroup name="LINK-ATTR">
		<xs:attribute name="ID-REF" type="xs:IDREF" use="required"/>
	</xs:attributeGroup>
	<xs:complexType name="MODIFICATION" abstract="false">
		<xs:sequence>
			<xs:element name="CHANGE" type="xs:string"/>
			<xs:element name="REASON" type="xs:string" minOccurs="0"/>
		</xs:sequence>
	</xs:complexType>
	<xs:complexType name="MODIFICATIONS">
		<xs:sequence>
			<xs:element name="MODIFICATION" type="MODIFICATION"
maxOccurs="unbounded"/>
		</xs:sequence>
	</xs:complexType>
	<xs:complexType name="SELECTION">
		<xs:sequence>
			<xs:element name="SHORT-NAME" type="SHORT-NAME"/>
			<xs:element name="VT" type="xs:string"/>
			<xs:element name="DESC" type="xs:string" minOccurs="0"/>
			<xs:element name="STATE" type="STATE"/>
		</xs:sequence>
	</xs:complexType>
	<xs:element name="SELECTION-DICTIONARY" type="SELECTION-DICTIONARY"/>
	<xs:complexType name="SELECTION-DICTIONARY">
		<xs:sequence>
			<xs:element name="SELECTION-LISTS" type="SELECTION-LISTS"/>
		</xs:sequence>
		<xs:attribute name="VERSION" type="VERSION" use="required"/>
	</xs:complexType>
	<xs:complexType name="SELECTION-GROUP">
		<xs:sequence>
			<xs:element name="SHORT-NAME" type="SHORT-NAME"/>
			<xs:element name="VT" type="xs:string"/>
			<xs:element name="DESC" type="xs:string" minOccurs="0"/>
			<xs:element name="SELECTION-SNREFS" type="SELECTION-SNREFS"
minOccurs="0"/>
			<xs:element name="SELECTION-GROUPS" type="SELECTION-GROUPS"
minOccurs="0"/>
		</xs:sequence>
	</xs:complexType>
	<xs:complexType name="SELECTION-GROUPS">
		<xs:sequence>
			<xs:element name="SELECTION-GROUP" type="SELECTION-GROUP"
minOccurs="0" maxOccurs="unbounded"/>
		</xs:sequence>
	</xs:complexType>
	<xs:complexType name="SELECTION-LIST">
		<xs:sequence>
			<xs:element name="SHORT-NAME" type="SHORT-NAME"/>
			<xs:element name="ADMIN-DATA" type="ADMIN-DATA"/>
			<xs:element name="SELECTIONS" type="SELECTIONS"/>
			<xs:element name="SELECTION-GROUPS" type="SELECTION-GROUPS"/>
		</xs:sequence>
	</xs:complexType>
	<xs:complexType name="SELECTION-LISTS">
		<xs:sequence>
			<xs:element name="SELECTION-LIST" type="SELECTION-LIST"
maxOccurs="unbounded">
				<xs:annotation>
					<xs:documentation>The list of selectable values.</
xs:documentation>
				</xs:annotation>
```

```
                </xs:element>
            </xs:sequence>
        </xs:complexType>
        <xs:complexType name="SELECTION-SNREFS">
            <xs:sequence>
                <xs:element name="SELECTION-SNREF" type="SNREF"
maxOccurs="unbounded"/>
            </xs:sequence>
        </xs:complexType>
        <xs:complexType name="SELECTIONS">
            <xs:sequence>
                <xs:element name="SELECTION" type="SELECTION" minOccurs="0"
maxOccurs="unbounded"/>
            </xs:sequence>
        </xs:complexType>
        <xs:complexType name="SHORT-NAME">
            <xs:simpleContent>
                <xs:extension base="SHORT-NAME-TEXT"/>
            </xs:simpleContent>
        </xs:complexType>
        <xs:simpleType name="SHORT-NAME-TEXT">
            <xs:restriction base="xs:string">
                <xs:pattern value="[a-zA-Z0-9_]{1,128}"/>
            </xs:restriction>
        </xs:simpleType>
        <xs:complexType name="SNREF">
            <xs:attribute name="SHORT-NAME" type="SHORT-NAME-TEXT" use="required"/>
        </xs:complexType>
        <xs:simpleType name="VERSION">
            <xs:restriction base="xs:string">
                <xs:enumeration value="1.1.0"/>
            </xs:restriction>
        </xs:simpleType>
</xs:schema>
```

B.1.3 FXD-Selection-Dictionary V1.2.0.xml

```
<?xml version="1.0" encoding="utf-8"?>
<SELECTION-DICTIONARY xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance" xsi:noNamespac
eSchemaLocation="FXD-Selection-Dictionary_V1.1.0.xsd" VERSION="1.2.0">
  <SELECTION-LISTS>
    <SELECTION-LIST>
      <SHORT-NAME>MON_COMPONENT</SHORT-NAME>
      <ADMIN-DATA>
        <DOC-REVISIONS>
          <DOC-REVISION>
            <REVISION-LABEL>1.1.0</REVISION-LABEL>
            <STATE>RELEASED</STATE>
            <DATE>2016-05-13T10:39:56+02:00</DATE>
            <MODIFICATIONS>
              <MODIFICATION>
                <CHANGE>First version
-&gt;ISO MainDocument 8.6.7</CHANGE>
              </MODIFICATION>
            </MODIFICATIONS>
          </DOC-REVISION>
          <DOC-REVISION>
            <REVISION-LABEL>1.2.0</REVISION-LABEL>
            <STATE>RELEASED</STATE>
            <DATE>2016-11-11T14:18:37+01:00</DATE>
            <MODIFICATIONS>
              <MODIFICATION>
                <CHANGE>new Elements added</CHANGE>
              </MODIFICATION>
            </MODIFICATIONS>
          </DOC-REVISION>
        </DOC-REVISIONS>
      </ADMIN-DATA>
      <SELECTIONS>
        <SELECTION>
          <SHORT-NAME>FXD_SL_MC_0000</SHORT-NAME>
```

```
    <VT>OTHER</VT>
    <STATE>RELEASED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0001</SHORT-NAME>
    <VT>Accelerator Pedal Position (APP) Sensor</VT>
    <STATE>DEPRECATED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0281</SHORT-NAME>
    <VT>Accelerator Pedal Position (APP) Sensor 1</VT>
    <STATE>RELEASED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0002</SHORT-NAME>
    <VT>Accelerator Pedal Position (APP) Sensor 1 and 2</VT>
    <STATE>RELEASED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0003</SHORT-NAME>
    <VT>Accelerator Pedal Position (APP) Sensor 2</VT>
    <STATE>RELEASED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0282</SHORT-NAME>
    <VT>Active Grille Air Shutter</VT>
    <STATE>RELEASED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0283</SHORT-NAME>
    <VT>Active Lambda Diagnosis</VT>
    <STATE>RELEASED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0284</SHORT-NAME>
    <VT>Air Conditioning (A/C) Compressor Control</VT>
    <STATE>RELEASED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0285</SHORT-NAME>
    <VT>Air Conditioning (A/C) Compressor Relay</VT>
    <STATE>RELEASED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0286</SHORT-NAME>
    <VT>Air Conditioning (A/C) Compressor Sensor</VT>
    <STATE>RELEASED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0004</SHORT-NAME>
    <VT>Airbag</VT>
    <STATE>DEPRECATED</STATE>
  </SELECTION>
  <SELECTION>
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    <VT>Airbag Control Modul</VT>
    <STATE>RELEASED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0005</SHORT-NAME>
    <VT>Ambient Air Temperature (AAT) Sensor</VT>
    <STATE>RELEASED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0288</SHORT-NAME>
    <VT>Autoignition</VT>
    <STATE>RELEASED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0006</SHORT-NAME>
    <VT>Barometric Pressure (BARO) Sensor</VT>
```

```
    <STATE>RELEASED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0007</SHORT-NAME>
    <VT>Battery Energy Control Module (BECM)</VT>
    <STATE>RELEASED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0008</SHORT-NAME>
    <VT>Battery Module</VT>
    <STATE>RELEASED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0289</SHORT-NAME>
    <VT>Battery Voltage</VT>
    <STATE>RELEASED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0009</SHORT-NAME>
    <VT>Boost Pressure</VT>
    <STATE>DEPRECATED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0010</SHORT-NAME>
    <VT>Boost Pressure Control</VT>
    <STATE>DEPRECATED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0011</SHORT-NAME>
    <VT>Brake Booster Pressure Sensor</VT>
    <STATE>RELEASED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0012</SHORT-NAME>
    <VT>Brake Light Switch</VT>
    <STATE>RELEASED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0013</SHORT-NAME>
    <VT>Brake Pedal Position (BPP) Sensor</VT>
    <STATE>RELEASED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0014</SHORT-NAME>
    <VT>Brake Vacuum Pump</VT>
    <STATE>RELEASED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0015</SHORT-NAME>
    <VT>Camshaft Position (CMP) Sensor</VT>
    <STATE>RELEASED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0016</SHORT-NAME>
    <VT>Camshaft Position (CMP) Sensor 2</VT>
    <STATE>RELEASED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0017</SHORT-NAME>
    <VT>Camshaft Position (CMP) Sensor 3</VT>
    <STATE>RELEASED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0018</SHORT-NAME>
    <VT>Camshaft Position (CMP) Sensor 4</VT>
    <STATE>RELEASED</STATE>
  </SELECTION>
  <SELECTION>
    <SHORT-NAME>FXD_SL_MC_0019</SHORT-NAME>
    <VT>Camshaft Position (CMP) Sensor Inlet</VT>
    <STATE>DEPRECATED</STATE>
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</SELECTION>
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0021</SHORT-NAME>
  <VT>Camshaft Position (CMP) Sensor Inlet 2 </VT>
  <STATE>DEPRECATED</STATE>
</SELECTION>
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0020</SHORT-NAME>
  <VT>Camshaft Position (CMP) Sensor Outlet</VT>
  <STATE>DEPRECATED</STATE>
</SELECTION>
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0022</SHORT-NAME>
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</SELECTION>
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0023</SHORT-NAME>
  <VT>Camshaft Position / Crankshaft Position (CMP/CKP) Sensor Inlet</VT>
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</SELECTION>
<SELECTION>
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  <VT>Camshaft Position / Crankshaft Position (CMP/CKP) Sensor Outlet</VT>
  <STATE>DEPRECATED</STATE>
</SELECTION>
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0290</SHORT-NAME>
  <VT>CAN: Brake System Control Module (BSCM)</VT>
  <STATE>RELEASED</STATE>
</SELECTION>
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0291</SHORT-NAME>
  <VT>CAN: Hybrid</VT>
  <STATE>RELEASED</STATE>
</SELECTION>
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0025</SHORT-NAME>
  <VT>CAN: Instrument Panel Cluster (IPC)</VT>
  <STATE>RELEASED</STATE>
</SELECTION>
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0292</SHORT-NAME>
  <VT>CAN: Master Slave</VT>
  <STATE>RELEASED</STATE>
</SELECTION>
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0026</SHORT-NAME>
  <VT>CAN: Powertrain</VT>
  <STATE>RELEASED</STATE>
</SELECTION>
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0293</SHORT-NAME>
  <VT>Catalyst System</VT>
  <STATE>RELEASED</STATE>
</SELECTION>
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0027</SHORT-NAME>
  <VT>Charge Air Cooler (CAC)</VT>
  <STATE>RELEASED</STATE>
</SELECTION>
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0294</SHORT-NAME>
  <VT>Charge Air Cooler (CAC) Coolant Pump</VT>
  <STATE>RELEASED</STATE>
</SELECTION>
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0295</SHORT-NAME>
  <VT>Charge Air Cooler (CAC) Coolant Temperature Sensor</VT>
  <STATE>RELEASED</STATE>
</SELECTION>
```

```
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0028</SHORT-NAME>
  <VT>Charge Air Cooler Temperature (CACT) Sensor</VT>
  <STATE>DEPRECATED</STATE>
</SELECTION>
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0029</SHORT-NAME>
  <VT>Charge Air Cooler Temperature (CACT) Sensor 2</VT>
  <STATE>DEPRECATED</STATE>
</SELECTION>
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0296</SHORT-NAME>
  <VT>Cold Start Detection</VT>
  <STATE>RELEASED</STATE>
</SELECTION>
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0445</SHORT-NAME>
  <VT>Cold Start Fuel Injector</VT>
  <STATE>RELEASED</STATE>
</SELECTION>
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0030</SHORT-NAME>
  <VT>Cold Start Strategy</VT>
  <STATE>RELEASED</STATE>
</SELECTION>
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0297</SHORT-NAME>
  <VT>COM: Active Grille Air Shutter</VT>
  <STATE>RELEASED</STATE>
</SELECTION>
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0298</SHORT-NAME>
  <VT>COM: Active Grille Air Shutter 2</VT>
  <STATE>RELEASED</STATE>
</SELECTION>
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0299</SHORT-NAME>
  <VT>COM: Airbag Control Modul</VT>
  <STATE>RELEASED</STATE>
</SELECTION>
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0300</SHORT-NAME>
  <VT>COM: All Wheel Drive Control Module (AWDCM)</VT>
  <STATE>RELEASED</STATE>
</SELECTION>
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0031</SHORT-NAME>
  <VT>COM: Ambient Air Temperature (AAT) Sensor</VT>
  <STATE>RELEASED</STATE>
</SELECTION>
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0301</SHORT-NAME>
  <VT>COM: Barometric Pressure (BARO) Sensor</VT>
  <STATE>RELEASED</STATE>
</SELECTION>
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0302</SHORT-NAME>
  <VT>COM: Battery Charger Control Module (BCCM)</VT>
  <STATE>RELEASED</STATE>
</SELECTION>
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0032</SHORT-NAME>
  <VT>COM: Battery Energy Control Module (BECM)</VT>
  <STATE>RELEASED</STATE>
</SELECTION>
<SELECTION>
  <SHORT-NAME>FXD_SL_MC_0033</SHORT-NAME>
  <VT>COM: Body Control Module (BCM)</VT>
  <STATE>RELEASED</STATE>
</SELECTION>
<SELECTION>
```

```
      <SHORT-NAME>FXD_SL_MC_0303</SHORT-NAME>
      <VT>COM: Body Control Module (BCM) 1</VT>
      <STATE>RELEASED</STATE>
    </SELECTION>
    <SELECTION>
      <SHORT-NAME>FXD_SL_MC_0304</SHORT-NAME>
      <VT>COM: Body Control Module (BCM) 2</VT>
      <STATE>RELEASED</STATE>
    </SELECTION>
    <SELECTION>
      <SHORT-NAME>FXD_SL_MC_0034</SHORT-NAME>
      <VT>COM: Brake Booster Pressure Sensor</VT>
      <STATE>RELEASED</STATE>
    </SELECTION>
    <SELECTION>
      <SHORT-NAME>FXD_SL_MC_0035</SHORT-NAME>
      <VT>COM: Brake Pressure Sensor</VT>
      <STATE>RELEASED</STATE>
    </SELECTION>
    <SELECTION>
      <SHORT-NAME>FXD_SL_MC_0036</SHORT-NAME>
      <VT>COM: Brake System Control Module (BSCM)</VT>
      <STATE>RELEASED</STATE>
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B.2 Selection Dictionary and Selection Lists

The purpose of the Selection Dictionary is the transportation of specification text (wording) from vehicle manufacturers to the ECU supplier.

The individual Selection Lists are summarized in a Selection Dictionary.

Status:

— The Selection Dictionary shall only be published in RELEASED state by ISO. Earlier entries shall not be removed, but rather be put in DEPRECATED (deprecated) state so the correct meaning remains throughout past FXD containers. The schema of the Selection Dictionary is determined mandatory in the file FXD-Selection-Dictionary_V1.1.0.xsd.

Table B.1 defines the naming of FXD change request form for new entries in the Selection Dictionary.

Table B.1 — Naming of FXD change request form for new entry in Selection Dictionary

Prefix	[vehicle manufacturer]_FXD-CRF_SD_xxx
Version	Versions are characterised by two-digit numbering prepending the capital letter "V". This means the first document version receives the version name "V01". For each further version, the version name will be increased by 1 for example, (V02, V03, V04...). Files with document status will receive one of the following letters additionally (according to the actual status). The capital letter "U" can be used for documents which are no longer valid. This is reasonable when a document is not up to date and a new version has not been made.
Date	Format for date: YYYYMMDD

A Selection List is determined for the following subclauses:

— MON-COMPONENT (B.3.4) ;

— MON-FREQUENCY (B.3.3);

— RATIO-GROUP (B.3.4);

— MCL-STRATEGY (B.3.5);

— READINESS-GROUP (B.3.6);

— SIMULATION-METHOD (B.3.7); and

— GENERIC-TYPE (B.3.8).

B.3 Selection Lists

B.3.1 General

The element "SELECTION-LIST" contains coordinated individual terms (Selections) which can also be grouped in several topics for navigation purpose (SELECTION-GROUP)

The pattern (Schema) of the Selection List is determined mandatory in the file "selection-dictionary.xsd". Figure B.1 shows the schema SELECTION-LIST.

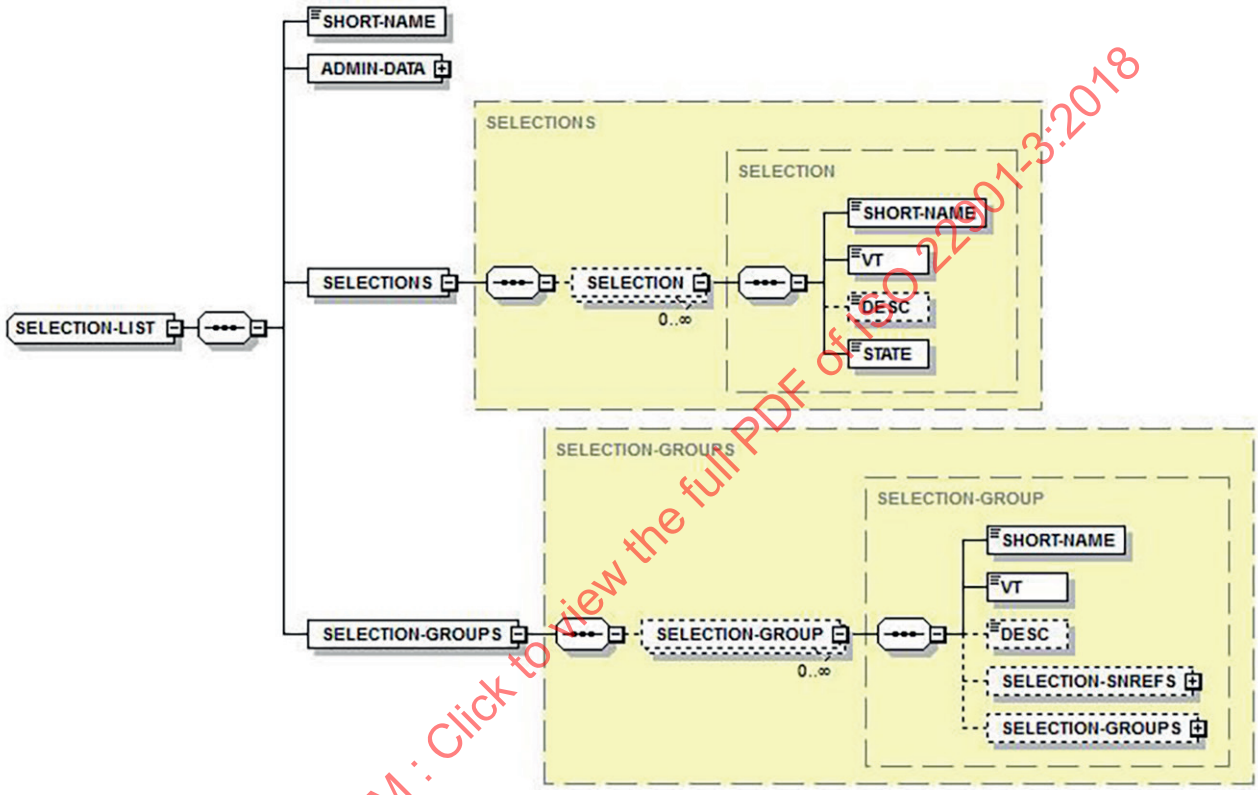


Figure B.1 — Schema SELECTION-LIST

English shall be used as language.

The terms used shall be based on the standards of SAE J1930-DA, the measured value specifications SAE 1979-DA, fault code specifications SAE J2012 and OBD legislation.

The allocation between SHORT-NAME and ITEMS for individual terms (SELECTIONS) shall stay permanent. If a vehicle manufacturer wishes to re-map terms to a company internal list, he needs to search the term SHORT-NAME in FXD, then continue to branch to a reference list.

The name conventions and abbreviations of the individual ITEMS are mandatory in order to identify all contents over their SHORT-NAMES and make an allocation to the creator possible at all times.

The creation rule for the title of SHORT-NAMES for specification text within individual SELECTION LIST is determined as follows:

— FXD,

— Followed by the initials SL for selection list.

Two or three letters indicating data content of the SELECTION-LIST.

SHORT-NAMES for the SELECTION ITEMS, which are determined mandatory, are listed in the corresponding SELECTION LIST chapters.

With the element SELECTION-GROUP, the individual specifications under SELECTION can be grouped according to their topic area.

B.3.2 MON-COMPONENT

By means of the Selection List MON-COMPONENT, a selection can be made to determine for which component or system a description is being made.

Here, the SHORT-NAME provides the basis for identification and starts with “FXD_”. The name of the Selection List starts with SL_MC_ and contains a sequential, four-digit number.

Within the Selection List for the monitoring component, the defined SHORT-NAME, the name of the component or of the system and the status are indicated.

— Defined format: FXD_SL_MC_nnnn

Table B.2 defines the example for the MON-COMPONENT Accelerator Pedal Position Sensor 1.

Table B.2 — Example for the MON-COMPONENT Accelerator Pedal Position (APP) Sensor

SHORT-NAME	VT	STATE
FXD_SL_MC_0001	Accelerator Pedal Position (APP) Sensor	RELEASED

B.3.3 MON-FREQUENCY

By means of the Selection List MON-FREQUENCY, a selection can be made to determine how often the monitor is to run.

Here, the SHORT-NAME starts with “FXD_”. The name of the Selection List starts with SL_MF_ and contains a sequential, three-digit numbering. Within the Selection List for the MON-FREQUENCY, the defined SHORT-NAME, the kind of monitoring and the status are indicated.

— Defined format: FXD_SL_MF_nnn

Table B.47 defines the example for the MON-FREQUENCY Continuous.

Table B.3 — Example for the MON-FREQUENCY Continuous

SHORT-NAME	VT	STATE
FXD_SL_MF_001	continuous	RELEASED

B.3.4 RATIO-GROUP

By means of the Selection List RATIO-GROUP, a selection can be made to determine which ratio group can be allocated to a symptom.

Here, the SHORT-NAME starts with “FXD_”. The name of the Selection List starts with SL_RAG_ and contains a sequential, three-digit numbering.

Within the Selection List for the RATIO-GROUP, the defined SHORT-NAME, the name of the ratio group and the status are indicated.

— Defined format: FXD_SL_RAG_nnn,

Table B.4 defines the example for the RATIO-GROUP PM.

Table B.4 — Example for the Ratio GROUP PM

SHORT-NAME	VT	STATE
FXD_SL_RAG_014	PM	RELEASED

B.3.5 MCL-STRATEGY

By means of the Selection List MCL-STRATEGY, a selection can be made to determine the legislation category based on chapters of the Final Regulation Order (FRO).

Here, the SHORT-NAME starts with 'FXD_'. The name of the Selection List starts with SL_MCL_ and contains sequential, three-digit numbering.

Within the Selection List for the MCL-STRATEGY, the defined SHORT-NAME, the name of the ratio group and the status are indicated.

— Defined format: FXD_SL_MCL_nnn,

Table B.5 defines the example for the MCL-STRATEGY Input Out-of-Range High.

Table B.5 — Example for the MCL-STRATEGY Input Out-of-Range High

SHORT-NAME	VT	STATE
FXD_SL_MCL_001	Input Out-of-Range High	RELEASED

B.3.6 READINESS-GROUP

By means of the Selection List RATIO-GROUP, a selection can be made to determine which readiness group can be allocated to a symptom.

Here, the SHORT-NAME starts with "FXD_". The name of the Selection List starts with SL_REG_ and contains a sequential, three-digit numbering.

Within the Selection List for the RATIO-GROUP, the defined SHORT-NAME, the name of the ratio group and the status are indicated.

— Defined format: FXD_SL_REG_nnn

Table B.6 defines the example for the READINESS-GROUP Catalyst Monitoring.

Table B.6 — Example for the READINESS-GROUP catalyst monitoring

SHORT-NAME	VT	STATE
FXD_SL_REG_003	catalyst monitoring	RELEASED

B.3.7 SIMULATION-METHOD

By means of the Selection List SIMULATION-METHOD, a selection can be made to determine which method is to be used to trigger the fault symptom.

Here, the SHORT-NAME starts with 'FXD_'. The name of the Selection List starts with SL_SM_ and contains a sequential, three-digit numbering.

Within the Selection List for the SIMULATION-METHOD, the defined SHORT-NAME, the name of the simulation method and the status are indicated.

Defined format: FXD_SL_SM_nnn,

Table B.7 defines the example for the SIMULATION-METHOD Remove Component.

Table B.7 — SIMULATION-METHOD selection list

SHORT-NAME	VT	STATE
FXD_SL_SM_001	remove component	RELEASED

B.3.8 GENERIC-TYPE

By means of the Selection List GENERIC-TYPE, a selection can be made to determine which type of diagnosis is to be associated with the fault detection.

Here, the SHORT-NAME starts with 'FXD_'. The name of the Selection List is starting with SL_GT_ and contains a sequential, three-digit numbering.

Within the Selection List for the GENERIC-TYPE, the defined SHORT-NAME, the name of the generic type and the status are indicated.

Defined format: FXD_SL_GT_nnn

Table B.8 defines the example for the GENERIC-TYPE communication.

Table B.8 — GENERIC-TYPE selection list

SHORT-NAME	VT	STATE
FXD_SL_GT_001	COMMUNICATION	RELEASED

Annex C
(normative)

Digital Annex of FXD Rule Set

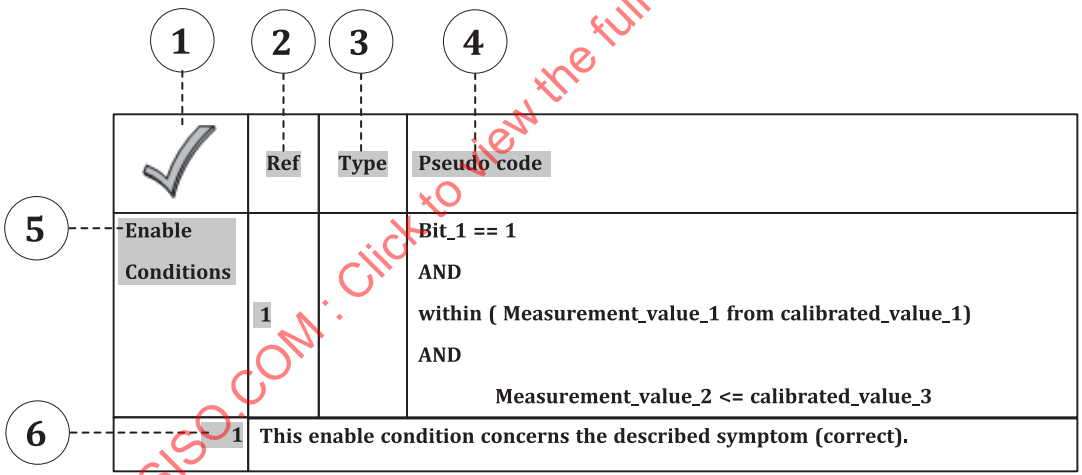
C.1 Legend of symbols and description of table structure

Legend of symbols

WARNING — Negative examples shall not be used

Correct/desired representation

Figure C.1 — Legend of the table structure.



Key

1 Identification mark whether this is a negative or positive example.

2 Indication of the individual references for Key 6.

3 The Type indicates which presentation style has been selected for the Pseudo codes. As designed in the FXD-Schema, the information can be presented using the Data Name [DATA-NAME], Display Name [DISPLAY-NAME], Long Name [LONG-NAME], Text Mapping [TEXT-MAP] or Description [DESC]. If no Type is indicated, the Pseudo code is presented as the Data Name [DATA-NAME].

4 The Pseudo code field lists examples of Abstract Syntax [ABSTRACT-SYNTAX]. Please note: the content in the examples shown above cannot be claimed to be complete and the examples do not necessarily mirror the real symptom sequence.

5 Indication of the part of the symptom description we are at, e.g. Enable Conditions [ENABLE-CONDITIONS], Fault Detection Criteria [FAULT-DETECTION-CRITERIA].

6 Explanations of the individual references in Key 2.

Figure C.1 — Legend of table structure

NOTE The name in front of the square brackets is a general term. The term in the square brackets shows the exact spelling of the element name.

Table C.1 defines the definition of terms.

Table C.1 — Definition of terms

Type of Display	Abbreviation	Element	Term Description
LONG-NAME	LO-NA	LONG-NAME	The LONG-NAME of an object is a short (a few words, less than a sentence) description that can be understood by the users.
DATA-NAME	DA-NA	DATA-NAME	The DATA-NAME of an object is the name (like a short name) used in the 'a2l' file for this object, typically the name used in the electronic control unit (ECU) software.
DISPLAY-NAME	DI-NA	DISPLAY-NAME	The DISPLAY-NAME of an object is an alternative name to the DATA-NAME tools introduced in the 'a2l' file. It is to be used by tools and presented to the users instead of the DATA-NAME.
L O N G - N A M E + TEXT-MAPPING	LO+TE	TEXT-MAP	A TEXT-MAPPING can be used to specify an alternative wording for a term or phrase for a dedicated purpose, e.g. a specific audience.
DESCRIPTION	DESC	DESC	The DESCRIPTION of an object provides an explanation of the object for human readers. It typically consists of a few sentences.
NOTE	NOTE	–	Additional information about the contents of the subsequent section.

C.2 Categories

To write symptom-based FXD descriptions, different types of information are required. These are divided into the following categories:

— C.3 – Basic FXD rules
This category shows elementary FXD rules.

— C.4 – Data preparation rules
This category shows the rules concerning WHAT TYPE of information is to be presented.

— C.5 – Presentation rules
This category shows HOW the information is to be presented.

C.3 Basic FXD rules

C.3.1 Overview

The following subclauses provide an overview of the general clause:

— C.3.2 – Description of basics;

— C.3.3 – Symptom-based descriptions;

— C.3.4 – Scope of the symptom description;

— C.3.5 – Definition of the enable conditions and the fault detection criteria;

— C.3.6 – Battery voltage and terminal status;

— C.3.7 – Topics that do not need to be described; and

— C.3.8 – Abstraction rules.

C.3.2 Description of basics

Describe only the path that leads to the fault detection or fault healing.

Here, all conditions / criteria / parameters that are required to enable or evaluate the monitor shall be listed.

— Starting point for fault detection:

— For all descriptions, it can be assumed that the component (system) is clearly (unambiguously and permanently) defective.

— Then, the description shall be restricted to represent “what does the software (SW) do to detect the fault”.

— Starting point for fault healing:

— For all descriptions, it can be assumed that the component (system) is clearly (unambiguously and permanently) good.

— Then, the description shall be restricted to represent „what does the SW do to heal the fault“.

C.3.3 Symptom-based descriptions

C.3.3.1 Overview

The structure of the XML-Schema in the FXD container is symptom-based. This is why all descriptions, without exception, shall be symptom-specific. This means that the descriptions of different symptoms, which may be “related”, shall be clearly distinguished from one another.

C.3.3.2 Example of description contents

Table C.2 defines the negative example of description contents.

Table C.2 — Negative example of description contents

STOP	Ref	Type	Pseudo code

Enable Conditions			`Bit_1 == 1`
			`AND`
			`within(measurement_value_1 from enable_threshold_value_1 to enable_threshold_value_2)`
			`AND`

	1		`measurement_value_2 <= enable_threshold_value_3`
			`OR`
	2		`measurement_value_2 > enable_threshold_value_3`
	2		`AND`
	2		`measurement_value_3 >= enable_threshold_value_4`
	2		`AND`
	2		`measurement_value_4 <= enable_threshold_value_5`
Reference	1	This enable condition concerns the described symptom (correct).	
	2	This enable condition does not concern the described symptom, but another symptom (wrong).	

C.3.4 Scope of the symptom description

All partial functions, strategy specifications (e.g. part load, full load...), options to switch between different threshold values (e.g. via code word, bitmasks ...) and the like, which can be selected by means of calibration, shall be described generally.

Using all these conditions / parameters, it has to be possible to detect and heal the actual fault by means of testing.

Also exempted from this rule are those conditions / criteria / parameters that explicitly do not have to be documented in accordance with the FXD rules described in the following sections.

C.3.5 Definition of the enable conditions and the fault detection criteria

C.3.5.1 Overview

A clear distinction shall be made between enable conditions [ENABLE-CONDITIONS] and fault detection criteria [FAULT-DETECTION-CRITERIA] (see Figure C.2).

NOTE The names enable condition or fault detection criteria in front of the square brackets are general terms. The term within the square brackets shows the exact spelling of the element name.

C.3.5.2 Examples of enable conditions and fault detection criteria

Figure C.2 shows the illustration of the software.

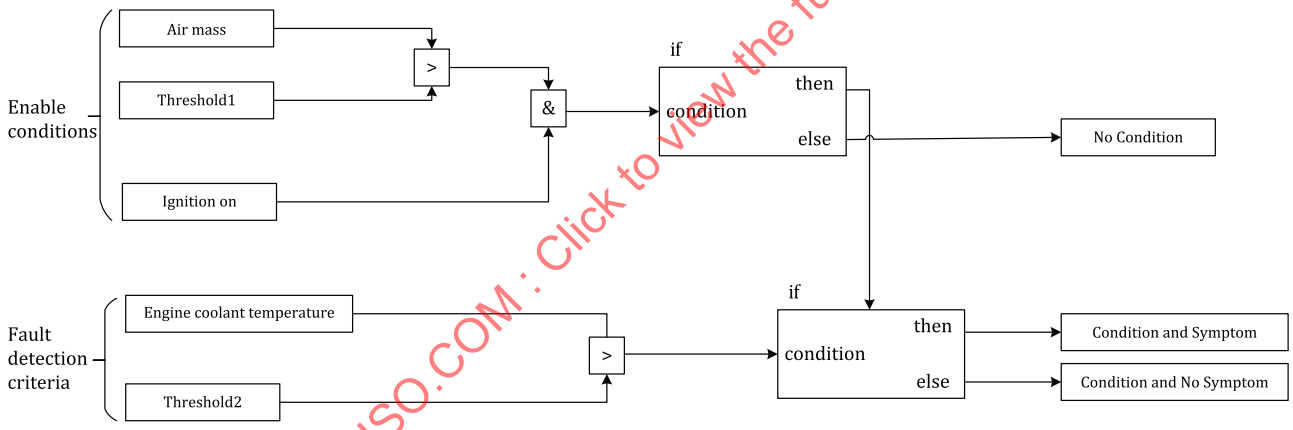


Figure C.2 — Illustration of the software

Table C.3 defines the positive example of the separation of enable conditions and fault detection criteria.

Table C.3 — Positive example of the separation of enable conditions and fault detection criteria

	Ref	Type	Pseudo code
Fault Detection Criteria	1		`measurement_value_1 > detection_threshold_value_1`

Enable Conditions	1		`measurement_value_2 > enable_threshold_value_2`
			`AND`
			`ignition == 1.0`

Reference	1	Clear separation of enable conditions and fault detection criteria.	

Table C.4 defines the negative example of identical enable conditions and fault detection criteria.

Table C.4 — Negative example of identical enable conditions and fault detection criteria

	Ref	Type	Pseudo code
Fault Detection Criteria			`measurement_value_1 > detection_threshold_value_1`

Enable Conditions	1		`measurement_value_2 > enable_threshold_value_2`
			`AND`
			`ignition == 1.0`
			`AND`
			`measurement_value_1 > detection_threshold_value_1`

Reference	1	Fault detection criteria shall not be listed under enable conditions.	

C.3.6 Battery voltage and terminal status

C.3.6.1 Overview

If a monitor is enabled, depending on things such as the battery voltage and the terminal status, this information shall be indicated.

C.3.6.2 Examples of battery voltage / ignition

Table C.5 defines the positive example of battery voltage / ignition.

Table C.5 — Positive example of battery voltage / ignition

	Ref	Type	Pseudo code

Fault Detection Criteria	1
	
	1
		LO-NA
		
		LO-NA
			`Ignition == 1.0`
			`AND`
			`Bit_2 == 1.0`
			`AND`
			`battery voltage > detection_threshold_value_1`

Reference	1	Simple check which ignition state or which battery voltage shall be present.	

Table C.6 defines the positive example of battery voltage / ignition "for time".

Table C.6 — Positive example of battery voltage / ignition "for time"

	Ref	Type	Pseudo code

Fault
Detection
Criteria
	1
	1
	1
		LO-NA
		
		LO-NA
			`ignition == 1.0`
			`AND`
			`battery voltage > detection_threshold_value_1`

Table C.6 *(continued)*

	Ref	Type	Pseudo code
	1		for_time >= 300.0 ms AND actuator not commanded
Reference	1	Ignition state and battery voltage condition shall be present for a defined time period.	

Table C.7 defines the positive example of ignition "delay".

Table C.7 — Positive example of ignition "delay"

	Ref	Type	Pseudo code
Fault Detection Criteria	1 1 1 1	LO-NA LO-NA 	ignition == 1.0 AND battery voltage > detection_threshold_value_1 delay_time = 200.0 ms AND …
Reference	1	Ignition state and battery voltage condition shall have been present before a defined time period.	

C.3.7 Topics that do not need to be described

C.3.7.1 Overview

Operational readiness of the electronic control units (ECUs):

The operational readiness of the control units that are involved in fault detection / healing is always required. This is why all conditions that are required for the control units to be active do not need to be listed. Typically, this includes activity of the main relay. Other conditions can be specific to the ECU.

Test calibration:

— All conditions that are required for the activation of the test calibrations and shorttrips do not need to be listed.

C.3.7.2 Example of the operational readiness of the ECU

Table C.8 defines the negative example of the operational readiness of the ECU.

Table C.8 — Negative example of the operational readiness of the ECU

	Ref	Type	Pseudo code
Enable Conditions	 1 1		lv_igk == 1.0 AND lv_rly_main == 1.0

Table C.8 *(continued)*

	Ref	Type	Pseudo code
			AND actuator not commanded
Reference	1	The condition that the main relay shall be active is indicated here; this condition does not have to be listed.	

C.3.8 Abstraction rules

C.3.8.1 Overview

Complex software implementations are to be described in a simplified way. However, the physical monitoring principle that the software is based on shall be included in the description.

— Signal-smoothing filters, other filters and the like do not have to be described as detailed as they are in the software.

— If a precise measurement value is available for the processed signal / variable, it is to be used.

— If no precise measurement value is available for the processed signal / variable, the facts are to be verbally described within the abstract syntax [ABSTRACT-SYNTAX] by indicating a text string (e.g. "filtered engine speed“).

C.3.8.2 Abstraction rule for VARIABLE-DESCRIPTION

— In case of complex SW-algorithms, the FXD author may decide to simplify the description even beyond the rules given so far.

— In this case, an additional comment has to be provided, using the DESC element, to inform the reader about the simplification.

— Recommended text for this information is “Further information on demand”.

C.3.8.3 Examples of abstraction rule

Table C.9 defines the positive example of an abstraction rule.

Table C.9 — Positive example of an abstraction rule

	Ref	Type	Pseudo code
Fault Detection Criteria	1 1 1		for_time(Bit_1 == 0.0 AND Bit_2 == 0.0,detection_threshold_value_1)
Reference	1	In the abstracted form, it is sufficient to indicate that a condition shall be present for a time period that can be defined.	

Table C.10 defines the negative example of an abstraction rule.

Table C.10 — Negative example of an abstraction rule

STOP	Ref	Type	Pseudo code

Fault
Detection
Criteria
	1
	1
	1
	
	2
			`for_time(Bit_1 == 0.0`
			`AND`
			`delta(Bit_2 == 0.0), detection_threshold_value _1)`
			`AND`
			`Bit_2 == 0.0`

Reference	1 2	Indication that the condition shall not change for a calibrated time. Indication in which condition the parameter shall be.	

C.3.9 Dealing with power stage monitors

C.3.9.1 Overview

For the following description of how to deal with power stage monitors, it is assumed that the power stages are integrated into the control units that lie in the focus of the FXD description, i.e. the control unit supplier has detailed knowledge of the software and hardware configuration of the installed power stage components.

To control the actuators, intelligent power stage components are used, among other components, as power amplifiers. These intelligent power stage components carry out OBDI monitors (short to battery, short to ground, open circuit) independently and transmit the monitoring result to the control unit's central processing unit (CPU) via a data bus in the control unit.

Typically, the monitoring threshold values are dependent on the following hardware criteria:

used type of power stage (for voltage-based threshold values) or

used type of power stage and concrete power stage pin connection (for current-based threshold values).

Generally, the description requirements for power stage monitors are the same as for all other monitors.

Furthermore, the following description requirements shall be considered:

Regarding enable conditions:

If required from a technical point of view, the state of the acutator (on/off) is to be indicated (to differentiate between online and offline monitors)

When the actuator is controlled using pulse-width modulated (PWM) signal technology, the PWM signal ranges during which the respective monitor can run are to be indicated

If so-called „diagnostic pulse generators“ are used to carry out the monitors, this is to be indicated

Regarding fault detection criteria:

If there are calibratable application labels for the fault threshold values, they shall always be indicated

If the supplier and the OEM have agreed to take project-specific hardware configurations into account, the following is also required:

Indication of concrete fault threshold values (values for the voltage/values for the current)

Indication of the concrete type of power stage (as a note within the fault detection criteria)